

Asymptotics and the gradient expansion

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Universality near equilibrium

Consider the expectation value of the energy momentum tensor in some **microscopic** theory. Close to equilibrium we will find

$$\langle \hat{T}^{\mu\nu} \rangle = \mathcal{E} u^\mu u^\nu + \mathcal{P}(\mathcal{E})(g^{\mu\nu} + u^\mu u^\nu) + \eta \sigma^{\mu\nu} + \dots$$

What do we expect?

- Option 1: for gradients of fixed magnitude, adding more terms will give an increasingly more accurate answer
- Option 2: for a fixed number of terms, the answer will become more accurate as the magnitude of the gradients diminishes

The second possibility means that the series is **asymptotic** but not necessarily convergent.

At late times: **universal** asymptotic behaviour across many theories.

Some quantities such as dispersion relations in the linearised theory are represented by series with a **finite radius of convergence** [Withers 1803.18058; Grozdanov, Kovtun, Starinets, Tadic 1904.01018, 1904.12862].

Divergent examples: late proper-time expansion of Bjorken flow in

- N=4 SYM via AdS/CFT
- Kinetic Theory (RTA)

The divergence of the gradient expansion:

- expresses the fact that subdominant contributions had been dropped
- **explains why** hydrodynamics works so well: “divergent series converge faster than convergent series” (G. Carrier)
- is connected with **non-hydrodynamic modes** in the microscopic theory (fast processes) so it should be seen as generic.

Relativistic Hydrodynamics

Conservation equation:

$$\nabla_{\alpha} T^{\alpha\beta} = 0$$

Constitutive relations as a gradient expansion

$$T^{\mu\nu} = \mathcal{E} u^{\mu} u^{\nu} + \mathcal{P}(\mathcal{E})(g^{\mu\nu} + u^{\mu} u^{\nu}) + \Pi^{\mu\nu}$$

The goal of hydrodynamics is match the (**asymptotic**) gradient expansion of any microscopic theory:

$$\Pi^{\mu\nu} = -\eta\sigma^{\mu\nu} + \dots$$

Why should the gradient expansion be divergent **in hydrodynamics**?

Causality and regulators

Known ways to do avoid acausal behaviour of Navier-Stokes theory:

- Mueller; Israel, Stewart (2nd order causal hydro)
- Bemfica, Disconzi, Noronha; Kovtun (1st order causal hydro)

Both these approaches introduce non-hydrodynamic modes which appear as a **UV-regulator** needed to maintain causality.

E.g. MIS (sound channel)

$$\omega_{\text{NH}} = -i \left(\frac{1}{\tau_\pi} - \frac{4}{3} \frac{\eta}{T s} k^2 \right) + \dots$$

Group velocity

$$v = \frac{1}{\sqrt{3}} \sqrt{1 + 4 \frac{\eta/s}{T \tau_\pi}} < 1 \quad \Leftrightarrow \quad T \tau_\pi > 2\eta/s$$

The relaxation time
is the regulator parameter



Two options:

- use hydrodynamics in regimes where it is independent of the regulator
- match the non-hydrodynamic sector to some microscopic theory

Testing for regulator independence:

- Compare results between different MIS variants and BDNK
- Look at sensitivity to 2nd order TCs [Habich et al. 1512.05354]
- Check separation of hydro and non-hydro modes [MS 1607.06381]

Modeling the non-hydrodynamic sector:

- Leading QNM of N=4 SYM [Heller, Janik, MS, Witaszczyk 1409.5087]
- Quasihydrodynamics [Grozdanov, Lucas, Poovutticul 1810.10016]

Asymptotics of Bjorken flow in MIS

The equations of MIS hydrodynamics imply a first order ODE which determines the pressure anisotropy

$$C_{\tau_\pi} \left(1 + \frac{\mathcal{A}}{12} \right) \mathcal{A}' + \left(\frac{C_{\tau_\pi}}{3w} + \frac{C_{\lambda_1}}{8C_\eta} \right) \mathcal{A}^2 = \frac{3}{2} \left(\frac{8C_\eta}{w} - \mathcal{A} \right)$$

where

$$\mathcal{A} \equiv \frac{\mathcal{P}_T - \mathcal{P}_L}{\mathcal{P}}, \quad w \equiv \tau T$$

Asymptotic late-time solution (the gradient expansion):

$$\mathcal{A} = \underbrace{\frac{8C_\eta}{w}}_{\text{Navier-Stokes}} + \underbrace{\frac{16C_\eta(C_{\tau_\pi} - C_{\lambda_1})}{3w^2}}_{\text{2nd order}} + \dots$$

Universal - no dependence on initial conditions.

