



Co-ordinated by
ECMWF



CoCO2

Prototype system for a
Copernicus CO₂ service

Towards CO₂ plume detection and inversion from satellites using deep neural networks

Atmospheric Constituents Data Assimilation
and Inverse Modeling- 23/03/22

Joffrey Dumont Le Brazidec¹, Pierre Vanderbecken¹,
Alban Farchi¹, Marc Bocquet¹, Jinghui Lian², Grégoire
Broquet², Thomas Lauvaux², Alexandre Danjou²

CEREA, École des Ponts and EdF R&D, Île-de-France, France [1]
LSCE, Laboratoire des sciences du climat et de l'environnement [2]





CoCO2, prototype system for a CO2 monitoring service

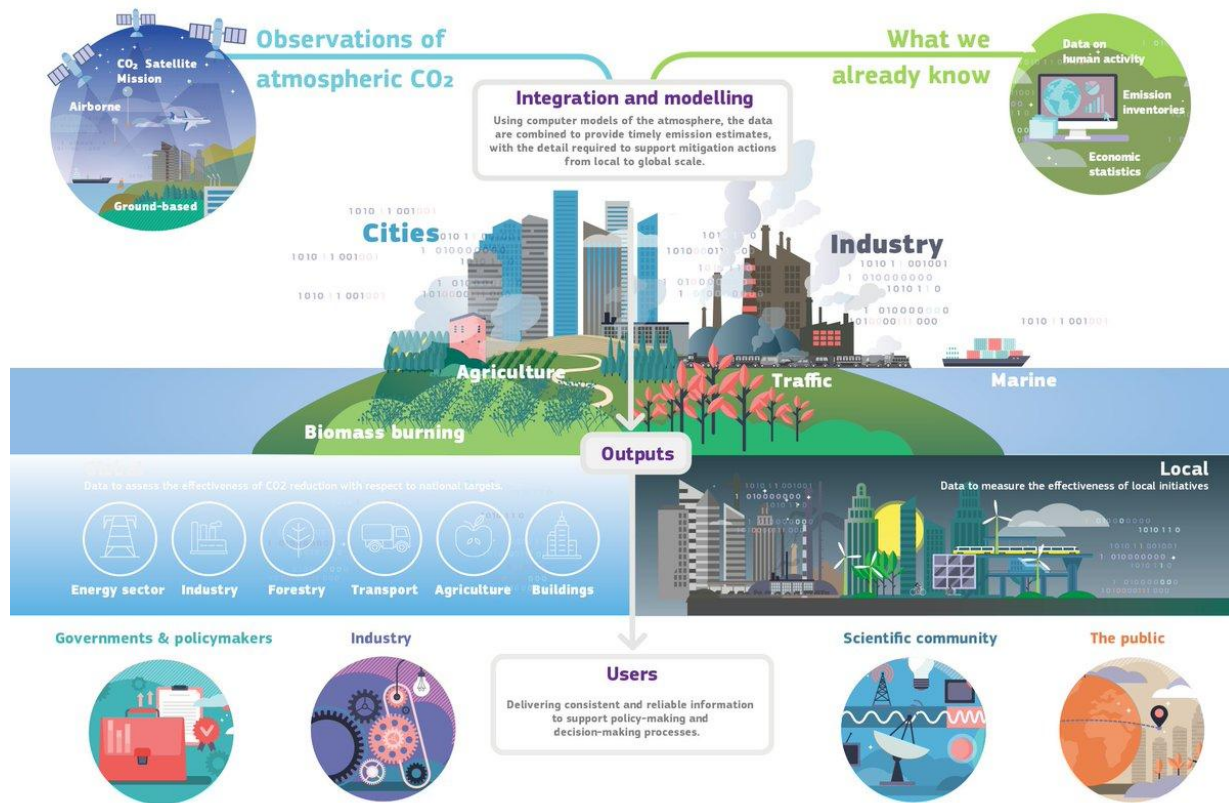
Our work = part of the **Copernicus CoCO2 project**, prototype of a CO₂ monitoring service which aims, in particular, to improve the estimation of CO₂ emissions from new satellites launched from 2025 onwards.

Our aim:

Focus on CO₂ emissions from point sources:

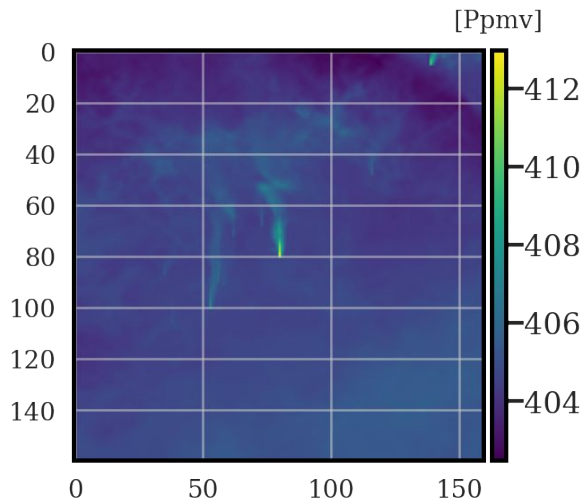
- ❑ large magnitude
- ❑ urban scale

based on the spaceborne imagery of the CO₂ atmospheric plumes from these sources.





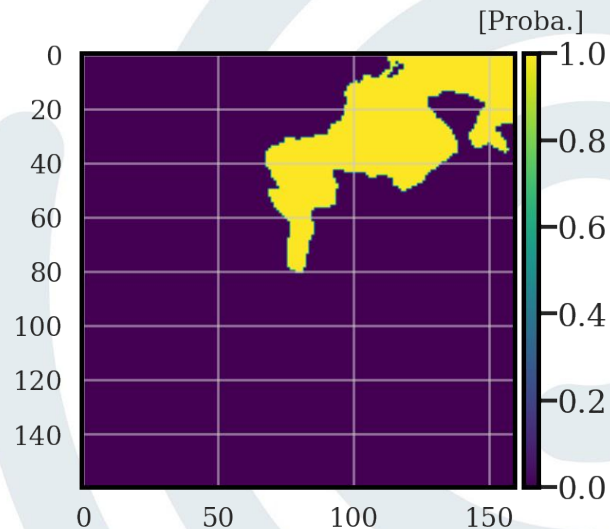
Estimating CO₂ emissions from a satellite image



