

# Some Advances in the Planar Directed Steiner Tree Problem

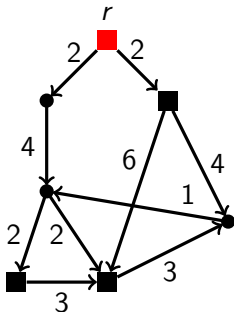
Zachary Friggstad and [Ramin Mousavi](#)

University of Alberta

**Alberta-Montana Combinatorics and Algorithms  
Workshop 2022**

## Definition

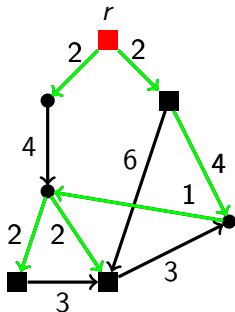
- ▶ Given a directed graph  $G = (V, E)$ , cost on edges, root node  $r$ , and a set of terminals  $X \subseteq V - r$ . The rest of vertices are called Steiner nodes
- ▶ Find a min cost subgraph such that every terminal is reachable from the root



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- ▶ Unidirected version has  $\approx 1.39$ -approx [Byrka et al. - 2013](#)

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- ▶ Planar and quasi-bipartite instances in the undirected version of DST have a rich literature, e.g. PTAS for planar instances [Borradaile et al. - 2009](#), and  $\approx 1.22$ -approx for quasi-bipartite instances [Goemans et al. - 2012](#)

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### Theorem (Friggstad-M.)

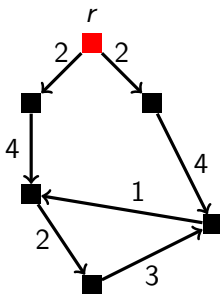
*There is a 20-approx for DST on quasi-bipartite, planar instances. We can generalize it to any graph that excludes a fixed minor.*

## Toolbox: primal-dual

- ▶ Primal-dual algorithm is rare in the directed network design problems. One use of this is in Arborescence (more on this in the next slide).
- ▶ In contrast, primal-dual algorithm is used in the undirected network design abundantly, e.g. [Guha et al. - 1999](#), [Könemann et al. - 2013](#), [Moldenhauer 2013](#), and [Demaine et al. - 2014](#)
- ▶ Why primal-dual algorithm is preferred? Can be viewed as combinatorial algorithm and usually fast and easy to implement!

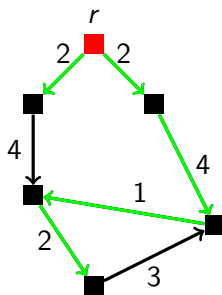
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Given a directed graph, edge cost and a root node  $r$ . Find a cheapest subgraph such that every node is reachable from  $r$



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$\delta^{in}(S)$  is the set of edges entering  $S$  and  $x(\delta^{in}(S)) := \sum_{e \in \delta^{in}(S)} x_e$

### Primal LP

$$\min \sum_e c_e \cdot x_e$$

$$x(\delta^{in}(S)) \geq 1, \forall S \subseteq V - r$$

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### Dual LP

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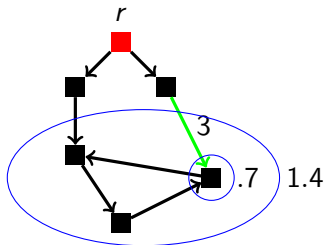
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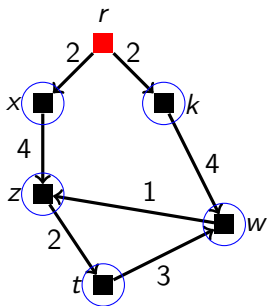
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# Primal-dual in action!

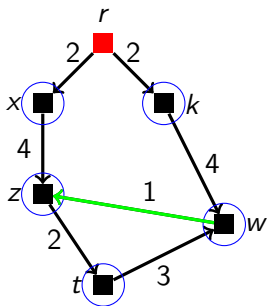
Recall the dual constraint for edge  $e$  is  $\sum_{S:e \in \delta^{in}(S)} y_S \leq c_e$

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Increase  $y_{\{x\}}, y_{\{k\}}, \dots$



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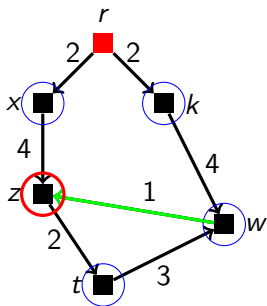