Exponential corrections imply a transseries structure

$$\mathcal{A} = \underbrace{\sum_{n>0} \frac{a_n^{(0)}}{w^n}}_{\Phi_0(w)} + \sigma e^{-\frac{3}{2C_{\tau\pi}}w} \underbrace{\left(w^{\frac{C_\eta - 2C_{\lambda_1}}{C_{\tau\pi}}} \sum_{n \geq 0} \frac{a_n^{(1)}}{w^n} \right)}_{\Phi_1(w)} + \dots$$

The form is determined by the non-hydrodynamic sector

$$\mathcal{A} = \sum_{n=0}^{\infty} \sigma^n e^{in\Omega w} \Phi_n(w), \quad \Omega = i \frac{3}{2C_{\tau\pi}} = -i \frac{3}{2} \text{Im}(\omega)$$

- The hydro sector is universal: no memory of initial conditions
- The transseries parameter contains the initial data
- The transseries describes the dissipation of initial state information
- Resurgence: all coefficients can be recovered from the hydro ones!

The energy density of N=4 SYM as a transseries

$$\mathcal{E}(u, \sigma) = \sum_{n \in \mathbb{N}_0^\infty} \sigma^n e^{-n \cdot A u} \Phi_n(u), \quad u \equiv \tau^{2/3}$$

Vector of QNM frequencies:

$$\mathbf{A} = (A_1, \bar{A}_1, A_2, \bar{A}_2, \dots)$$

Sectors labelled by

$$\mathbf{n} = (n_1, n_{\bar{1}}, n_2, n_{\bar{2}}, \dots) = \sum_i n_i \mathbf{e}_i + \sum_i n_{\bar{i}} \bar{\mathbf{e}}_i$$

