# Well-posedness and dynamics of solutions to the generalized KdV with low power nonlinearity

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# Outline



- 2 Local well-posedness results
- **3** Numerical Investigations

### 4 Bibliography





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- **3** Numerical Investigations

### ④ Bibliography

In this talk, we study two types of the generalized Korteweg-de Vries equation: one,  ${\bf gKdV}$ 

$$\begin{cases} \partial_t u + \partial_x^3 u + u^{\alpha} \partial_x u = 0, \quad x, t \in \mathbb{R}, \\ u(x, 0) = u_0, \end{cases}$$
(gKdV)

where the power  $\alpha = \frac{m}{k}$  with  $m, k \ge 1$  odd integers.

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where the power  $\alpha = \frac{m}{k}$  with  $m, k \ge 1$  odd integers.

We also consider the  ${\bf GKdV},$  with the absolute value incorporated into the nonlinearity

$$\begin{cases} \partial_t v + \partial_x^3 v + |v|^{\alpha} \partial_x v = 0, \quad x, t \in \mathbb{R}, \\ v(x,0) = v_0, \end{cases}$$
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where  $\alpha > 0$ .

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- Local behavior. We present local well-posedness (LWP) results for a subclass of  $H^1(\mathbb{R})$ . (By LWP we mean, existence, uniqueness and continuous dependence of the map data-to-solution).
- Global behavior. We use numerical methods to study the large time behavior of solutions. In this part, more differences between the two equations will be pointed out.

• The gKdV and GKdV equations can be regarded as extensions of the *k*-generalized KdV equation

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- The integer cases k ≥ 2 have been used in several physical contexts, such as shallow-water waves among many others.
- The modular power nonlinearity as in GKdV  $(|v|^{\alpha}\partial_x v)$  has also been used in physics; for example, when  $\alpha \in (0, 1)$  it is studied in models of non-Maxwellian trapped electrons and description of their dynamics in ion-acoustic solitary waves

• A special case of  $\alpha = \frac{1}{2}$  is called the *Schamel equation*,

$$\partial_t v + \partial_x^3 v + |v|^{\frac{1}{2}} \partial_x v = 0, \qquad x, t \in \mathbb{R},$$

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- In the case 0 < α < 1, by using weighted spaces the well-posednesss was studied by Linares, Miyazaki and Ponce, 2019.
- In this talk, we show extensions of the previous well-posedness results to a wider class of fractional weights and  $\alpha > 0$ .

• Formally, solutions of the gKdV and GKdV equations satisfy the mass and  $L^1$ -type conservation laws:

$$M[t] = \int (u(x,t))^2 dx = M[0],$$
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• The energy is also conserved: in the gKdV case

$$E_{gKdV}[t] = \frac{1}{2} \int |\partial_x u(x,t)|^2 \, dx - \frac{1}{(\alpha+1)(\alpha+2)} \int \left(u(x,t)\right)^{\alpha+2} \, dx.$$

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and in the GKdV case

$$E_{GKdV}[t] = \frac{1}{2} \int |\partial_x v(x,t)|^2 \, dx - \frac{1}{(\alpha+1)(\alpha+2)} \int |v(x,t)|^{\alpha+2} \, dx$$

• In a few very specific cases the gKdV equation has infinitely many conserved quantities: in the KdV ( $\alpha = 1$ ) and the modified KdV ( $\alpha = 2$ ); these models are referred to as completely integrable.

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- No other cases of gKdV or GKdV are known to be completely integrable.
- Both (gKdV) and (GKdV) equations are invariant under the scaling: if *u* solves one of them, then so does

$$u_{\lambda}(x,t) = \lambda^{\frac{2}{\alpha}} u(\lambda x, \lambda^{3}t), \quad \lambda > 0.$$

Consequently, the (homogeneous) Sobolev space  $\dot{H}^{s_c}$  is invariant under the scaling when

$$s_c = \frac{1}{2} - \frac{2}{\alpha}$$

.

The traveling (solitary) wave solutions for both equations are of the form  $u(x,t) = Q_c(x - ct - c_0)$ , where c > 0 denotes the speed of propagation,  $c_0$  is an initial shift, and  $Q_c$  is the rescaled ground state solution Q,

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$$Q_c(x) = c^{\frac{1}{\alpha}}Q(c^{\frac{1}{2}}x),$$

where Q is taken to be a smooth, positive, vanishing at infinity solution in the GKdV case of the equation:

$$-Q + Q'' + \frac{1}{(\alpha+1)}|Q|^{\alpha}Q = 0,$$

and in the gKdV case

$$-Q + Q'' + \frac{1}{(\alpha+1)}Q^{\alpha+1} = 0.$$

Though technically the equations above are different, the positive (ground state) solutions are the same in both cases. In such case, we have

$$Q(x) = \left(\frac{(\alpha+1)(\alpha+2)}{2}\right)^{\frac{1}{\alpha}} \operatorname{sech}^{\frac{2}{\alpha}}\left(\frac{\alpha x}{2}\right),$$



Figure 1: The ground state profiles Q for  $\alpha = \frac{1}{9}, \frac{5}{9}, \frac{7}{9}, 1, 3$ .