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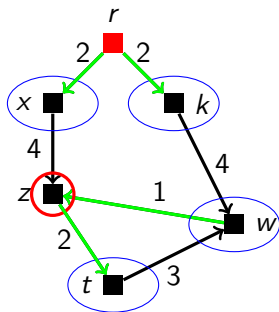
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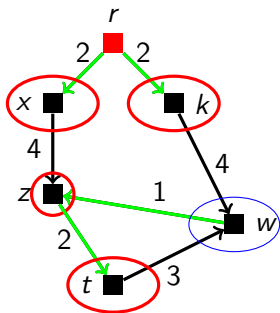
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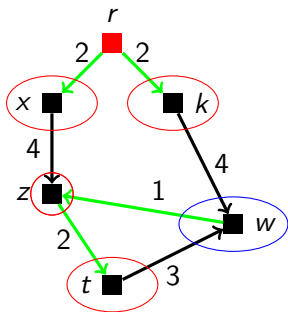
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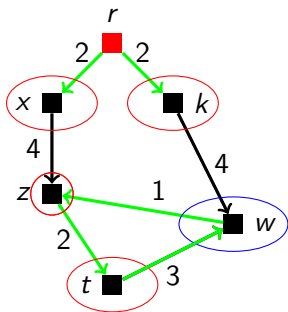
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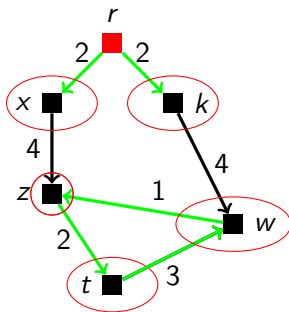
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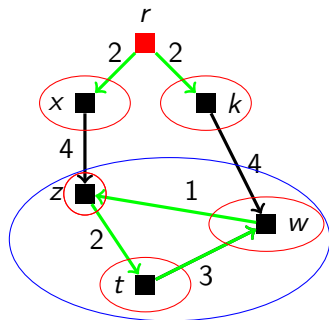


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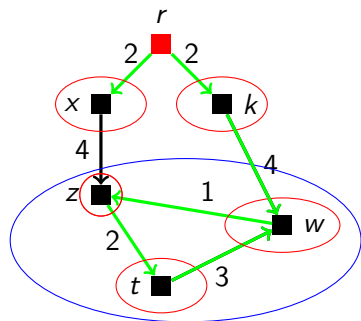
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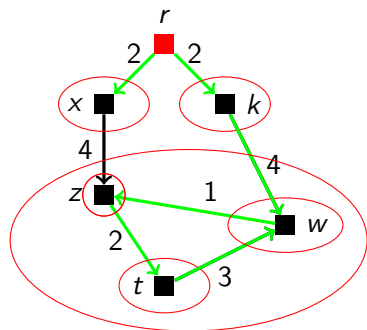
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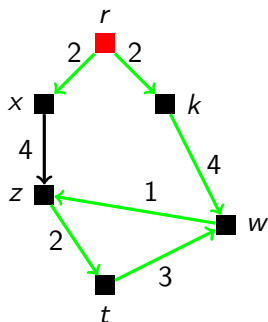
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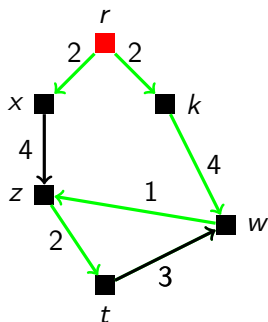


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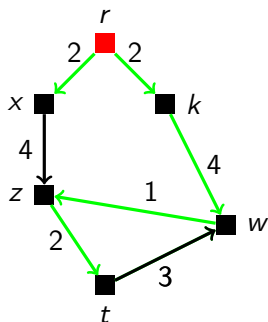
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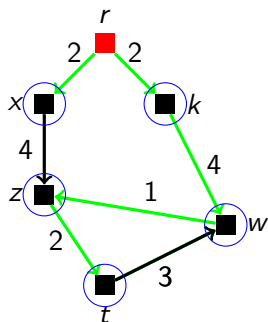
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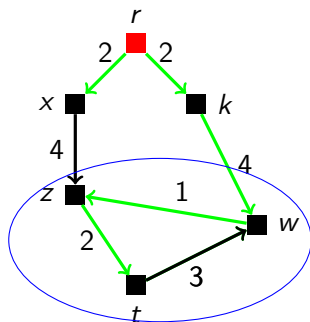
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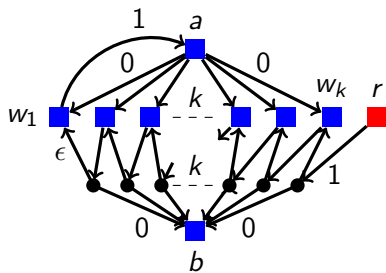
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## Dual LP