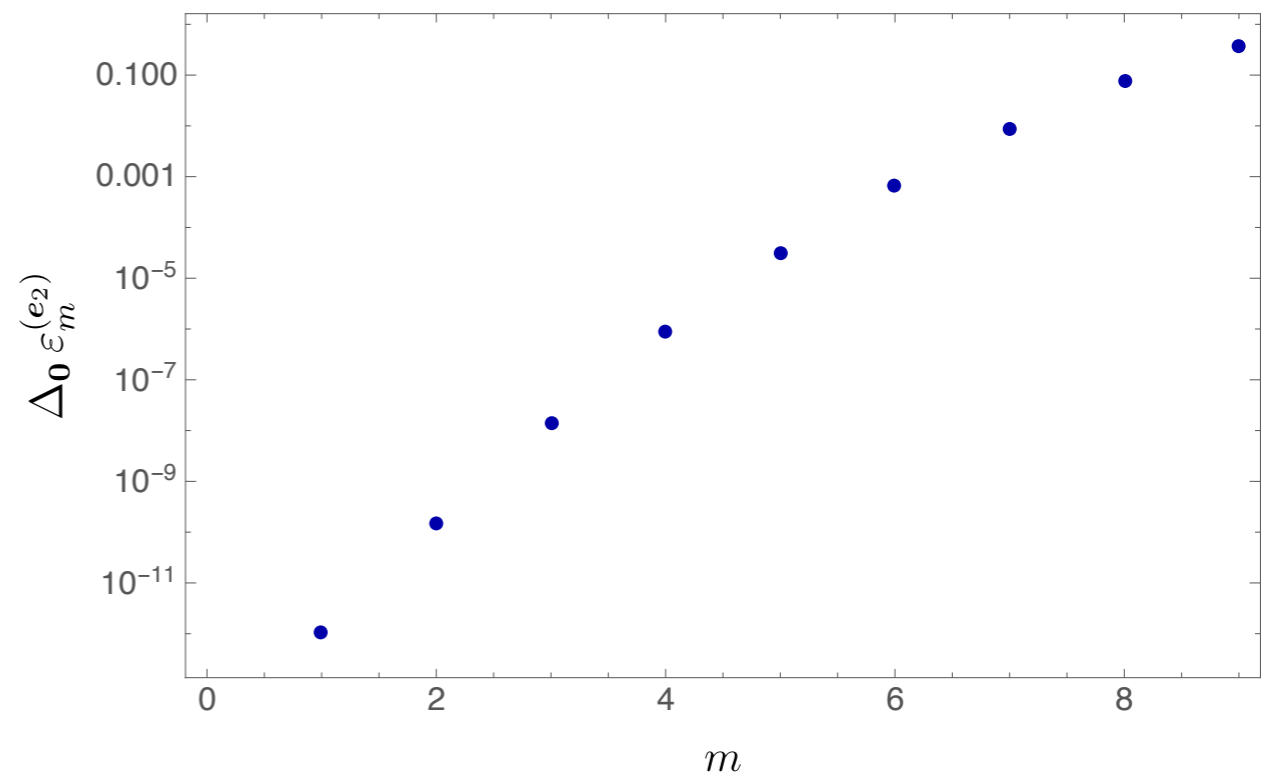
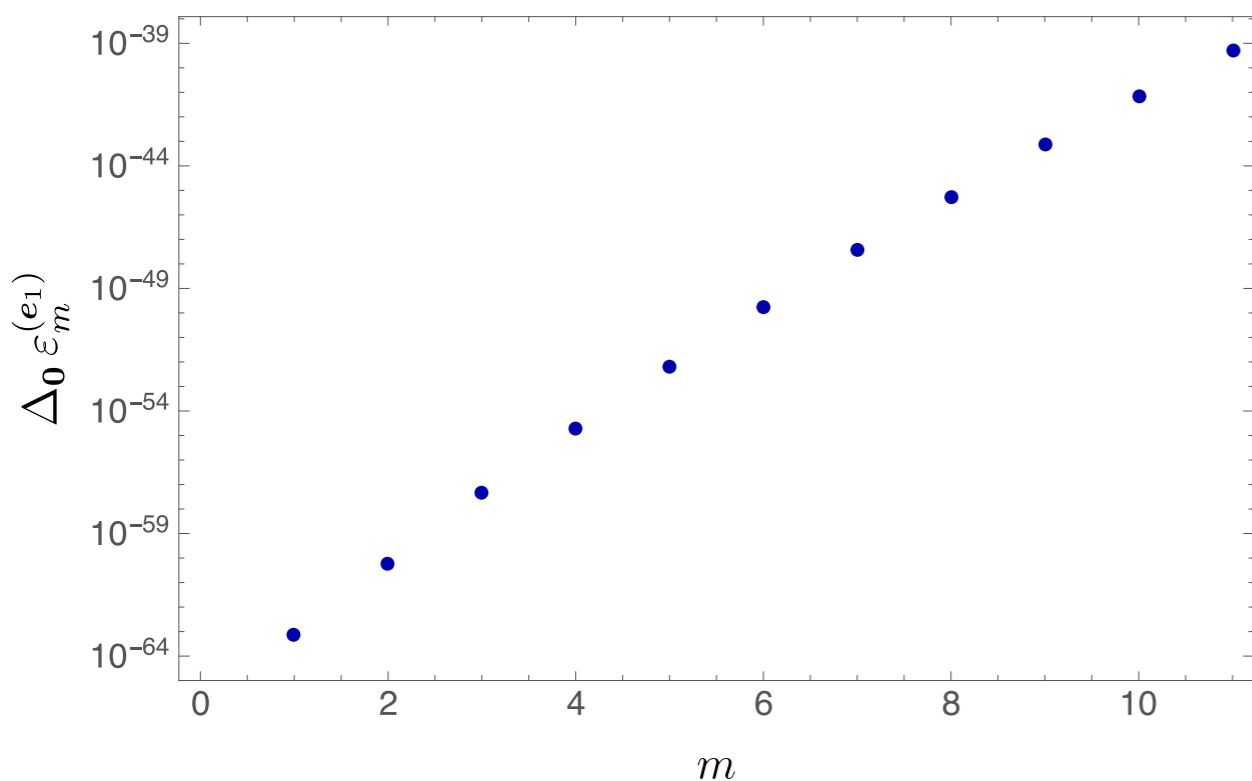
Transseries sectors