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#### Remark

One of the major difficulties for well-posedness is that the nonlinearities are not necessarily smooth

 $u^{\alpha}\partial_x u, \qquad |v|^{\alpha}\partial_x v$ 

e.g., if  $0 < \alpha < 1$ , the function  $z \mapsto |z|^{\alpha}$  is not of class  $C^1$ . Classical methods of LWP are not expected to work in general.

#### Strategies

• The approach to obtain the existence is based on the work of Cazenave and Naumkin 2016, where authors developed a method to obtain local and global well-posedness for the NLS equation.

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- The approach to obtain the existence is based on the work of Cazenave and Naumkin 2016, where authors developed a method to obtain local and global well-posedness for the NLS equation.
- The idea is to consider initial conditions satisfying

 $\inf_{x \in \mathbb{R}} \langle x \rangle^m |u_0(x)| > 0,$ 

where  $\langle x \rangle^m = (1 + |x|^2)^{\frac{m}{2}}$ , and construct local solutions of the gKdV and GKdV equations from such data.

#### Theorem (O. et al (2022))

Let  $\alpha > 0$ ,  $m \in \mathbb{R}^+$ ,  $m > \max\{\frac{1}{2\alpha}, \frac{1}{2}\}$ . Let  $s \in \mathbb{Z}$  with  $s \ge 2m + 4$ , and assume that  $u_0$  is a real-valued (or complex-valued) function such that

$$v_0 \in H^s(\mathbb{R}), \ \langle x \rangle^m v_0 \in L^\infty(\mathbb{R}), \ \langle x \rangle^m \partial_x^j v_0 \in L^2(\mathbb{R}), \ j = 1, 2, 3, 4,$$
(1)

$$\|v_0\|_{H^s} + \|\langle x \rangle^m v_0\|_{L^{\infty}} + \sum_{j=1}^4 \|\langle x \rangle^m \partial_x^j v_0\|_{L^2} < \delta$$
(2)

for some  $\delta > 0$  and

$$\inf_{x \in \mathbb{R}} \langle x \rangle^m |v_0(x)| =: \lambda > 0.$$
(3)

Then there exist  $T = T(\alpha, \delta, s, \lambda) > 0$  and a unique solution v of the GKdV equation (or a unique solution u of the gKdV equation with  $\alpha = \frac{m}{k} > 0$ , where m, k are odd integers) in the class

$$v \in C([0,T]; H^s(\mathbb{R})), \qquad \langle x \rangle^m \partial_x^j v \in C([0,T]; L^2(\mathbb{R})), \ j = 1, 2, 3, 4$$
 (4)

with

$$\langle x \rangle^m v \in C([0,T]; L^{\infty}(\mathbb{R})), \qquad \partial_x^{s+1} v \in L^{\infty}(\mathbb{R}; L^2([0,T])), \tag{5}$$

and

$$\sup_{0 \le t \le T} \|\langle x \rangle^m (v(t) - u_0)\|_{L^{\infty}} \le \frac{\lambda}{2}.$$
 (6)

Moreover, the map  $u_0 \mapsto v(\cdot, t)$  is continuous in the following sense: for any compact  $I \subset [0, T]$ , there exists a neighborhood V of  $u_0$  satisfying (1) and (3) such that the map is Lipschitz continuous from V into the class defined by (4) and (5).

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A key argument is the deduction of the following lemma, which relates the action of fractional weights on solutions of the linear KdV equation.

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A key argument is the deduction of the following lemma, which relates the action of fractional weights on solutions of the linear KdV equation.

#### Lemma

Let  $m \in \mathbb{R}^+$ . Then for any  $t \in \mathbb{R}$ , there exists C > 0 such that  $\|\langle x \rangle^m e^{t\partial_x^3} f\|_{L^2} \le C \langle t \rangle^{\lfloor m \rfloor + 1} (\|J^{2m}f\|_{L^2} + \|\langle x \rangle^m f\|_{L^2}).$ 

Here, we denote by  $\{e^{t\partial_x^3}\}_{t\in\mathbb{R}}$  the unitary group associated to solutions of the Airy equation  $\partial_t u + \partial_x^3 u = 0$  with initial condition  $u_0$ .

