Why in some cases the asymptotic linearized problem yields optimal results for a nonlinear version of the "carré du champ"

Maria J. Esteban

CEREMADE CNRS & Université Paris-Dauphine

in collaboration with J. Dolbeault, M. Loss and M. Muratori

"Entropies, the Geometry of Nonlinear Flows, and their Applications", BIRS, April 10, 2018

Why in some cases the asymptotic linearized problem yields optimal results for a nonlinear version of the "carré du champ" - p.1/21

Symmetry, symmetry breaking and nonlinear flows

In this talk I will discuss symmetry and symmetry breaking issues for the positive solutions of equations like

$$-\operatorname{div}\left(|x|^{-\beta} \nabla w\right) = |x|^{-\gamma} \left(w^{2p-1} - w^p\right) \quad \text{in} \quad \mathbb{R}^d \setminus \{0\}\,,$$

Alternatively, we could consider the equation

 $-\Delta \varphi + \Lambda \varphi = \varphi^{p-1}$ on \mathcal{M} , \mathcal{M} is a sphere, a compact manifold, an infinite cylinder...

Symmetry, symmetry breaking and nonlinear flows

In this talk I will discuss symmetry and symmetry breaking issues for the positive solutions of equations like

$$-\operatorname{div}\left(|x|^{-\beta} \nabla w\right) = |x|^{-\gamma} \left(w^{2p-1} - w^p\right) \quad \text{in} \quad \mathbb{R}^d \setminus \{0\}\,,$$

Alternatively, we could consider the equation

 $-\Delta \varphi + \Lambda \varphi = \varphi^{p-1}$ on \mathcal{M} , \mathcal{M} is a sphere, a compact manifold, an infinite cylinder...

We will see that this discussion about symmetry is strongly linked to the use of nonlinear flows and entropies.

Symmetry, symmetry breaking and nonlinear flows

In this talk I will discuss symmetry and symmetry breaking issues for the positive solutions of equations like

$$-\operatorname{div}\left(|x|^{-\beta} \nabla w\right) = |x|^{-\gamma} \left(w^{2p-1} - w^p\right) \quad \text{in} \quad \mathbb{R}^d \setminus \{0\}\,,$$

Alternatively, we could consider the equation

 $-\Delta \varphi + \Lambda \varphi = \varphi^{p-1}$ on \mathcal{M} , \mathcal{M} is a sphere, a compact manifold, an infinite cylinder...

We will see that this discussion about symmetry is strongly linked to the use of nonlinear flows and entropies.

- Elliptic approach (DEL, Invent 2016; DELM, CRAS, 2017).
- Parabolic approach (DEL, J. Ell. Parab. Eqs 2016).
- Linearization around symmetric solutions and optimality (DEL, J. Ell. Parab. Eqs 2016).

Caffarelli-Kohn-Nirenberg (CKN) critical and subcritical inequalities

$$\begin{split} \left(\int_{\mathbb{R}^d} \frac{|w|^{2p}}{|x|^{\gamma}} \, dx \right)^{\frac{1}{2p}} &\leq \mathcal{C}_{\beta,\gamma,p} \left(\int_{\mathbb{R}^d} \frac{|\nabla w|^2}{|x|^{\beta}} \, dx \right)^{\frac{\theta}{2}} \left(\int_{\mathbb{R}^d} \frac{|w|^{p+1}}{|x|^{\gamma}} \, dx \right)^{\frac{1-\theta}{p+1}} \\ \gamma - 2 &< \beta < \frac{d-2}{d} \gamma, \quad \gamma \in (-\infty, d), \quad p \in (1, p_\star] , \\ p_\star &:= \frac{d-\gamma}{d-\beta-2} \quad \text{and} \quad \vartheta = \frac{(d-\gamma)\left(p-1\right)}{p\left(d+\beta+2-2\gamma-p\left(d-\beta-2\right)\right)}. \end{split}$$

Caffarelli-Kohn-Nirenberg (CKN) critical and subcritical inequalities

$$\left(\int_{\mathbb{R}^d} \frac{|w|^{2p}}{|x|^{\gamma}} dx \right)^{\frac{1}{2p}} \leq \mathcal{C}_{\beta,\gamma,p} \left(\int_{\mathbb{R}^d} \frac{|\nabla w|^2}{|x|^{\beta}} dx \right)^{\frac{\theta}{2}} \left(\int_{\mathbb{R}^d} \frac{|w|^{p+1}}{|x|^{\gamma}} dx \right)^{\frac{1-\theta}{p+1}}$$
$$\gamma - 2 < \beta < \frac{d-2}{d} \gamma, \quad \gamma \in (-\infty,d), \quad p \in (1,p_\star],$$
$$p_\star := \frac{d-\gamma}{d-\beta-2} \quad \text{and} \quad \vartheta = \frac{(d-\gamma)(p-1)}{p(d+\beta+2-2\gamma-p(d-\beta-2))}.$$

