## Existence of vortex sheets for 2D stochastic Euler equations

## Mario Maurelli Joint work with Zdzislaw Brzezniak

University of York<sup>1</sup> and University of Edinburgh

Banff, August 20, 2018

<sup>&</sup>lt;sup>1</sup>work supported by Newton International Fellowship

 Introduction
 Aim

 Main result
 Deterministic 2D Euler equations

 Proof
 Stochastic 2D Euler equations, transport noise

 Possible developments
 Stochastic 2D Euler equations, other noises

**Motivation**: in the deterministic case, we have existence of solutions to 2D Euler equations with singular vorticity, in particular vortex sheets (initial vorticity concentrated on a line). Question: what for *stochastic* 2D Euler equations? **Main result**: existence of a martingale solution to the 2D stochastic Euler equations with transport noise:

$$\partial_t \xi + u \cdot \nabla \xi + \sum_k \sigma_k \cdot \nabla \xi \circ \dot{W}^k = 0$$
  
$$\xi = \text{const} + \text{curl} u$$

( $\sigma_k$  given vector fields,  $W^k$  independent Brownian motions) when the vorticity is a non-negative measure and in  $H^{-1}$ . This includes vortex sheets.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

2D Euler equations (on  $\mathbb{R}^2$  or  $\mathbb{T}^2$ )

$$\partial_t u + (u \cdot \nabla)u = -\nabla p$$
  
div $u = 0$ 

In vorticity form:  $\xi = \text{const} + \text{curl u}$  (scalar valued):

$$\partial_t \xi + u \cdot \nabla \xi = 0,$$
  
 $u = K * \xi$ 

where  $K = \nabla^{\perp} G$  and G is the Green function of the Laplacian. Note  $K(x) \approx \frac{x^{\perp}}{|x|^2}$ . Solutions in distributional form.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Results:

- Vorticity ξ in L<sub>x</sub><sup>∞</sup>: existence and uniqueness (Yudovich 63, Marchioro-Pulvirenti 94).
- Vorticity  $\xi$  in  $L^p$ , p > 1: existence (DiPerna-Majda 87).
- Vorticity  $\xi$  in  $\mathcal{M}_+ \cap H^{-1}$ : existence (Delort 91).

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Comparison with Onsager dissipative solutions:

- Vorticity in L<sup>p</sup>: solutions u are more regular (W<sup>1,p</sup>) than Hölder. From DiPerna-Lions and Ambrosio theory: existence of a Lagrangian flow, renormalization expected for bounded u; actually renormalization and energy conservation hold for p > 3/2 and also below under some restrictions.
- Vorticity in  $\mathcal{M}_+ \cap H^{-1}$ : not known.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Now we introduce noise. Noise interpretation:

- uncertainties
- can give rise to turbulent phenomena
- can improve well-posedness theory w.r.t. the deterministic case (regularization by noise)

Here: Extension of Delort existence result to stochastic case.

Introduction Aim Main result Deterministic 2D Euler equations Proof Stochastic 2D Euler equations, transport noise Possible developments Stochastic 2D Euler equations, other noises

Stochastic 2D Euler equations with transport noise (on the vorticity):

$$\partial_t \xi + u \cdot \nabla \xi + \sum_k \sigma_k \cdot \nabla \xi \circ \dot{W}^k = 0$$
$$u = K * \xi$$

Here  $\sigma_k$  are given divergence-free vector fields, assumed regular, and  $W^k$  are independent real Brownian motions,  $\circ$  denotes Stratonovich integration.

Solution:  $\xi : [0, T] \times \mathbb{T}^2 \times \Omega \to \mathbb{R}$  random scalar field.