Inversion:

From a given satellite image:
estimate emission rates from
a point source

Emissions and
“consequences” of the
emissions: the plume,
are directly related

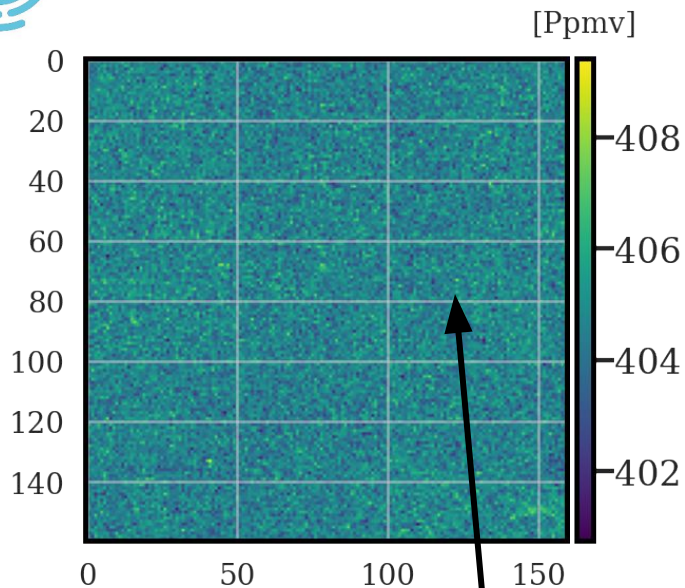


Segmentation:

-> find map of probabilities
(pixel values between 0 and 1)
describing potential positions
of the plume



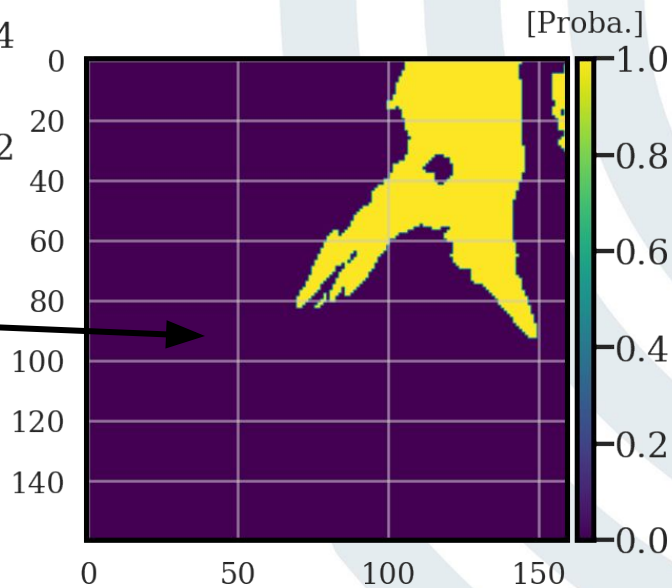
Where is the plume ?



Many plumes concealed under the background

Signal of CO₂ plumes induced by cities emissions is intrinsically difficult to detect

- Rarely exceeds values of a few ppm
- Perturbed by variable regional CO₂ background signals and satellite noise





Detectability factors¹

- **Signal-to-noise ratio:**
 - “Background” noise:
 - Variability of the background
 - Instrument noise
 - Plume “definition” (signal):
 - Meteorological conditions, which determine dilution and dispersion
 - Intensity of the source emission
- **Image integrity:**
 - Clouds
 - Number of satellite overpasses

Simulate satellite observations (OSSE)

1. Detectability of CO₂ emission plumes of cities and power plants with the Copernicus Anthropogenic CO₂ Monitoring (CO₂M) mission. Kuhlman et al.



Outline

To segment and inverse plumes in images with low SNR ratio: need of techniques that can learn specific characteristics of plumes, other than high signal, such as spatial patterns

-> deep learning methods

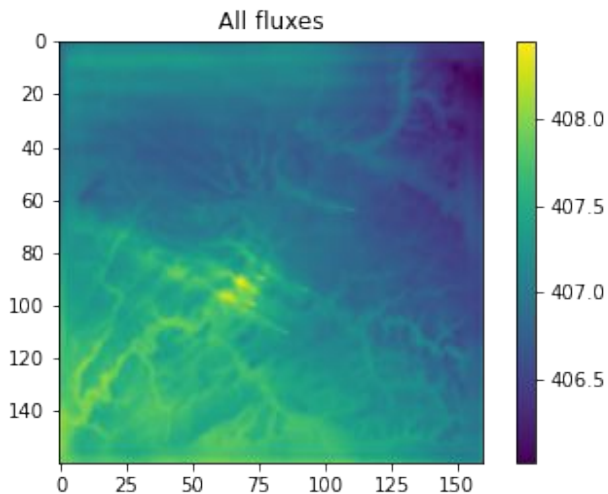
- I. In the framework of CoCO2: creation of a synthetic dataset, i.e., of pairs of XCO2 field/plume or emission
- II. Segmentation
- III. Inversion



Creation of an XCO₂ field/plume pair

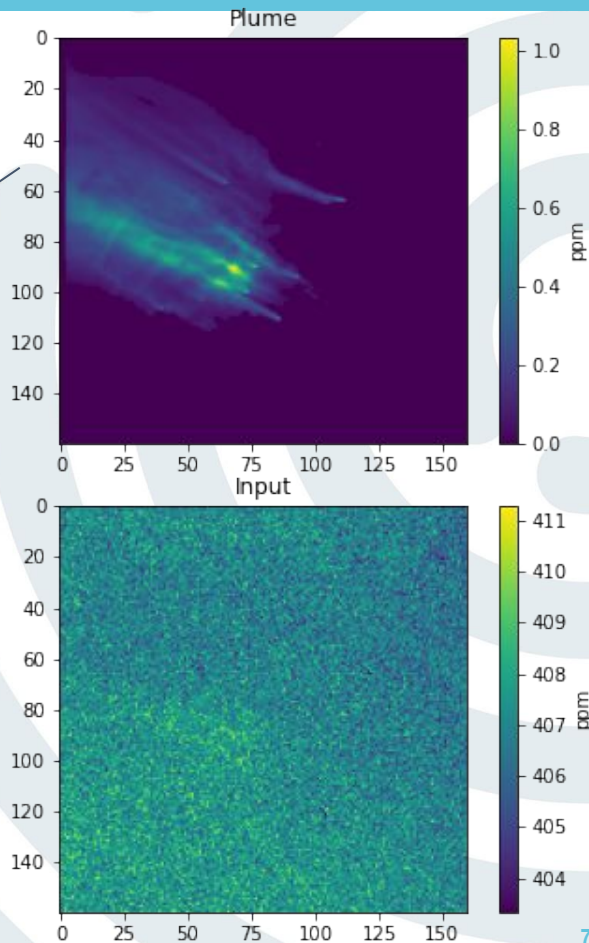
July, afternoon,
emissions from Paris
= 17.3 Mt.yr-1