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#### Idea proof decay lemma

We write  $m = m_1 + m_2$ , where  $m_1 \in \mathbb{Z}^+ \cup \{0\}$ ,  $m_2 \in [0, 1)$ . Then by Plancherel's identity and Leibniz's rule, we deduce

$$\begin{aligned} \|\langle x \rangle^m e^{t\partial_x^3} f\|_{L^2} &\leq C \|e^{t\partial_x^3} f\|_{L^2} + C \||x|^{m_2} |x|^{m_1} U(t) f\|_{L^2} \\ &\leq C \|f\|_{L^2} + C \|D^{m_2} \left(\frac{d^{m_1}}{d\xi^{m_1}} (e^{it\xi^3} \widehat{f})\right)\|_{L^2}. \end{aligned}$$
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To deal with the local derivative, we use the identity

$$\frac{d^k}{d\xi^k}(e^{it\xi^3}) = e^{it\xi^3} \sum_{l=0}^{\lfloor \frac{2k}{3} \rfloor} c_l t^{k-l} \xi^{2k-3l},$$

For the fractional part, we use one Stein's derivatives

$$\mathcal{D}^{\beta}f(x) = \left(\int_{\mathbb{R}^N} \frac{|f(x) - f(y)|^2}{|x - y|^{N + 2\beta}} \, dy\right)^{1/2}, \ x \in \mathbb{R}^N$$

Which satisfies  $\|\mathcal{D}^{\beta}f\|_{L^{2}} = \|D^{\beta}f\|_{L^{2}} = \||\xi|^{\beta}\widehat{f}\|_{L^{2}}.$ 

Another key ingredient to study the nonlinear equation is the following sharp version of Kato's smoothing effect.

Lemma (Kenig-Ponce-Vega 1993) For all  $f \in L^2(\mathbb{R})$  complex or real valued,  $\|e^{t\partial_x^3}f\|_{L^\infty_t L^2_x} + \|\partial_x U(t)f\|_{L^\infty_x L^2_t} = (1 + \frac{1}{\sqrt{3}})\|f\|_{L^2}.$ 

Our LWP is obtained by using the contraction mapping principle based on the integral formulation of gKdV or GKdV acting on the following space

Our LWP is obtained by using the contraction mapping principle based on the integral formulation of gKdV or GKdV acting on the following space

$$\begin{aligned} \mathcal{X}_{T} &= \Big\{ u \in C([0,T]; H^{s}(\mathbb{R})) : \\ \|u\|_{\mathcal{X}_{T}} &:= \|u\|_{L_{T}^{\infty}H_{x}^{s}} + \|\langle x \rangle^{m} u\|_{L_{T}^{\infty}L_{x}^{\infty}} + \sum_{l=1}^{4} \|\langle x \rangle^{m} \partial_{x}^{l} u\|_{L_{T}^{\infty}L_{x}^{2}} \\ &+ \|\partial_{x}^{s+1} u\|_{L_{x}^{\infty}L_{T}^{2}} \leq 2C_{1}\delta, \\ &\sup_{0 \leq t \leq T} \|\langle x \rangle^{m} (u(t) - u(0))\|_{L^{\infty}} \leq \frac{\lambda}{2} \Big\}. \end{aligned}$$

#### Remarks

• An example of initial data that satisfies the conditions in the LWP theorem

$$u_0(x) = \frac{2\lambda e^{i\theta}}{\langle x \rangle^m} + \varphi(x), \quad \lambda \in \mathbb{R}, \quad \theta \in \mathbb{R},$$

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with  $\varphi \in \mathcal{S}(\mathbb{R})$  (the Schwartz class of functions).

• Numerically we study solutions to the Cauchy problems gKdV and GKdV with initial data decaying at infinity as slow as 1/|x|. We have LWP for a wider class of conditions with  $\beta > \max\{\frac{1}{2\alpha}, \frac{1}{2}\}$  (for  $\alpha > \frac{1}{2}$ ).

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- The class of initial data does not include any exponentially decaying data. for example, the ground state.

#### Remarks

• Using the numerical approach, we are able to investigate the behavior of solutions which decay exponentially.

- Using the numerical approach, we are able to investigate the behavior of solutions which decay exponentially.
- An interesting problem it to investigate analytically LWP for solutions of gKdV and GKdV in spaces that include the ground state Q (i.e., exponential spaces).





2 Local well-posedness results



### 4 Bibliography

#### Soliton resolution conjecture

It formally states that a solution will eventually evolve into a finite number of solitons plus radiation, i.e.,

$$u(x,t) \approx \sum_{j=0}^{N} Q_{c_j}(x - c_j t - a_j) + r(x,t)$$

as  $t \to \infty$ , where r(x,t) is the radiation and  $Q_c$  is some rescaled version of a soliton with a shift  $a_j$  and speed  $c_j = c_j(t) \to c_j^*$ .

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#### Numerical confirmation for gKdV and GKdV

We confirm the soliton resolution in various settings for single peak initial data (e.g., perturbations of solitons, Gaussian, super-Gaussian and polynomially decaying data).