$$\Phi_n(u) = u^{-\beta_n} \sum_{k=0}^{+\infty} \varepsilon_k^{(n)} u^{-k}$$

Transseries parameters (integration constants):

$$\sigma^n \equiv \sigma_1^{n_1} \sigma_{\bar{1}}^{n_{\bar{1}}} \sigma_2^{n_2} \sigma_{\bar{2}}^{n_{\bar{2}}} \dots$$

- **Hydro sector:** $n = \mathbf{0}$ (380 coeffs)
- **Fundamental sectors** corresponding to individual QNMs
 - $n = e_1$ (250 coeffs)
 - $n = e_2$ (200 coeffs)
- **Mixed sectors** corresponding to QNM coupling
 - $n = 2e_1$ (100 coeffs)
 - $n = e_1 + \bar{e}_1$ (100 coeffs)



Resurgence: all you need is the (hydrodynamic) gradient expansion.

Late times linearised MIS

The shear channel dispersion relation is (+ is the hydro mode)

$$\omega_{\pm} = \frac{1}{2\tau_R} \left(-i \pm \sqrt{4D\tau_R k^2 - 1} \right), \quad D \equiv \frac{\eta}{T_S}$$

The Green's function of the corresponding linear problem solves

$$(\tau_R \partial_t^2 + \partial_t - D \partial_x^2) G(t, x) = \delta(t) \delta(x)$$

It can be calculated exactly and satisfies causality constraints.

$$G(t, x) = \theta(t - |x|) (I_+(t, x) + I_-(t, x)) \equiv \theta(t - |x|) \tilde{G}(t, x)$$

$$I_{\pm}(t, x) = \pm \frac{1}{2\pi} \int_0^{\infty} dk \frac{e^{i(kx - \omega_{\pm} t)}}{\omega_+ - \omega_-}$$

Using standard asymptotic methods one finds

$$G_H \equiv \tilde{G}(t,0) \sim \frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{t}} \sum_{k=0}^{\infty} a_k t^{-k}$$

$$a_k = \frac{(-1)^k \Gamma(1/2 + k)}{2^{k+1} \Gamma(1/2 - k) \Gamma(1 + k)}$$

This series is factorially divergent:

$$\frac{a_{k+1}}{a_k} \sim \frac{k}{2t}$$

The Borel transform can be done analytically

$$\mathcal{B}[\sqrt{t}G_H](\xi) = \sum_{n \geq 0} \frac{a_n}{\Gamma[n+1]} \xi^n = \frac{1}{\sqrt{2\pi^{3/2}}} K(\xi/2) \equiv B(\xi)$$

The elliptic function K has a cut on the real axis; the location of the branch point of the Borel transform is set by the relaxation time.

Correspondingly, the Borel sum exhibits a **complex ambiguity**

$$\mathcal{S}_{\pm}G_H = \sqrt{t} \int_{C_{\pm}} d\xi e^{-w\xi} B(\xi) = \frac{1}{2}e^{-t} \left(I_0(t) \pm \frac{i}{\pi} K_0(t) \right)$$

Thus, the answer is given up to an exponentially damped contribution

$$\mathcal{S}G_H = \mathcal{S}_-G_H + \sigma \left(\mathcal{S}_+G_H - \mathcal{S}_-G_H \right)$$

To get a real result the transseries parameter must be

$$\sigma = \frac{1}{2} + c, \quad c \in \mathbb{R}$$

The non-hydrodynamic mode contribution cancels the ambiguity.

This matches the exact result for the Green function.

Summary

- Gradient expansions appear both in microscopic theories and in hydrodynamic models and are asymptotic (and often divergent)
- The divergence is connected with the presence of non-hydrodynamic (gapped) modes which act as a UV-regulator necessary for causality
- The realm of applicability of hydrodynamics can be understood as the region of regulator-independence
- It may be interesting and useful to formulate theories of hydrodynamics with specific non-hydrodynamic sectors