*Simulated atmospheric
dispersion of the plume
only*



*Addition of the
simulated
background*

*Addition of the
satellite noise
(0.7ppm)*





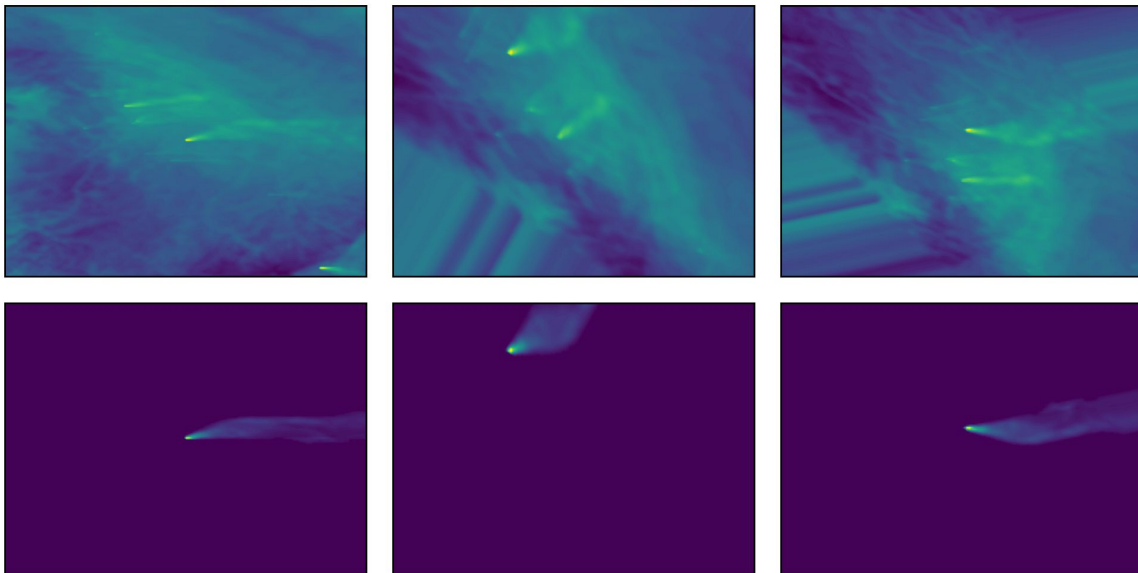
Get the widest possible diversity of plumes

Variety of point sources,
geographical areas,
plume types, plumes
number ...

1-year simulation (~2km, 1hr) of the XCO₂ fields in the

- ❖ Paris (LSCE/Suez-Origins) with CHIMERE model
- ❖ Berlin, and ~15 power plants (EMPA) with COSMO-GHG model

areas, tracing the anthropogenic plume and other bio and anthropogenic components.

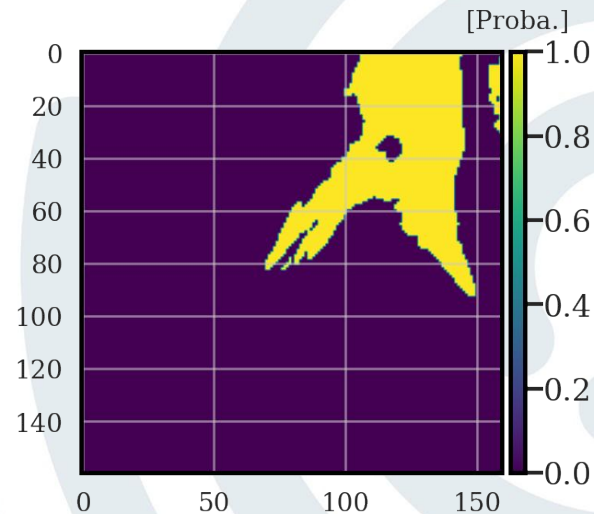
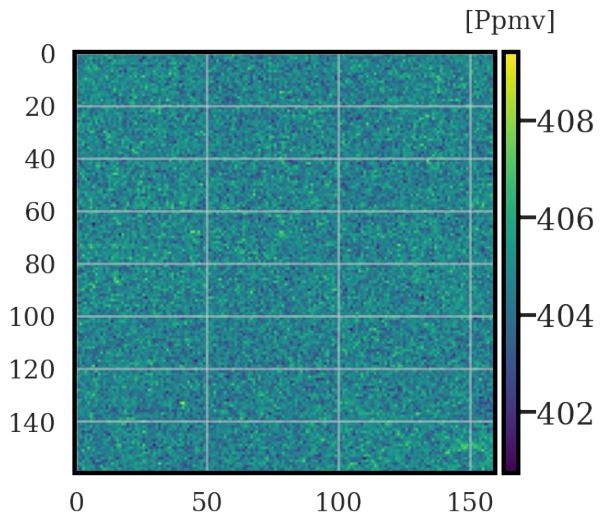


Dataset must be as diverse as possible:

