Everything Everywhere All at Once:

Holographic Entropy Cone, Entanglement Wedge Nesting, Differential Entropy, Black Holes, Modular Chern Numbers, Toric Code, Cubohemioctahedron...



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Known Entropy Inequalities

Table 1: Representatives for each of the 8 inequality orbits of the holographic entropy cone C_5 for 5 regions. Respectively, their orbit lengths are 15, 20, 45, 72, 10, 60, 60 and 90, thus defining 372 facets for C_5 in a 31-dimensional entropy space.

Cuenca, 2019

1. $S_A + S_B \ge S_{AB}$

3. $S_{ABC} + S_{ADE} + S_{BCDE} \ge S_A + S_{BC} + S_{DE} + S_{ABCDE}$

5. $S_{ABC} + S_{ABD} + S_{ABE} + S_{ACD} + S_{ACE} + S_{ADE} + S_{BCE} + S_{BDE} + S_{CDE} \ge S_{AB} + S_{AC} + S_{AD} + S_{BE} + S_{CE} + S_{DE} + S_{BCD} + S_{ABCE} + S_{ABDE} + S_{ACDE}$

7. $2S_{ABC}+S_{ABD}+S_{ABE}+S_{ACD}+S_{ADE}+S_{BCE}+S_{BDE} \ge S_{AB}+S_{AC}+S_{AD}+S_{BC}+S_{BE}+S_{DE}+S_{ABCD}+S_{ABCE}+S_{ABDE}$

2. $S_{AB} + S_{AC} + S_{BC} \ge S_A + S_B + S_C + S_{ABC}$

4. $S_{ABC} + S_{ABD} + S_{ACE} + S_{BDE} + S_{CDE} \ge S_{AB} + S_{AC} + S_{BD} + S_{CE} + S_{DE} + S_{ABCDE}$

 $\begin{array}{l} 6. \ 3S_{ABC} + 3S_{ABD} + S_{ABE} + S_{ACD} + 3S_{ACE} + \\ S_{ADE} + S_{BCD} + S_{BCE} + S_{BDE} + S_{CDE} \geq 2S_{AB} + \\ 2S_{AC} + S_{AD} + S_{AE} + S_{BC} + 2S_{BD} + 2S_{CE} + S_{DE} + \\ 2S_{ABCD} + 2S_{ABCE} + S_{ABDE} + S_{ACDE} \end{array}$

8. $S_{AD} + S_{BC} + S_{ABE} + S_{ACE} + S_{ADE} + S_{BDE} + S_{CDE} \ge S_A + S_B + S_C + S_D + S_{AE} + S_{DE} + S_{BCE} + S_{ABDE} + S_{ACDE}$

New Inequalities

Toric inequalities are defined for m and n, which are both odd. They take the following form:

$$\sum_{i=1}^{m} \sum_{j=1}^{n} S_{A_{i}^{+}B_{j}^{-}} \ge \sum_{i=1}^{m} \sum_{j=1}^{n} S_{A_{i}^{-}B_{j}^{-}} + S_{A_{1}^{(m)}}$$
(1.6)

We characterize and explore these inequalities in Section 2.2, then prove them in Section 5.1. We exemplified how terms of (1.6) can be arranged on a discretized torus in inequality (1.3). As we explain in Section 2.2.1, that spatial arrangement has further, even more compelling features.

Projective plane inequalities are defined for m = n. They read:

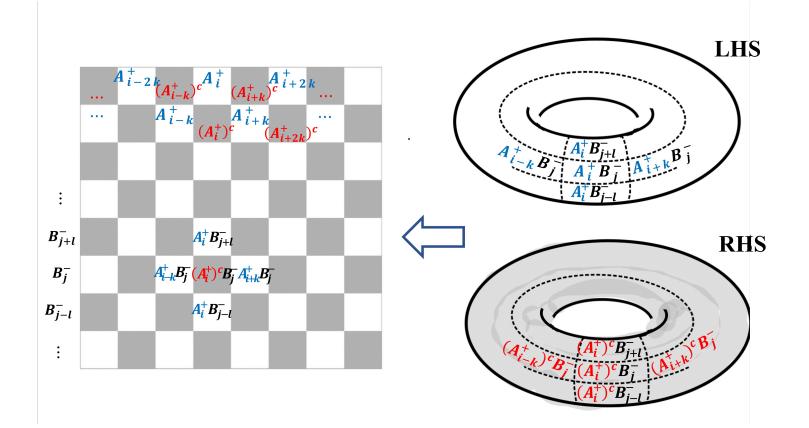
$$\frac{1}{2}\sum_{k=1}^{m}\sum_{i=1}^{m} \left(S_{A_{i}^{(k)}B_{i+k}^{(m-k)}} + S_{A_{i}^{(k)}B_{i+k+1}^{(m-k)}} \right) \ge \sum_{k=1}^{m}\sum_{i=1}^{m}S_{A_{i}^{(k-1)}B_{i+k}^{(m-k)}} + S_{A_{1}^{(m)}}$$
(1.7)