When $p = p_{\star} = q/2$, $\theta = 1$, the above inequality becomes

$$\left(\int_{\mathbb{R}^d} \frac{|w|^q}{|x|^{b\,q}} \, dx\right)^{2/q} \le \mathsf{C}_{a,b} \int_{\mathbb{R}^d} \frac{|\nabla w|^2}{|x|^{2\,a}} \, dx$$

with $a \le b \le a+1$ if $d \ge 3$, $a < b \le a+1$ if d = 2, $a \ne \frac{d-2}{2}$

$$q = \frac{2d}{d - 2 + 2(b - a)}$$

$$\left(\int_{\mathbb{R}^d} \frac{|w|^q}{|x|^{b\,q}} \, dx\right)^{2/q} \le \mathsf{C}_{a,b} \int_{\mathbb{R}^d} \frac{|\nabla w|^2}{|x|^{2\,a}} \, dx$$

 $C_{a,b} = best constant for general functions w$ $C_{a,b}^* = best constant for radially symmetric functions w$

 $\mathsf{C}^*_{a,b} \le C_{a,b}$

Up to scalar multiplication and dilation, the optimal radial function is

$$w_{a,b}^*(x) = \left(1 + |x|^{-\frac{2a(1+a-b)}{b-a}}\right)^{-\frac{b-a}{1+a-b}}$$

Question: is optimality (equality) achieved ? do we have $w_{a,b} = w_{a,b}^*$?

Linear instability of radial minimizers: the Felli-Schneider curve

Looking for the set of pairs (a, b) such that the functional

$$\mathsf{C}_{a,b}^{\star} \int_{\mathbb{R}^d} \frac{|\nabla w|^2}{|x|^{2\,a}} \, dx - \left(\int_{\mathbb{R}^d} \frac{|w|^p}{|x|^{b\,p}} \, dx \right)^{2/p}$$

is linearly instable at $w = w_{a,b}^*$ (Catrina, Wang; Felli, Schneider).



Moving planes and symmetrization techniques

The symmetry region:



Chou, Chu; Horiuchi (a > 0)

Betta, Brock, Mercaldo, Posteraro (a < 0, b > 0)

Perturbation results: C-S Lin, Z-Q Wang; Smets, Willem; Dolbeault, E., Tarantello (2007 & 2009)

The minimizers are radially symmetric outside of the Felli-Schneider zone.

That is,

The symmetric minimizers are global minimizers whenever they are stable / whenever they are local minimizers.

That is,

Instability of radial minimizers is the only possible cause of symmetry breaking.

The minimizers are radially symmetric outside of the Felli-Schneider zone.

That is,

The symmetric minimizers are global minimizers whenever they are stable / whenever they are local minimizers.

That is,

Instability of radial minimizers is the only possible cause of symmetry breaking.

ANSWER: YES (Dolbeault, E., Loss, Inv. 2016).

Resolution of the conjecture: A Sobolev type inequality

Define

$$\alpha = \sqrt{\frac{d-1}{n-1}} =: \alpha_{\rm FS}$$
 (Stability zone defined by $\alpha \le \alpha_{\rm FS}$)

THEOREM [2016].- If $\alpha \leq \alpha_{FS}$ and $d \geq 2$, optimality is achieved by radial functions.

Idea of the proof : With the change of variables : $r \mapsto r^{\alpha}$, $w(r, \omega) = v(r^{\alpha}, \omega)$, and with

$$n = \frac{d - b p}{\alpha} = \frac{d - 2 a - 2}{\alpha} + 2, \qquad \mathsf{D}v = \left(\alpha \frac{\partial v}{\partial r}, \frac{1}{r} \nabla_{\omega} v\right)$$

 $p = \frac{2n}{n-2}$ and the CKN the inequality becomes

$$\alpha^{1-\frac{2}{p}} \left(\int_{\mathbb{R}^d} |v|^p \, d\mu_n \right)^{\frac{2}{p}} \leq \mathsf{C}_{a,b} \int_{\mathbb{R}^d} |\mathsf{D}v|^2 \, d\mu_n \,, \quad d\mu := r^{n-1} \, dr \, d\omega \, `` = dx \, (\mathbb{R}^n)"$$

Resolution of the conjecture: A Sobolev type inequality

Define

$$\alpha = \sqrt{\frac{d-1}{n-1}} =: \alpha_{\rm FS}$$
 (Stability zone defined by $\alpha \le \alpha_{\rm FS}$)

THEOREM [2016].- If $\alpha \leq \alpha_{FS}$ and $d \geq 2$, optimality is achieved by radial functions.