- use of data augmentation techniques to artificially “create” more plumes



Segmentation: Supervised learning

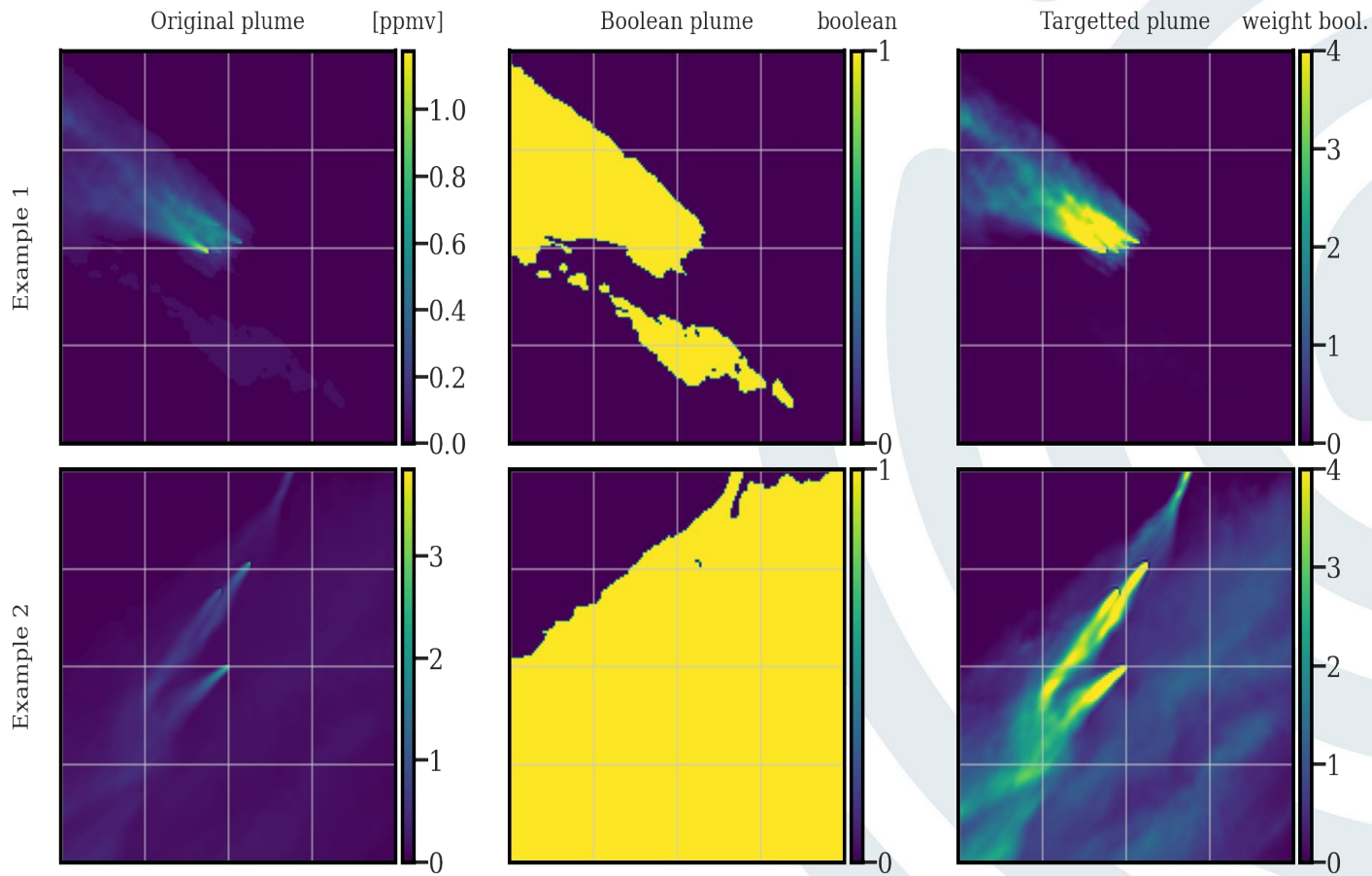


Statistical model

The model learns the relation between pairs of a provided input (simulated satellite image) and an output (here, segmented plume)



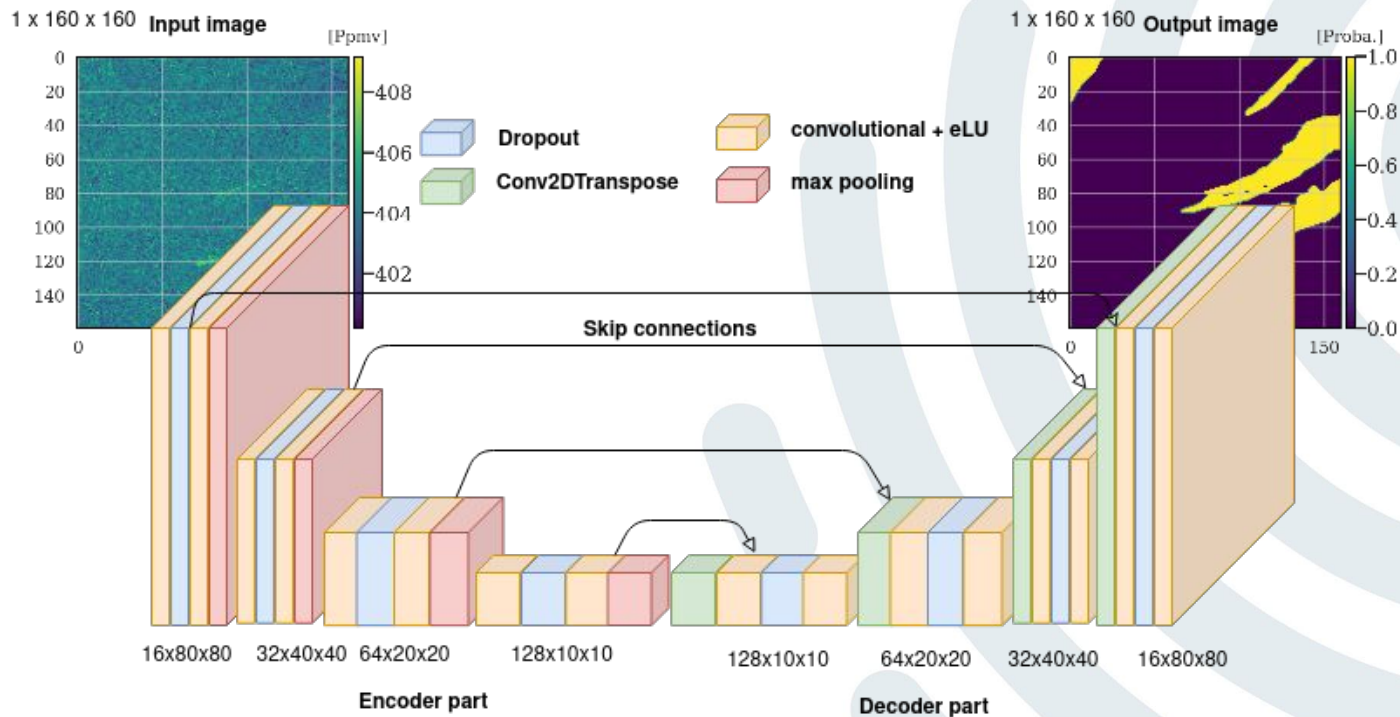
Segmentation: But what *exactly* is a plume ?