We consider Schamel's equation (GKdV with  $|u|^{\frac{1}{2}}\partial_x u$ ) with initial condition  $u_0(x) = Ae^{-x^2}$ .

#### Remark

As typical for the KdV-type equations, a part of the solution propagates to the right as a soliton (or several solitons) and another part of the solution produces dispersive oscillations to the left, referred to as the radiation, decaying toward negative infinity



Figure 2: Time evolution in Schamel's equation of Gaussian data  $u_0 = A e^{-x^2}$  (left), at t = 50 (middle) and t = 200 (right) with the fitting to the rescaled soliton  $Q_c$ . Top row: A = 6. Bottom row: A = -6.

We consider initial condition

$$u_0(x) = v_0(x) = AQ(x+a)$$

We check the evolution of solutions of gKdV  $(u^{\alpha}\partial_x u)$ , and GKdV  $(|u|^{\alpha}\partial_x u)$  when A > 0, A < 0.

### Large time behavior: Case A > 0



Figure 3: Time evolution for  $u_0 = v_0 = Q(x + 25)$  for  $\alpha = \frac{1}{9}$  (top row) and  $\alpha = \frac{7}{9}$  (bottom row); solution u of (gKdV) (solid blue) and v of (GKdV) (dotted red). Right column: both solutions are fitted with shifted  $Q_c = Q$  from (c = 1).

### Large time behavior: Case A < 0



Figure 4: Time evolution for  $u_0 = v_0 = -Q(x+25)$  for  $\alpha = \frac{1}{9}$  (top row) and  $\alpha = \frac{7}{9}$  (bottom row). Right column: the GKdV solution v(x,t) (dashed red) fitted to shifted  $Q_c$  (dotted magenta).

We consider initial condition

$$u_0(x) = v_0(x) = Ae^{-(x-a)^2}.$$

We check the evolution of solutions of gKdV  $(u^{\alpha}\partial_x u)$ , and GKdV  $(|u|^{\alpha}\partial_x u)$ .



Figure 5: Time evolution for  $u_0 = v_0 = Ae^{-(x+50)^2}$ , A = 6 and  $\alpha = \frac{1}{9}$ .

### Large time behavior: A > 0

#### Remark

• We observe what Miura called the "parade of solitons", i.e., the formation of a train of solitons with decreasing heights (or speed), and thus, eventually separating further and further from each other.

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## Large time behavior: A > 0

- We observe what Miura called the "parade of solitons", i.e., the formation of a train of solitons with decreasing heights (or speed), and thus, eventually separating further and further from each other.
- When  $0 < \alpha \ll 1$ , we don't need a large domain to observe the train of solitons, which is an advantage compared with integer powers.
- The solitons of gKdV  $(u^{\alpha}\partial_x u)$  model are slightly higher (and thus, faster) than the ones generated by the same data in the GKdV  $(|v|^{\alpha}\partial_x v)$  model.

## Large time behavior: A < 0



Figure 6: Time evolution for  $u_0 = v_0 = A e^{-(x+a)^2}$ . Top row:  $\alpha = \frac{1}{9}$ , A = -6, a = 50. Second row:  $\alpha = \frac{7}{9}, A = -6, a = 50$ .

### Remarks

• The solutions of gKdV start radiating to the left (solid blue).

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- Whereas the solutions to the GKdV evolve the negative bump into a (negative) soliton propagating to the right, and smaller in amplitude radiation outgoing to the left.
- The larger the power *α* is, the faster the separation of the soliton(s) from radiation occurs.
- We observe that in GKdV the formation of solitons is not influenced by the sign of the initial condition.



Figure 7: The gKdV time evolution for  $u_0 = -6 e^{-x^2}$ ,  $\alpha = \frac{1}{9}$ , till t = 100.

#### Remarks

• One can observe that the first negative bump in the radiation decreases in its magnitude (becomes smaller, see the top row), and then eventually disappears.

- One can observe that the first negative bump in the radiation decreases in its magnitude (becomes smaller, see the top row), and then eventually disappears.
- Then the next positive bump starts to separate from the pulse-like radiation, and because it is positive (in gKdV model), it starts forming a soliton, or asymptotically approaches a rescaled version of it.

#### Remarks

We also study the cases α → 0. We find that the smaller the power α is, the longer the time the solution evolves into a rescaled soliton (the biggest bump) and the shorter the height of that bump is (for the same data).

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- We conjecture that when  $\alpha \to 0$ , the time the main lump evolves into a soliton will go to  $\infty$  as well.

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- We conjecture that when  $\alpha \to 0$ , the time the main lump evolves into a soliton will go to  $\infty$  as well.
- We also study the iteration of two bump profiles.



### 1 Introduction

- 2 Local well-posedness results
- 3 Numerical Investigations

### 4 Bibliography

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