Idea of the proof : With the change of variables : $r \mapsto r^{\alpha}$, $w(r, \omega) = v(r^{\alpha}, \omega)$, and with

$$n = \frac{d - b p}{\alpha} = \frac{d - 2 a - 2}{\alpha} + 2, \qquad \mathsf{D}v = \left(\alpha \frac{\partial v}{\partial r}, \frac{1}{r} \nabla_{\omega} v\right)$$

 $p = \frac{2n}{n-2}$ and the CKN the inequality becomes

$$\alpha^{1-\frac{2}{p}} \left(\int_{\mathbb{R}^d} |v|^p \, d\mu_n \right)^{\frac{2}{p}} \leq \mathsf{C}_{a,b} \int_{\mathbb{R}^d} |\mathsf{D}v|^2 \, d\mu_n \,, \quad d\mu := r^{n-1} \, dr \, d\omega \, `` = dx \, (\mathbb{R}^n) "$$

The parameters α and n vary in the ranges $0 < \alpha < \infty$ and $d < n < \infty$ and the *Felli-Schneider curve* in the (α, n) variables is given by $\alpha = \alpha_{FS}$.

Notations

If ∇_{ω} denotes the gradient with respect to the angular variables $\omega \in S^{d-1}$ and Δ_{ω} is the Laplace-Beltrami operator on S^{d-1} , we define

$$\mathsf{D}v = \left(\alpha \, \frac{\partial v}{\partial r}, \frac{1}{r} \, \nabla_\omega v\right) \;,$$

we define the self-adjoint operator L by

$$Lv := -D^* D v = \alpha^2 v'' + \alpha^2 \frac{n-1}{r} v' + \frac{\Delta_{\omega} v}{r^2}$$

The fundamental property of L is the fact that

$$\int_{\mathbb{R}^d} v_1 \operatorname{L} v_2 d\mu_n = -\int_{\mathbb{R}^d} \operatorname{D} v_1 \cdot \operatorname{D} v_2 d\mu_n \quad \forall v_1, v_2 \in \mathcal{D}(\mathbb{R}^d)$$

 \triangleright Heuristics: we look for a monotonicity formula along a well chosen nonlinear flow, based on the analogy with the decay of the Fisher information along the fast diffusion flow in \mathbb{R}^d

Fisher information decay and a fast diffusion equation

Let $u = |v|^p$, $p = \frac{2n}{n-2}$.

Up to multiplicative constants, $\int_{\mathbb{R}^d} |v|^p d\mu_n = \int_{\mathbb{R}^d} u d\mu_n$, and $\int_{\mathbb{R}^d} |\mathsf{D}v|^2 d\mu_n = \mathcal{I}[u]$, with

$$\mathcal{I}[u] := \int_{\mathbb{R}^d} u \, |\mathsf{Dp}|^2 \, d\mu_n \,, \quad \mathsf{p} = \frac{m}{1-m} \, u^{m-1} \quad \text{and} \quad m = 1 - \frac{1}{n}$$

Here \mathcal{I} is the *Fisher information* and p is the *pressure function*.

Let $u = |v|^p$, $p = \frac{2n}{n-2}$.

Up to multiplicative constants, $\int_{\mathbb{R}^d} |v|^p d\mu_n = \int_{\mathbb{R}^d} u d\mu_n$, and $\int_{\mathbb{R}^d} |\mathsf{D}v|^2 d\mu_n = \mathcal{I}[u]$, with

$$\mathcal{I}[u] := \int_{\mathbb{R}^d} u \, |\mathsf{Dp}|^2 \, d\mu_n \,, \quad \mathsf{p} = rac{m}{1-m} \, u^{m-1} \quad \text{and} \quad m = 1 - rac{1}{n}$$

Here \mathcal{I} is the *Fisher information* and p is the *pressure function*.

Next, define the fast diffusion equation (flow)

$$\frac{\partial u}{\partial t} = \mathbf{L}u^m, \quad m = 1 - \frac{1}{n}$$

 \triangleright STRATEGY: Assume that $\alpha \leq \alpha_{\rm FS}$,

1) prove that for all $t \ge 0$, $\frac{d}{dt} \int_{\mathbb{R}^d} u(t) d\mu_n = 0$ and $\frac{d}{dt} \mathcal{I}[u(t, \cdot)] \le 0$,

2) prove that $\frac{d}{dt}\mathcal{I}[u(t,\cdot)] = 0$ means, in particular, that u is radially symmetric.

Mass conservation and Fisher information decay along the fast diffusion flow

Easy to see: the mass $\int_{\mathbb{R}^d} u \, d\mu_n$ is conserved along the flow.

With
$$\mathbf{p} = \frac{m}{1-m} u^{m-1}$$
, $\mathcal{I}[u] := \int_{\mathbb{R}^d} u |\mathsf{D}\mathbf{p}|^2 d\mu_n$,