Segmentation: U-net CNN with EfficientNetB0 encoder

- ❑ capture spatial features of the image through application of successive filters
- ❑ i.e., transform image into relevant features maps
- used to recognise spatial features that belong to an anthropogenic plume





Generalising or extrapolating geographically

Two ways of training !

❖ **Generalising**

- Training on pairs of Berlin fields/plumes
- Testing on Berlin fields

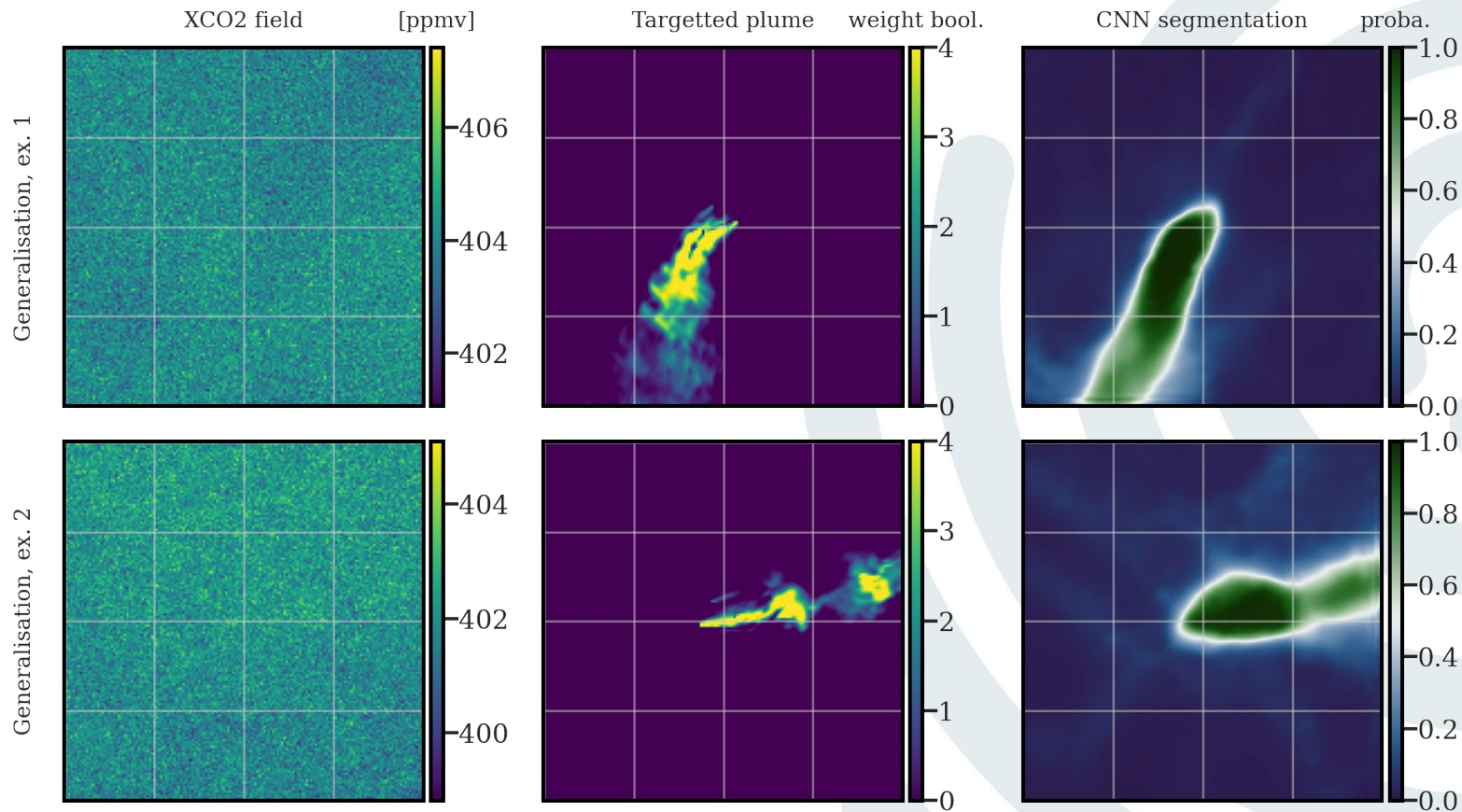
❖ **Extrapolating**

- Training on pairs of Paris and power plant fields/plumes
- Testing on Berlin fields

A universal model (=extrapolation) is harder but preferable:
it limits the amount of data needed to segment all future plumes