Notation:
$$A_i^{(k)} = A_i A_{i+1} \dots A_{i+k-1}$$
 and $B_j^{(l)} = B_j B_{j+1} \dots B_{j+l-1}$
 $A_i^{\pm} \equiv A_i^{((m\pm 1)/2)}$ and $B_j^{\pm} \equiv B_j^{((n\pm 1)/2)}$

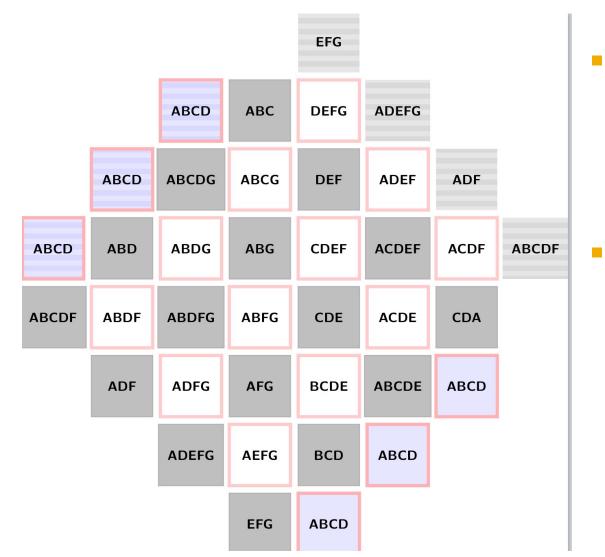
To give you a feeling:

$$S_{A_{1}A_{2}A_{3}B_{1}} + S_{A_{3}A_{4}A_{5}B_{1}} + S_{A_{5}A_{1}A_{2}B_{1}} + S_{A_{2}A_{3}A_{4}B_{1}} + S_{A_{4}A_{5}A_{1}B_{1}} + S_{A_{1}A_{2}A_{3}B_{2}} + S_{A_{3}A_{4}A_{5}B_{2}} + S_{A_{5}A_{1}A_{2}B_{2}} + S_{A_{2}A_{3}A_{4}B_{2}} + S_{A_{4}A_{5}A_{1}B_{2}} + S_{A_{1}A_{2}A_{3}B_{3}} + S_{A_{3}A_{4}A_{5}B_{3}} + S_{A_{5}A_{1}A_{2}B_{3}} + S_{A_{2}A_{3}A_{4}B_{3}} + S_{A_{4}A_{5}A_{1}B_{3}} \geq (2.9)$$

The inequalities live on twodimensional manifolds



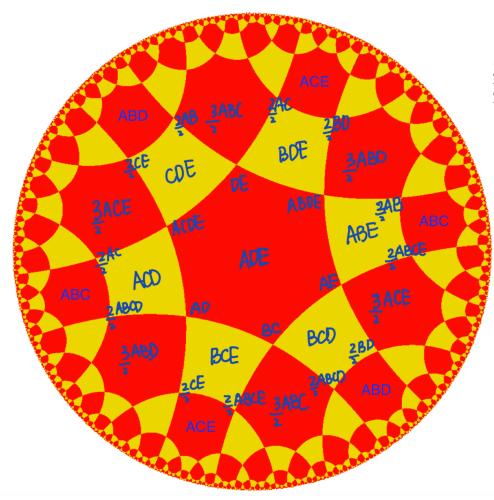
This inequality lives on the projective plane:



 Neighboring relations given by <u>entanglement</u> wedge nesting

 Neighboring four terms form a <u>discretized second</u> <u>derivative</u>

One last inequality: cubohemioctahedron



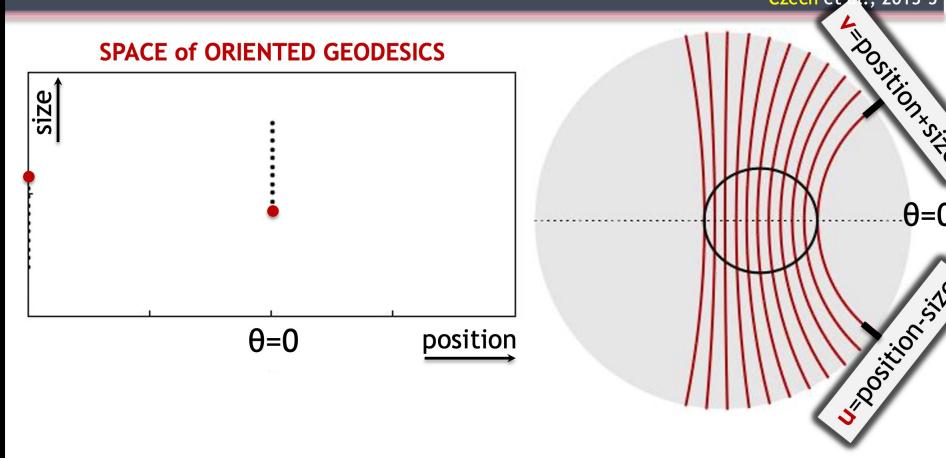
 $\begin{array}{l} 6. \ 3S_{ABC} + 3S_{ABD} + S_{ABE} + S_{ACD} + 3S_{ACE} + \\ S_{ADE} + S_{BCD} + S_{BCE} + S_{BDE} + S_{CDE} \geq 2S_{AB} + \\ 2S_{AC} + S_{AD} + S_{AE} + S_{BC} + 2S_{BD} + 2S_{CE} + S_{DE} + \\ 2S_{ABCD} + 2S_{ABCE} + S_{ABDE} + S_{ACDE} \end{array}$

These two-dimensional manifolds are kinematic spaces

- What does that mean?
- A brief review...