Some calculations: Let $u_0 \ge 0$. Up to estimates near the origin and near infinity,

$$\frac{d}{dt}\mathcal{I}[u(t,\cdot)] = -2(n-1)^{n-1} \int_{\mathbb{R}^d} \mathcal{K}[\mathbf{p}] \, \mathbf{p}^{1-n} \, d\mu_n \,,$$

with $d\mu_n = r^{n-1} dx$ and $\zeta_{\star} > 0$,

$$\begin{split} \mathcal{K}[\mathbf{p}] &:= \alpha^4 \left(1 - \frac{1}{n} \right) \left[\mathbf{p}'' - \frac{\mathbf{p}'}{r} - \frac{\Delta_{\omega} \, \mathbf{p}}{\alpha^2 \left(n - 1 \right) r^2} \right]^2 + 2 \, \alpha^2 \, \frac{1}{r^2} \left| \nabla_{\omega} \mathbf{p}' - \frac{\nabla_{\omega} \mathbf{p}}{r} \right|^2 \\ &+ \frac{1}{r^4} \left(\left(n - 2 \right) \left(\alpha_{\mathrm{FS}}^2 - \alpha^2 \right) \int_{S^d} |\nabla_{\omega} \mathbf{p}|^2 \, \mathbf{p}^{1-n} \, d\omega + \zeta_\star \left(n - d \right) \int_{S^d} |\nabla_{\omega} \mathbf{p}|^4 \, \mathbf{p}^{1-n} \, d\omega \right) \,. \end{split}$$

Mass conservation and Fisher information decay along the fast diffusion flow

Easy to see: the mass $\int_{\mathbb{R}^d} u \, d\mu_n$ is conserved along the flow.

With
$$\mathbf{p} = \frac{m}{1-m} u^{m-1}$$
, $\mathcal{I}[u] := \int_{\mathbb{R}^d} u |\mathsf{D}\mathbf{p}|^2 d\mu_n$,

Some calculations: Let $u_0 \ge 0$. Up to estimates near the origin and near infinity,

$$\frac{d}{dt}\mathcal{I}[u(t,\cdot)] = -2(n-1)^{n-1} \int_{\mathbb{R}^d} \mathcal{K}[\mathbf{p}] \, \mathbf{p}^{1-n} \, d\mu_n \,,$$

with $d\mu_n = r^{n-1} dx$ and $\zeta_{\star} > 0$,

$$\begin{split} \mathcal{K}[\mathbf{p}] &:= \alpha^4 \left(1 - \frac{1}{n} \right) \left[\mathbf{p}'' - \frac{\mathbf{p}'}{r} - \frac{\Delta_{\omega} \, \mathbf{p}}{\alpha^2 \left(n - 1 \right) r^2} \right]^2 + 2 \, \alpha^2 \, \frac{1}{r^2} \left| \nabla_{\omega} \mathbf{p}' - \frac{\nabla_{\omega} \mathbf{p}}{r} \right|^2 \\ &+ \frac{1}{r^4} \left(\left(n - 2 \right) \left(\alpha_{\rm FS}^2 - \alpha^2 \right) \int_{S^d} |\nabla_{\omega} \mathbf{p}|^2 \, \mathbf{p}^{1-n} \, d\omega + \zeta_\star \left(n - d \right) \int_{S^d} |\nabla_{\omega} \mathbf{p}|^4 \, \mathbf{p}^{1-n} \, d\omega \right) \,. \end{split}$$

So, if $\alpha \leq \alpha_{\rm FS}$, $\frac{d}{dt}\mathcal{I}[u(t,\cdot)] \leq 0$, and $\frac{d}{dt}\mathcal{I}[u(t,\cdot)] = 0$ implies that p is radially symmetric.

Elliptic proof for rigidity (uniqueness of positive solutions) if $\alpha \leq \alpha_{FS}$

If $\alpha \leq \alpha_{FS}$ and if p_0 is a critical point of the E-L equations for CKN, written in the good variables, then

$$\frac{\partial}{\partial t} \mathcal{I}[u(t)]_{|_{t=0}} = \mathcal{I}'[\mathsf{u}(t)] \cdot \frac{\partial}{\partial t} u(t)_{|_{t=0}} = \mathcal{I}'[\mathsf{u}_0] \cdot \mathrm{L}u_0^m = 0 = -C \int_{\mathbb{R}^d} \mathcal{K}[\mathsf{p}_0] \,\mathsf{p}_0^{1-n} \,d\mu_n \,, \ \mathsf{p}_0 = \frac{m \, u_0^{m-1}}{1-m} \,d\mu_n \,d\mu_$$

$$0 = \mathcal{K}[\mathbf{p}_{0}] \ge \int_{\mathbb{R}^{d}} \alpha^{4} \left(1 - \frac{1}{n}\right) \left[\mathbf{p}_{0}^{\prime\prime} - \frac{\mathbf{p}_{0}^{\prime}}{r} - \frac{\Delta_{\omega} \,\mathbf{p}_{0}}{\alpha^{2} \left(n - 1\right) r^{2}}\right]^{2} \,\mathbf{p}_{0}^{1-n} \,d\mu_{n}$$
$$+ \int_{\mathbb{R}^{d}} \left(n - 2\right) \left(\alpha_{\mathrm{FS}}^{2} - \alpha^{2}\right) |\nabla_{\omega} \mathbf{p}_{0}|^{2} \,\mathbf{p}_{0}^{1-n} \,d\mu_{n} + \int_{\mathbb{R}^{d}} \zeta_{\star} \left(n - d\right) |\nabla_{\omega} \mathbf{p}_{0}|^{4} \,\mathbf{p}_{0}^{1-n} \,d\mu_{n} \,,$$

where $\zeta_{\star} > 0$ and n > d.