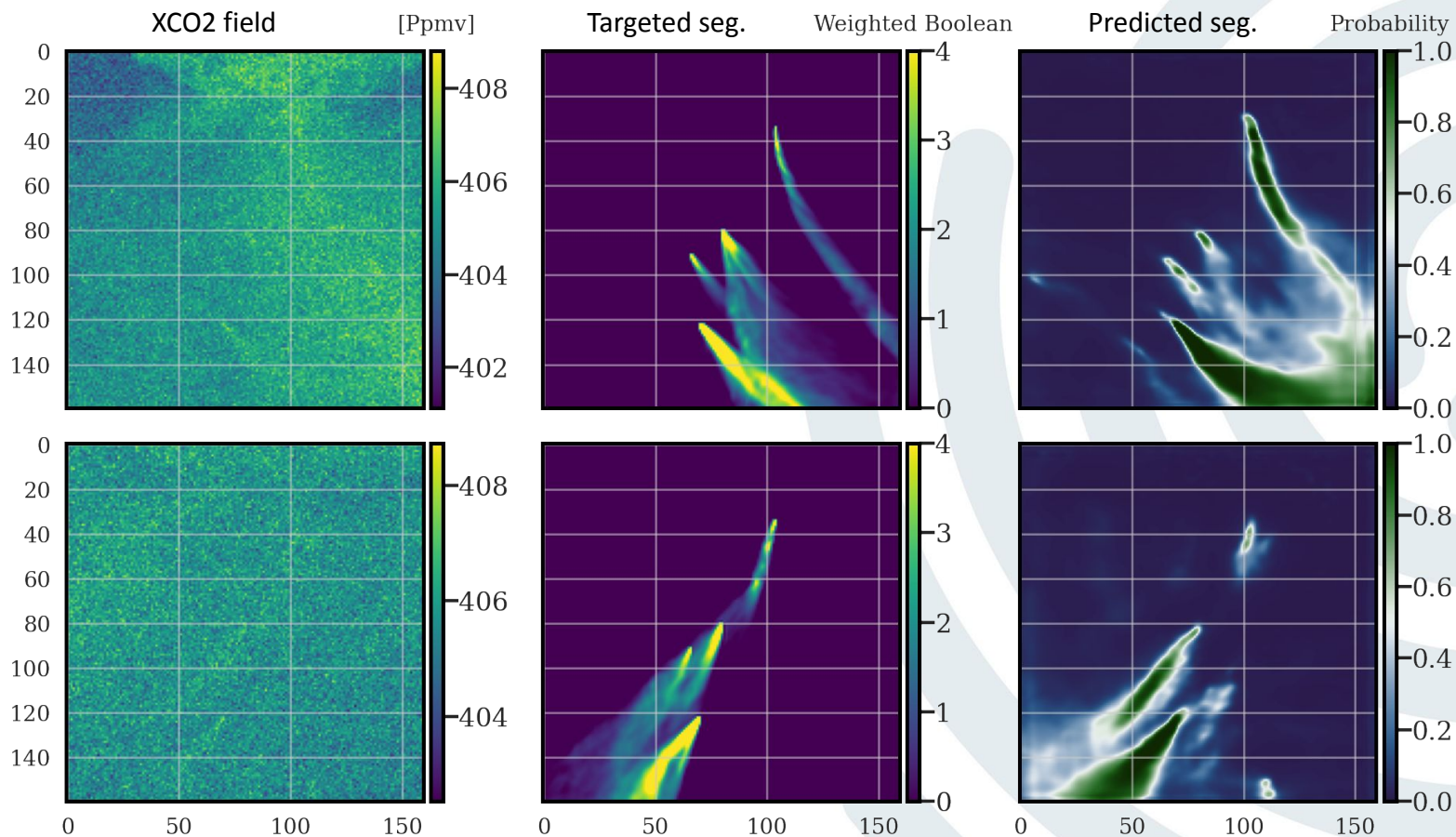


Segmentation: Generalisation on Berlin



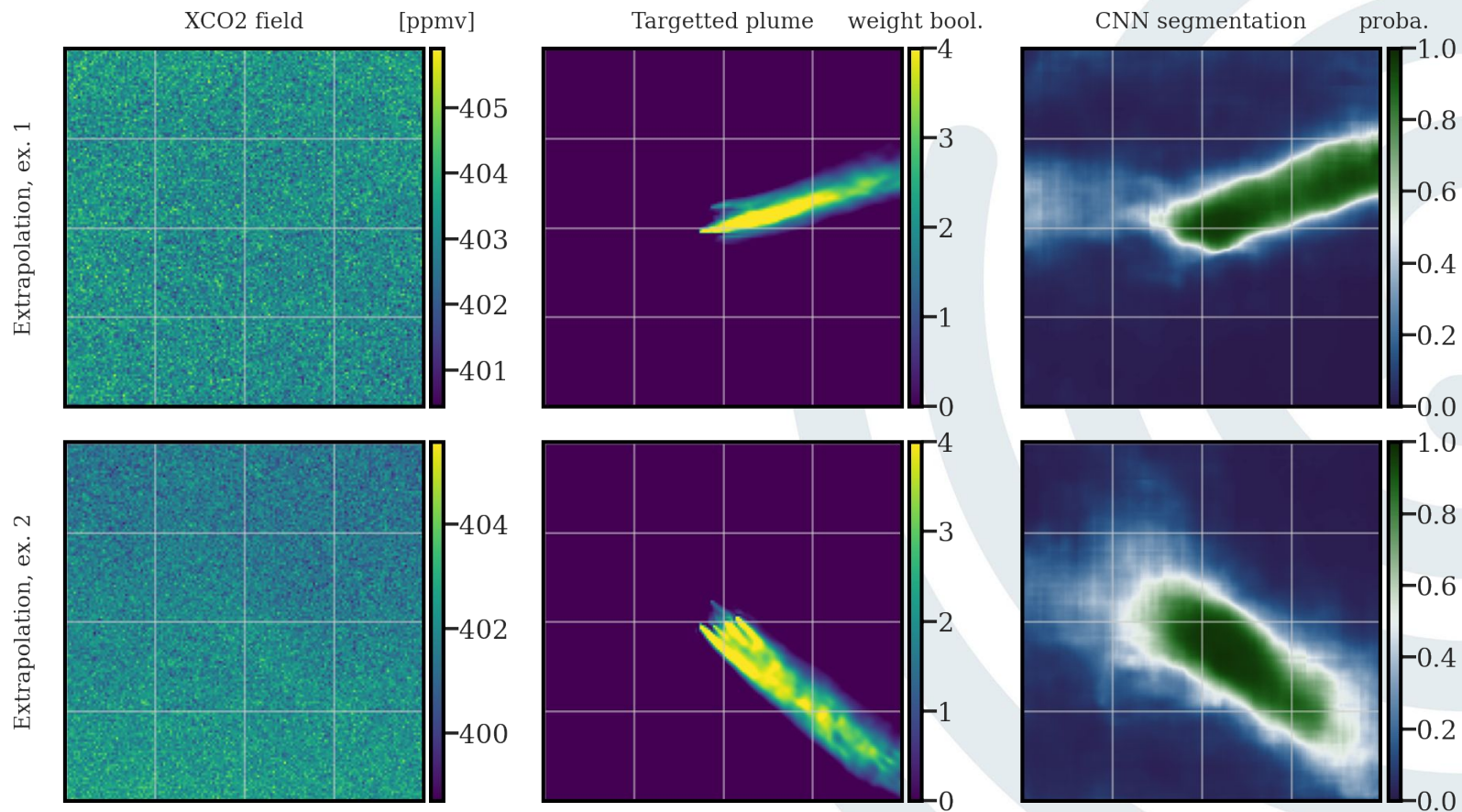


Segmentation as generalisation: multi-plume PP area



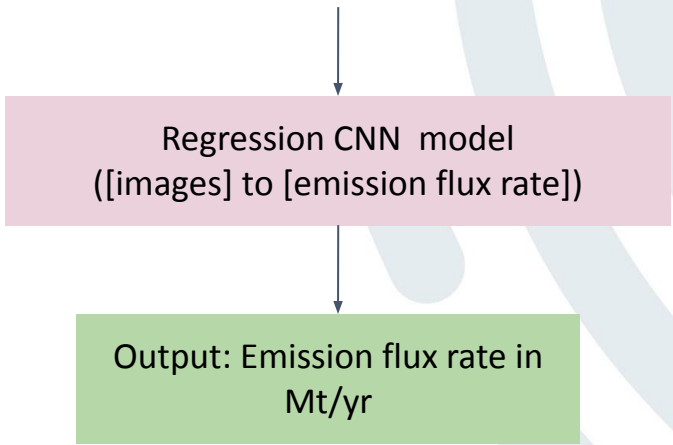
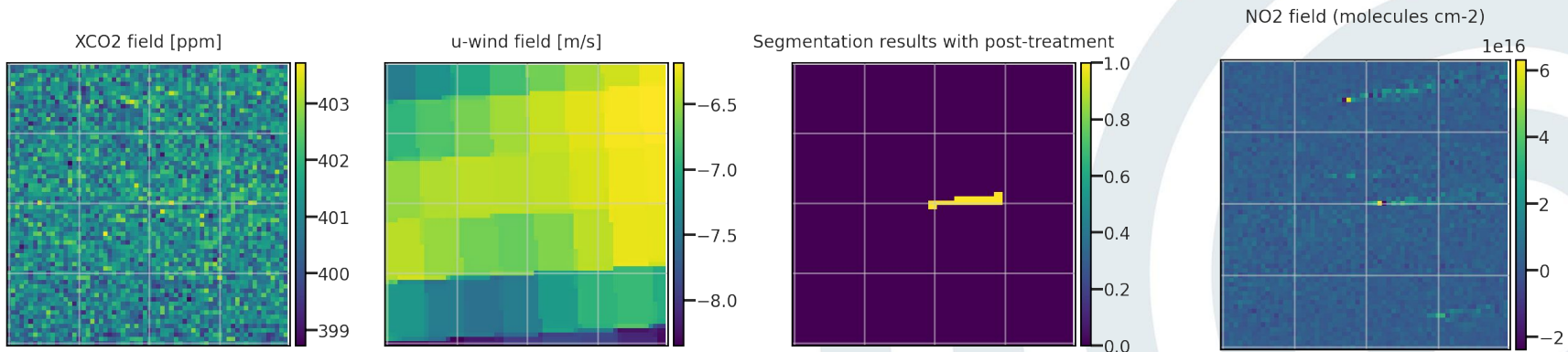


Segmentation as extrapolation: Berlin





Inversion: Set-up

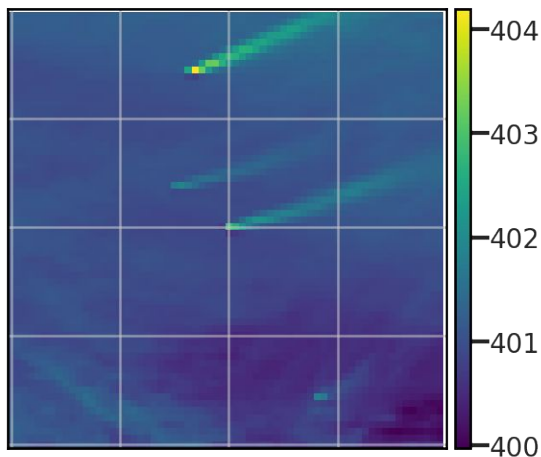


- xco2 field at time t
- xco2 field at time $t-2$
- wind fields at time t (u and v)
- segmentation predictions (with post-treatment)