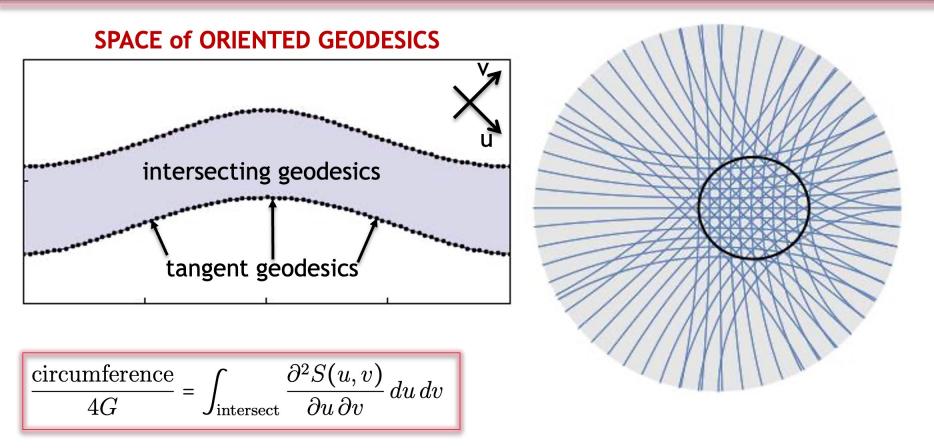
How to describe a center of AdS₃?

Czech et 2., 2013-5



How to describe a center of AdS₃?

Czech et al., 2013-5



All the new inequalities have the schematic form:

 $\int_{\text{intersect}} \frac{\partial^2 S(u,v)}{\partial u \, \partial v} \, du \, dv > \text{S(all the A-regions)}$

New inequalities:

Length of some curve in a two-sided black hole background

>

Entropy of the black hole

 LHS can also be understood as the Chern number of an "entanglement Berry parameter space"

Why toric code?

Proof involves constructing a table for LHS terms and RHS terms:

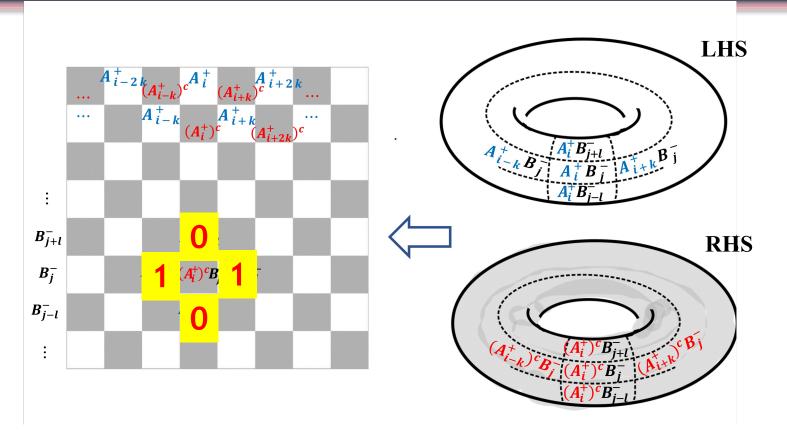
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	0	0	1	0	0	0	1								
	0	1	0	0	0	0	1								
\mathbf{C}	0	1	1	0	0	1	1								
	1	0	0	0	0	0	1								
Α	1	0	1	1	0	0	1								
В	1	1	0	0	1	0	1								
	1	1	1	0	0	0	1								

Table 2. Proof by contraction of monogamy of the holographic mutual information.

Another example of a "contraction map"

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6	31552	00(unique after	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0		0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0
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The assignment of 0's and 1's is based on the existence of certain loops on the two-d manifold



- This is just like local excitations and "logical bits" in the toric code. Still trying to understand why.
- Probably related to the toric code being a stabilizer state...
 The inequalities probably count stabilizer operators...

Everything Everywhere All at Once:

- Two new infinite families of holographic entropy inequalities.
- They naturally live on (discretized) two-dimensional manifolds.
 One of the resulting polytopes is the <u>cubohemioctahedron</u>.
- The spatial organization on the 2d manifolds is dictated by entanglement wedge nesting.
- These manifolds are <u>kinematic spaces</u> or <u>modular Berry</u> parameter spaces.
- The inequalities motivate a new type of <u>differential entropy</u>.
- Schematically, they read:

"length of a curve" > "black hole horizon"

"modular Chern number" > "black hole horizon"

 The proof involves manipulations, which are familiar from the toric code. This probably reflects properties of stabilizer states.