Elliptic proof for rigidity (uniqueness of positive solutions) if $\alpha \leq \alpha_{FS}$

If $\alpha \leq \alpha_{FS}$ and if p_0 is a critical point of the E-L equations for CKN, written in the good variables, then

$$\frac{\partial}{\partial t} \mathcal{I}[u(t)]_{|t=0} = \mathcal{I}'[\mathsf{u}(t)] \cdot \frac{\partial}{\partial t} u(t)_{|t=0} = \mathcal{I}'[\mathsf{u}_0] \cdot \mathrm{L}u_0^m = 0 = -C \int_{\mathbb{R}^d} \mathcal{K}[\mathsf{p}_0] \,\mathsf{p}_0^{1-n} \,d\mu_n \,, \ \mathsf{p}_0 = \frac{m \, u_0^{m-1}}{1-m} \,d\mu_n \,d\mu_$$

$$0 = \mathcal{K}[\mathbf{p}_0] \ge \int_{\mathbb{R}^d} \alpha^4 \left(1 - \frac{1}{n}\right) \left[\mathbf{p}_0'' - \frac{\mathbf{p}_0'}{r} - \frac{\Delta_{\omega} \, \mathbf{p}_0}{\alpha^2 \, (n-1) \, r^2}\right]^2 \, \mathbf{p}_0^{1-n} \, d\mu_n \\ + \int_{\mathbb{R}^d} \left(n-2\right) \left(\alpha_{\rm FS}^2 - \alpha^2\right) |\nabla_{\omega} \mathbf{p}_0|^2 \, \mathbf{p}_0^{1-n} \, d\mu_n + \int_{\mathbb{R}^d} \zeta_{\star} \, (n-d) \, |\nabla_{\omega} \mathbf{p}_0|^4 \, \mathbf{p}_0^{1-n} \, d\mu_n \, ,$$

where $\zeta_{\star} > 0$ and n > d.

So, $\nabla_{\omega} \mathbf{p}_0 \equiv 0$, that is, \mathbf{p}_0 does not depend on ω , which means radial symmetry. Moreover, $\mathbf{p}_0'' - \frac{\mathbf{p}_0'}{r} - \frac{\Delta_{\omega} \mathbf{p}_0}{\alpha^2 (n-1) r^2} \equiv 0$, which implies that for some a, b > 0, $\mathbf{p}_0 = a + b r^2$.

Elliptic proof for rigidity (uniqueness of positive solutions) if $\alpha \leq \alpha_{FS}$

If $\alpha \leq \alpha_{FS}$ and if p_0 is a critical point of the E-L equations for CKN, written in the good variables, then

$$\frac{\partial}{\partial t} \mathcal{I}[u(t)]_{|_{t=0}} = \mathcal{I}'[\mathsf{u}(t)] \cdot \frac{\partial}{\partial t} u(t)_{|_{t=0}} = \mathcal{I}'[\mathsf{u}_0] \cdot \mathrm{L}u_0^m = 0 = -C \int_{\mathbb{R}^d} \mathcal{K}[\mathsf{p}_0] \,\mathsf{p}_0^{1-n} \,d\mu_n \,, \ \mathsf{p}_0 = \frac{m \, u_0^{m-1}}{1-m} \,d\mu_n \,d\mu_$$

$$0 = \mathcal{K}[\mathbf{p}_0] \ge \int_{\mathbb{R}^d} \alpha^4 \left(1 - \frac{1}{n}\right) \left[\mathbf{p}_0'' - \frac{\mathbf{p}_0'}{r} - \frac{\Delta_{\omega} \, \mathbf{p}_0}{\alpha^2 \, (n-1) \, r^2}\right]^2 \, \mathbf{p}_0^{1-n} \, d\mu_n \\ + \int_{\mathbb{R}^d} \left(n-2\right) \left(\alpha_{\rm FS}^2 - \alpha^2\right) |\nabla_{\omega} \mathbf{p}_0|^2 \, \mathbf{p}_0^{1-n} \, d\mu_n + \int_{\mathbb{R}^d} \zeta_{\star} \, (n-d) \, |\nabla_{\omega} \mathbf{p}_0|^4 \, \mathbf{p}_0^{1-n} \, d\mu_n \, ,$$

where $\zeta_{\star} > 0$ and n > d.

So, $\nabla_{\omega} \mathbf{p}_0 \equiv 0$, that is, \mathbf{p}_0 does not depend on ω , which means radial symmetry. Moreover, $\mathbf{p}_0'' - \frac{\mathbf{p}_0'}{r} - \frac{\Delta_{\omega} \mathbf{p}_0}{\alpha^2 (n-1) r^2} \equiv 0$, which implies that for some a, b > 0, $\mathbf{p}_0 = a + b r^2$.