- no2 field



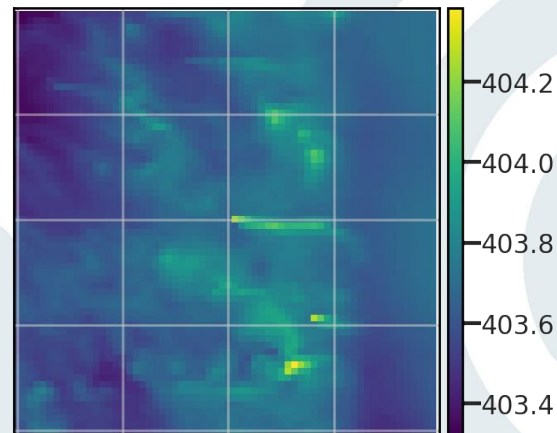
Inversion: About the data

XCO₂ field [ppm]



Boxberg - emissions flux: 23.5 Mt/yr

XCO₂ field [ppm]



Patnow - emissions flux: 7.0 Mt/yr

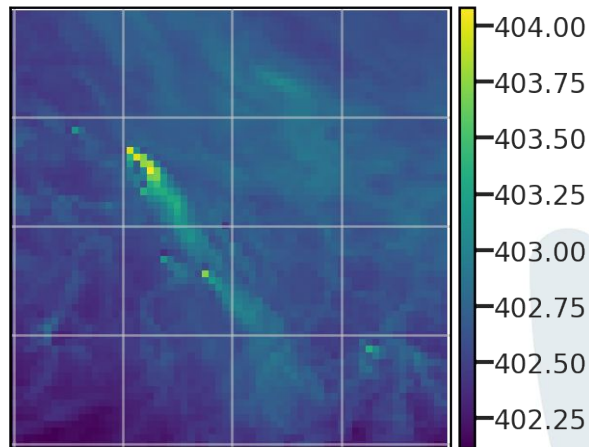
Power plants for test considered are various:

- power plant above background noise / of high emission rate (e.g. Boxberg)
- power plant below background noise / of low emission rate (e.g. Patnow)
- power plant with multiple “high” plumes (e.g. Boxberg)