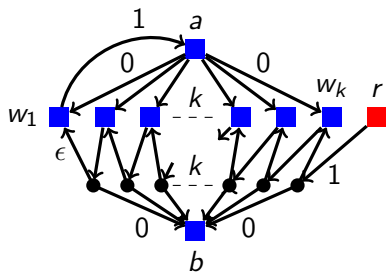
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- ▶  $\text{cost}(F) \leq 20 \cdot \text{cost}(\bar{y}) \leq 20 \cdot \text{OPT}$
- ▶ Natural thing to try is to use the “same” primal-dual algorithm for Arborescence here!

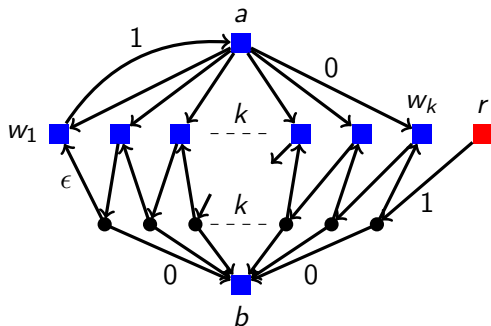
There is always an obstacle!



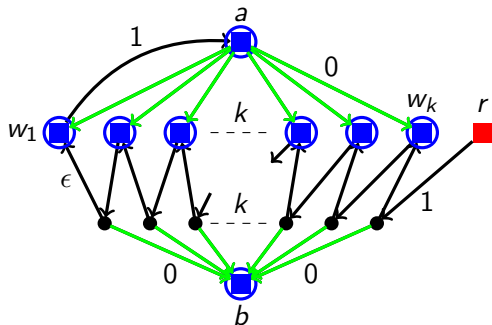
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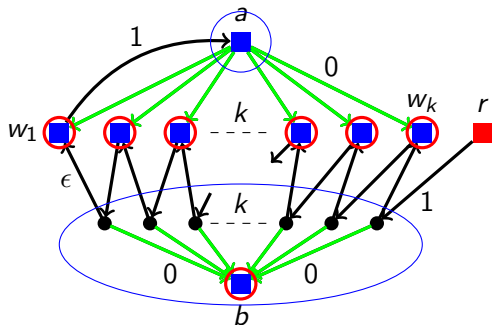
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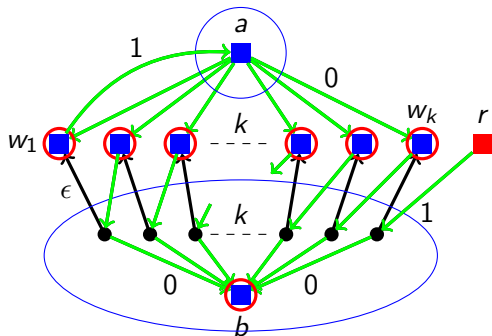
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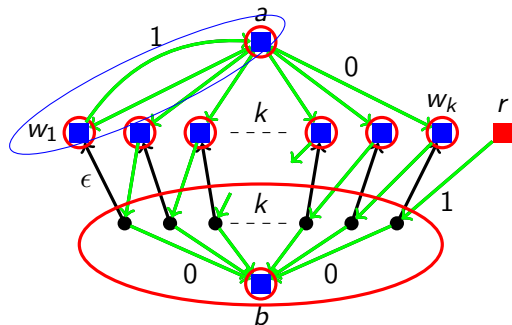


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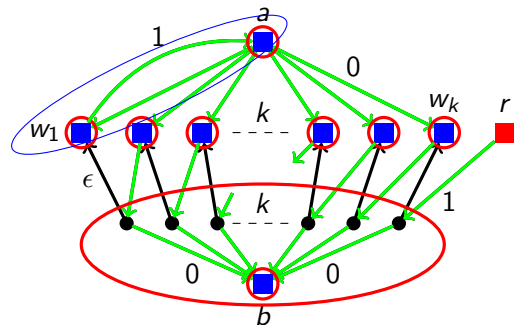




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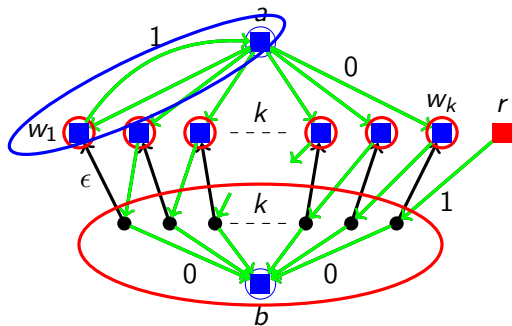