In the case of subcritical CKN inequalities, the method has to be modified, and Renyi entropies shown to be concave:

$$\mathcal{E}[u] := \int_{\mathbb{R}^d} u^m \, d\mu_n \, , \, \mathcal{E}' = (1-m)\mathcal{I} \, , \, \mathcal{R}[u] := \left(\int_{\mathbb{R}^d} u^m \, d\mu_n\right)^\sigma \, , \, \sigma = \frac{1}{d(1-m)} - 1$$

- Painful estimates of boundary terms in integrations by parts.
- No way to obtain improved inequalities from the remainder terms.

- No clear understanging of why a local stability result for the symmetric solutions yields a global result (non existence of other positive solutions apart from the symmetric ones, when these are stable).

Alternative parabolic approach in self-similar variables

With
$$\mu = 2 + n (m - 1)$$
 and $\kappa = \left(\frac{2 m}{1 - m}\right)^{1/\mu}$, let

$$u(t,x) = \frac{1}{\kappa^n R^n} g\left(\tau, \frac{x}{\kappa R}\right) \quad \text{where} \quad \begin{cases} \frac{dR}{dt} = R^{1-\mu}, \quad R(0) = R_0 = \kappa^{-1}, \\ \tau(t) = \frac{1}{2} \log\left(\frac{R(t)}{R_0}\right). \end{cases}$$
(0)

In self-similar variables the function g solves

$$\frac{\partial g}{\partial \tau} = \mathsf{D}^* \left(g \, z \right) \tag{0}$$

where, with the notation $\mathcal{B}_{\alpha}(x) := \left(1 + \frac{|x|^2}{\alpha^2}\right)^{\frac{1}{m-1}}$,

$$z(\tau, x) := \mathsf{D}g^{m-1} - \frac{2}{\alpha}x = \mathsf{D}\left(g^{m-1} - \frac{|x|^2}{\alpha^2}\right) = \mathsf{D}\mathsf{q}\,, \quad \mathsf{q} := g^{m-1} - \mathcal{B}_{\alpha}^{m-1}$$

The exponent m is now in the range $m_1 \leq m < 1$ with $m_1 = 1 - 1/n$.

Bakry-Emery type calculation

For any R >, let us consider the solution of the no-flux boundary problem

$$\frac{\partial g}{\partial \tau} = \mathsf{D}^* \left(g \, z\right) \text{ in } B_R \ ; \quad z \cdot \omega = 0 \quad \text{on } \partial B_R \ .$$

and suppose that g is smooth at the origin. Then, by defining $p := g^{m-1}$, computing in B_R and taking the limit $R \to +\infty$, we get

$$\begin{aligned} \frac{d}{d\tau} \int_{\mathbb{R}^d} g \, |z|^2 \, d\mu_n + 4 \int_{\mathbb{R}^d} g \, |z|^2 \, d\mu_n \\ \leq &-2 \frac{1-m}{m} \int_{\mathbb{R}^d} \left(\alpha^4 \left(1 - \frac{1}{n}\right) \left[\mathsf{p}'' - \frac{\mathsf{p}'}{r} - \frac{\Delta_\omega \, \mathsf{p}}{\alpha^2 \, (n-1) \, r^2} \right]^2 + \frac{2 \, \alpha^2}{r^2} \left| \nabla_\omega \mathsf{p}' - \frac{\nabla_\omega \mathsf{p}}{r} \right|^2 \right) g^m \, d\mu_n \\ &- 2 \frac{1-m}{m} \left(m - m_1\right) \int_{\mathbb{R}^d} \left(\mathsf{L}_\alpha g^{m-1} - 2 \, n \right)^2 \, g^m \, d\mu_n \\ &- 2 \frac{1-m}{m} \int_{\mathbb{R}^d} \frac{\mathsf{Q}[\mathsf{p}]}{r^4} \, g^m \, d\mu_n - 2 \frac{1-m}{m} \left(n-2\right) \left(\alpha_{\mathrm{FS}}^2 - \alpha^2\right) \int_{\mathbb{R}^d} \frac{|\nabla_\omega \mathsf{p}|^2}{r^4} \, g^m \, d\mu_n \end{aligned}$$

$$\leq 0$$
 when $\alpha \leq lpha_{
m FS}$.

Improved inequalities

For all $x \in \mathbb{R}^d$, t > 0 let

$$v_{\star}(t,x) := \frac{1}{\kappa^{n}(\mu t)^{n/\mu}} \,\mathcal{B}_{\star}\left(\frac{x}{\kappa^{\mu/\mu_{\star}} \,(\mu t)^{1/\mu_{\star}}}\right) \quad \text{where} \quad \mathcal{B}_{\star}(x) := \left(1 + |x|^{2+\beta-\gamma}\right)^{-1/(1-m)}$$

$$\mathsf{G}[v] := \left(\int_{\mathbb{R}^d} v^m \, |x|^{-\gamma} \, dx \right)^{\sigma-1} \int_{\mathbb{R}^d} v \, |\nabla \mathsf{p}|^2 \, |x|^{-\beta} \, dx$$

The CKN inequalities are equivalent to the inequality $G[v] \ge G[v_{\star}]$.