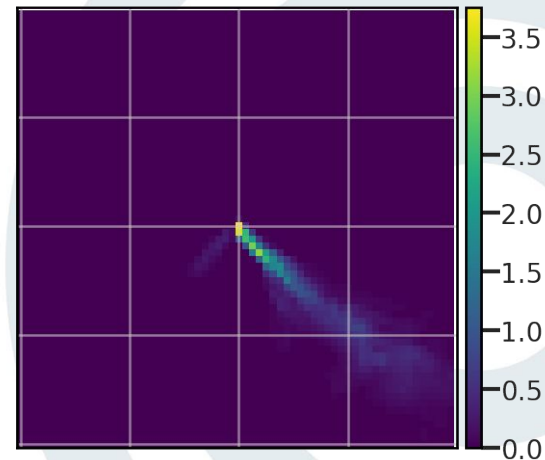


Inversion: data augmentation ?

Lippendorf background [ppm]



Lippendorf plume [ppm]



+ scaling ×



scaling × emission flux

Key is to generate new data at training time:

- each image used to train the CNN has new random gaussian noise
- each {plume, emission} of an image used to train the CNN is scaled by a random scaling factor



Inversion: About the model

Model:

Inversion is a less complicate problem than segmentation.

For ~ the same base set of images

- ★ for segmentation, good performance is achieved with encoders such as EfficientNetB0 (~5M parameters)
- ★ for inversion, good performance is achieved with much simpler regression models (~100k parameters)

Several “small” state-of-the-art models (with descaling) have been considered (squeezenet, shufflenet) but less good performances than simple model only consisting of convolutions, maxpooling, dropout, ...

Training

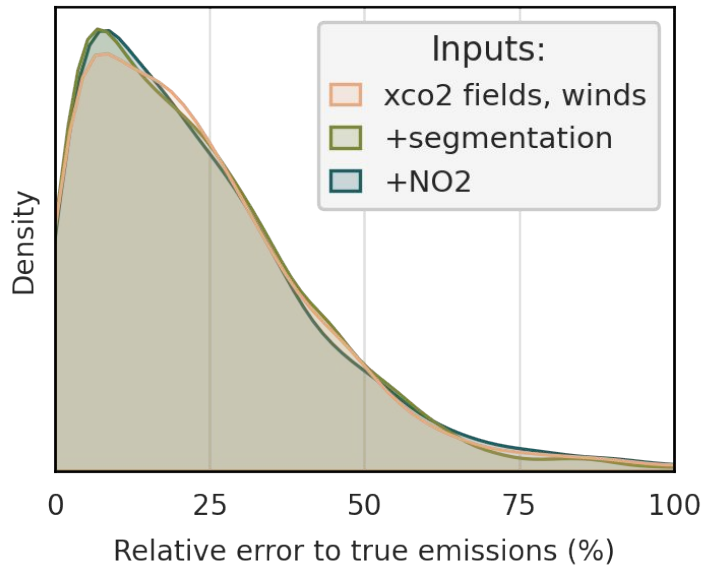
Model only trained only in “geographical extrapolation” mode. For example:

- ❖ *Train*: on a subset of power plants excluding Boxberg
- ❖ *Test*: on Boxberg power plant.

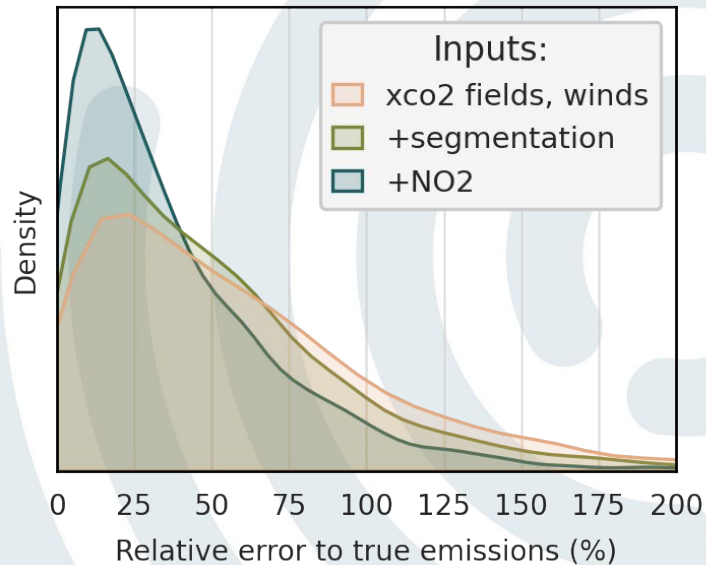


Inversion: preliminary results

Lippendorf (emission flux range: 10-25 Mt/yr)



Patnow (emission flux range: 5-10 Mt/yr)



| | Mass-balance, Cross-sectional | CNN model |
|-----------------------|--------------------------------|--------------|
| Lippendorf (high SNR) | median > 35% (when applicable) | median ~ 19% |
| Patnow (low SNR) | non-applicable | median ~ 28% |



Conclusions - next steps

Inversion conclusions

CNN models for XCO₂ plume inversion:

- I. Ability to perform inversion on low SNR plumes with the help of a segmentation pre-step or NO₂ fields
- II. CNN models outperform standard plume inversion methods with or without the help of NO₂ fields
- III. Performance is not degraded by the presence of multiple plumes on the same image

Next steps

- ❖ Inversion of city plumes. But few data available ...
- ❖ Consideration of clouds on images.
- ❖ Dealing with real CO₂ satellite observations (coming in 2027)

joffrey.dumont@enpc.fr



THANK YOU

Dumont Le Brazidec, Joffrey, Pierre Vanderbecken, Alban Farchi, Marc Bocquet, Jinghui Lian, Grégoire Broquet, Gerrit Kuhlmann, Alexandre Danjou, et Thomas Lauvaux. 2022. « Segmentation of XCO₂ Images with Deep Learning: Application to Synthetic Plumes from Cities and Power Plants ». *Geoscientific Model Development Discussions*, décembre, 1-29. <https://doi.org/10.5194/gmd-2022-288>.

This presentation reflects the views only of the author, and the Commission cannot be held responsible for any use which may be made of the information contained therein.



coco2-project.eu



@CoCO2_project