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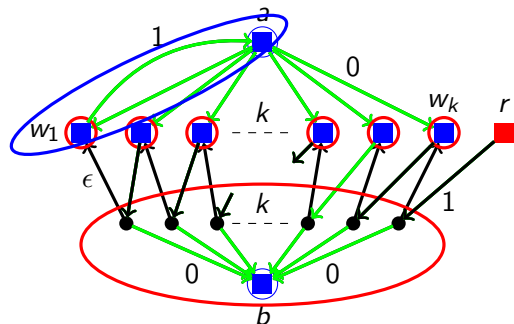
- ▶ Bottom set bought too many edges that aren't used for its connectivity

But sometimes there is a bypass!



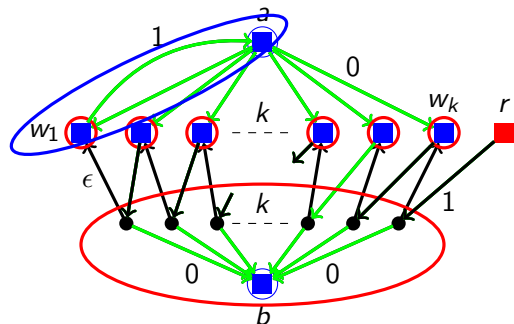
- ▶ Make the bottom set to purchase only one of the downward edges.

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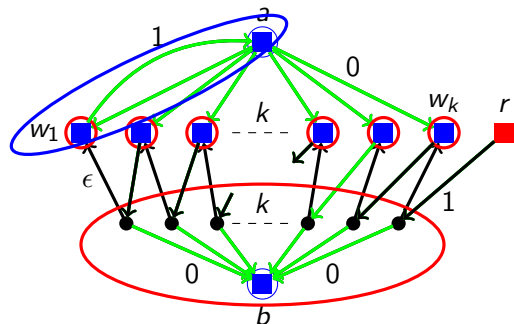
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- ▶ The top active set will buy the rest of the downward edges as it grows.
- ▶ How to formalize this?
- ▶ Introducing two buckets: expansion and killer!

But sometimes there is a bypass!

- ▶ Where does planarity is used?!

# But sometimes there is a bypass!

- ▶ Where does planarity is used?!
  - ▶ The average degree of active sets w.r.t. final solution is constant



## But sometimes there is a bypass!

- ▶ Where does planarity is used?!
  - ▶ The average degree of active sets w.r.t. final solution is constant
  - ▶ We actually need every minor of the graph also has a constant average degree

## Open problems

- ▶ Planar DST?
- ▶ Planar DAG DST?
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**Thank You**

## Bonus! The analysis

- ▶ Fix an iteration

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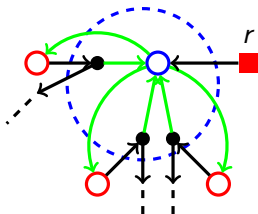
- ▶ Fix an iteration
- ▶ Every active set has at most one killer edge entering it

## Bonus! The analysis

- ▶ Fix an iteration
- ▶ Every active set has at most one killer edge entering it
- ▶ What about expansion edges?

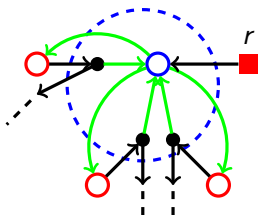
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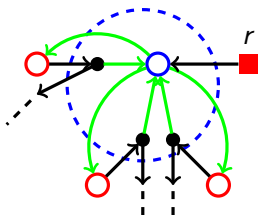


- ▶ Charge the expansion edges to an active set down the road!



## Bonus! The analysis

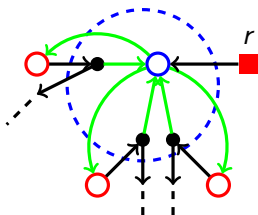
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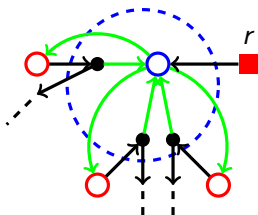
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## Bonus! The analysis

- ▶ Fix an iteration
- ▶ Every active set has at most one killer edge entering it
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- ▶ Charge the expansion edges to an active set down the road!
- ▶ Where does planarity is used?!
  - ▶ Recall relation between average degree of active sets and performance guarantee
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