Improved inequalities

For all $x \in \mathbb{R}^d$, t > 0 let

$$v_{\star}(t,x) := \frac{1}{\kappa^{n}(\mu t)^{n/\mu}} \, \mathcal{B}_{\star}\left(\frac{x}{\kappa^{\mu/\mu_{\star}} \, (\mu t)^{1/\mu_{\star}}}\right) \quad \text{where} \quad \mathcal{B}_{\star}(x) := \left(1 + |x|^{2+\beta-\gamma}\right)^{-1/(1-m)}$$

$$\mathsf{G}[v] := \left(\int_{\mathbb{R}^d} v^m \, |x|^{-\gamma} \, dx \right)^{\sigma-1} \int_{\mathbb{R}^d} v \, |\nabla \mathsf{p}|^2 \, |x|^{-\beta} \, dx$$

The CKN inequalities are equivalent to the inequality $G[v] \ge G[v_{\star}]$.

THEOREM.- Define
$$h(t) := \left(1 + \frac{2m}{1-m}\mu t\right)^{1/\mu}$$
 $\forall t \ge 0$, with $\mu = 2\frac{2+\beta-d+m(d-\gamma)}{2+\beta-\gamma}$,

$$\mathsf{G}[v(t,\cdot)] - \mathsf{G}[v_{\star}] \ge \mathcal{C} \int_{t}^{\infty} \mathsf{h}(s)^{3\,\mu-2} \int_{\mathbb{R}^{d}} v^{m}(s,x) \, \frac{|\nabla_{\omega} v^{m-1}(s,x)|^{2}}{|x|^{4}} \, |x|^{\gamma-2\beta} \, dx \, ds \quad \forall t \ge 0 \, .$$

if $\alpha \leq \alpha_{\rm FS}$, if v is smooth at the origin, if $||v_0||_{1,\gamma} = ||\mathcal{B}_{\star}||_{1,\gamma}$, and if

$$\left(C_1 + |x|^{2+\beta-\gamma}\right)^{-1/(1-m)} \le v_0(x) \le \left(C_2 + |x|^{2+\beta-\gamma}\right)^{-1/(1-m)} \quad \forall x \in \mathbb{R}^d,$$

(REMARK.- Different, and better, remainder terms in the critical and in the subcritical case).

Linearization and optimality

Let us linearize the equation $\frac{\partial g}{\partial \tau} = \mathsf{D}^*(g z)$ around a Barenblatt profile \mathcal{B}_{α} , by taking a solution g_{ε} s.t. $\int_{\mathbb{R}^d} g_{\varepsilon} = M_{\star} = \int_{\mathbb{R}^d} \mathcal{B}_{\alpha}, \ g_{\varepsilon} = \mathcal{B}_{\alpha} \left(1 + \varepsilon f \mathcal{B}_{\alpha}^{1-m}\right)$. Taking ε to 0 we find

$$\frac{\partial f}{\partial t} = \mathcal{L}_{\alpha} f \quad \text{where} \quad \mathcal{L}_{\alpha} f := (m-1) \mathcal{B}_{\alpha}^{m-2} \mathsf{D}^* (\mathcal{B}_{\alpha} \mathsf{D} f) .$$

We define the scalar products

$$\langle f_1, f_2 \rangle = \int_{\mathbb{R}^d} f_1 f_2 \mathcal{B}_{\alpha}^{2-m} d\mu_n \quad \text{and} \quad \langle \langle f_1, f_2 \rangle \rangle = \int_{\mathbb{R}^d} \mathsf{D} f_1 \cdot \mathsf{D} f_2 \mathcal{B}_{\alpha} d\mu_n$$

and its corresponding Hilbert spaces, X and Y ($Y \subset X$). We see that

$$\frac{1}{2} \frac{d}{dt} \langle f, f \rangle = - \langle \langle f, f \rangle \rangle ; \quad \frac{1}{2} \frac{d}{dt} \langle \langle f, f \rangle \rangle = - \langle \langle f, \mathcal{L}_{\alpha} f \rangle \rangle$$

and if λ_1 is the smallest positive eigenvalue of \mathcal{L}_{α} , with $\mathcal{L}_{\alpha} f_1 = \lambda_1 f_1$, then it has been proved by Bonforte-Dolbeault-Muratori-Nazaret that $f_1 \in Y \subset X$. Moreover $\lambda_1 \ge 4$ iff $\alpha \le \alpha_{FS}$. A simple expansion of a square tells us that λ_1 is also optimal in the inequality

 $-\langle\!\langle g, \mathcal{L}_{\alpha} g \rangle\!\rangle \ge \lambda_1 \langle\!\langle g, g \rangle\!\rangle$, $\forall g$, s.t. $\langle\!\langle g, 1 \rangle\!\rangle = 0$ (Hardy-Poincaré type inequality).

Link between the nonlinear problem and the asymptotic linearized problem

Define
$$\mathcal{I}[g] := \int_{\mathbb{R}^d} g |z|^2 d\mu_n$$
; $\frac{d}{d\tau} \mathcal{I}[g] = -\mathcal{K}[g]$
Since for $\alpha \le \alpha_{\text{FS}}$, $-\mathcal{K}[g] + 4\mathcal{I}[g] = \frac{d}{d\tau} \mathcal{I}[g] + 4\mathcal{I}[g] = \frac{d}{d\tau} \int_{\mathbb{R}^d} g |z|^2 d\mu_n + 4 \int_{\mathbb{R}^d} g |z|^2 d\mu_n \le 0$

the functional $g \mapsto \frac{\mathcal{K}[g]}{\mathcal{I}[g]} - 4$ is nonnegative and if $\alpha \leq \alpha_{\rm FS}$, its minimizer is $g = \mathcal{B}_{\alpha}$. Moreover, with $g_{\varepsilon} = \mathcal{B}_{\alpha} \left(1 + \varepsilon f \mathcal{B}_{\alpha}^{1-m} \right)$,

$$4 \leq \mathcal{C}_2 := \inf_u \frac{\mathcal{K}[g]}{\mathcal{I}[g]} \leq \lim_{\varepsilon \to 0} \inf_f \frac{\mathcal{K}[g_\varepsilon]}{\mathcal{I}[g_\varepsilon]} = \inf_f \frac{\langle\!\langle f, \mathcal{L}_\alpha f \rangle\!\rangle}{\langle\!\langle f, f \rangle\!\rangle} = \frac{\langle\!\langle f_1, \mathcal{L}_\alpha f_1 \rangle\!\rangle}{\langle\!\langle f_1, f_1 \rangle\!\rangle} = \lambda_1 \,.$$

Link between the nonlinear problem and the asymptotic linearized problem

Define
$$\mathcal{I}[g] := \int_{\mathbb{R}^d} g |z|^2 d\mu_n$$
; $\frac{d}{d\tau} \mathcal{I}[g] = -\mathcal{K}[g]$
Since for $\alpha \le \alpha_{\rm FS}$, $-\mathcal{K}[g] + 4\mathcal{I}[g] = \frac{d}{d\tau} \mathcal{I}[g] + 4\mathcal{I}[g] = \frac{d}{d\tau} \int_{\mathbb{R}^d} g |z|^2 d\mu_n + 4 \int_{\mathbb{R}^d} g |z|^2 d\mu_n \le 0$

the functional $g \mapsto \frac{\mathcal{K}[g]}{\mathcal{I}[g]} - 4$ is nonnegative and if $\alpha \leq \alpha_{\text{FS}}$, its minimizer is $g = \mathcal{B}_{\alpha}$. Moreover, with $g_{\varepsilon} = \mathcal{B}_{\alpha} \left(1 + \varepsilon f \, \mathcal{B}_{\alpha}^{1-m} \right)$,

ſ

$$4 \leq \mathcal{C}_2 := \inf_u \frac{\mathcal{K}[g]}{\mathcal{I}[g]} \leq \lim_{\varepsilon \to 0} \inf_f \frac{\mathcal{K}[g_\varepsilon]}{\mathcal{I}[g_\varepsilon]} = \inf_f \frac{\langle\!\langle f, \mathcal{L}_\alpha f \rangle\!\rangle}{\langle\!\langle f, f \rangle\!\rangle} = \frac{\langle\!\langle f_1, \mathcal{L}_\alpha f_1 \rangle\!\rangle}{\langle\!\langle f_1, f_1 \rangle\!\rangle} = \lambda_1 \,.$$

Summarizing, the infimum of \mathcal{K}/\mathcal{I} is achieved in the asymptotic regime as $g \to \mathcal{B}_{\alpha}$ and determined by the spectral gap of \mathcal{L}_{α} when $\lambda_1 = 4$. And $\mathcal{K}/\mathcal{I} > 4$ if $\lambda_1 > 4$, that is, when $\alpha < \alpha_{\rm FS}$. Finally,

If
$$\alpha > \alpha_{\rm FS}$$
, $C_2 = \inf_u \frac{\mathcal{K}[u]}{\mathcal{I}[u]} \le \lambda_1 < \infty$

If
$$\alpha \leq \alpha_{\rm FS}$$
, $4 \leq C_2 = \inf_u \frac{\mathcal{K}[u]}{\mathcal{I}[u]} \leq \lambda_1$.

4

Thank you for your attention!

Why in some cases the asymptotic linearized problem yields optimal results for a nonlinear version of the "carré du champ" - p.20/21

Why in some cases the asymptotic linearized problem yields optimal results for a nonlinear version of the "carré du champ" - p.21/21