• Noise interpretation: Calling formally  $\zeta(t,x) = \sum_k \sigma_k(x) \dot{W}^k$ ,  $\zeta$  is a random field, Gaussian, decorrelated in time, correlated and smooth in space.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Features of transport noise:

1) Solution follows stochastic characteristics of the fluid (formally):

$$egin{aligned} &\xi_t(X_t) = \xi_0 \ & dX_t = u(t,X_t) dt + \sigma_k(X_t) \circ dW_t \end{aligned}$$

2) Stochastic Constantin-Iyer formula (proved by Flandoli-Luo for the 3D case)

$$u_t = \Pi[(\nabla X_t^{-1})^T u_0(X_t^{-1})]$$

3) As consequence of transport property: enstrophy and any  $L^p$  norm are preserved.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

In velocity form:

$$\partial_t u + (u \cdot \nabla)u + [(\sigma_k \cdot \nabla)u + (\nabla \sigma_k)^T u] \circ \dot{W}^k = -\nabla p$$
  
div  $u = 0$ 

Note: zero order term, energy (that is  $L^2$  norm of u) is not preserved.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Results:

- Vorticity in L<sup>∞</sup>: existence and uniqueness, in pathwise sense (Brzezniak-Flandoli-M. 16). Idea of proof (in the line of Marchioro-Pulvirenti 94): prove uniqueness of stochastic characteristics (stochastic flows), then prove renormalization-type property.
- Vorticity in L<sup>2</sup>, transport noise in the velocity: existence of a martingale solution (Yokoyama 14, with a similar technique to the one here).

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

Other results:

- Crisan-Flandoli-Holm 17: local existence and uniqueness in 3D.
- Flandoli-Gubinelli-Priola 11: regularization by noise for vorticity concentrated in a finite number of points.

Aim Deterministic 2D Euler equations Stochastic 2D Euler equations, transport noise Stochastic 2D Euler equations, other noises

A few examples of other noises:

- Mikulevicius–Valiukevicius 00: local existence of smooth solutions under 2D  $(+\dot{W}^1 + \dot{W}^2)$  noise.
- Bessaih–Flandoli 99, Bessaih 99: existence of a martingale solution under affine multiplicative noise  $+\sum_{k} \sigma_{k}(x) u \dot{W}^{k}$ .
- Brzezniak–Peszat 01: existence of a martingale solution in  $L^2$  under multiplicative noise +G(u)dW, G(u) in  $W^{1,p}$  (roughly speaking.
- Glatt-Holtz–Vicol 14: existence of smooth solutions under additive noise  $(\sum_k \sigma_k(x) \dot{W}^k)$  and linear multiplicative  $(\alpha u \dot{W}^k)$  noise.

Main result

Stochastic 2D Euler equations on the torus  $\mathbb{T}^2$ :

$$\partial_t \xi + u \cdot \nabla \xi + \sum_k \sigma_k \cdot \nabla \xi \circ \dot{W}^k = 0$$
  
 $u = K * \xi$ 

Assumptions on  $\sigma_k$ :

- divergence-free
- regular:  $\sum_k \|\sigma_k\|_{C^2}^2 < \infty$
- the covariance matrix  $C(x, y) = \sum_{k} \sigma_{k}(x) \sigma_{k}(y)^{T}$  is locally translation-invariant and even (OK if the noise is "locally isotropic")

Main result

## Theorem (Brzezniak-M.)

Assume  $\sigma_k$  as above. Let  $\xi_0$  be in  $\mathcal{M}_+ \cap H^{-1}$ . Then there exists a weak (in the probabilistic sense) solution  $\xi$  with a.s. values in  $C_t(\mathcal{M}_+, w^*) \cap L^2_t(H^{-1})$ .

Main result

Remarks:

- We chose the torus as the simplest case, we expect the result to hold also on  $\mathbb{R}^2.$
- The assumptions on the structure of the covariance matrix associated with  $\sigma_k$  may be relaxed, they are put to simplify Itô-Stratonovich corrections.



How to make sense of  $u \cdot \nabla \xi$  for  $\xi$  measure? u is in general not bounded.

Poupaud 02 trick: since K is odd, we can write formally

$$\int u(x)\xi(x)\nabla\varphi(x)dx = \int \int \xi(x)\xi(y)K(x-y)\nabla\varphi(x)dx$$
$$= \frac{1}{2}\int \int \xi(x)\xi(y)F_{\varphi}(x,y)dx$$

where

$$F_{\varphi}(x,y) = K(x-y) \cdot (\nabla \varphi(x) - \nabla \varphi(y))$$

Recall  $K(x - y) \approx \frac{(x - y)^{\perp}}{|x - y|^2}$ . Therefore, for  $\varphi$  in  $C^2$ ,  $F_{\varphi}$  is regular outside the diagonal  $\{x = y\}$  and bounded everywhere.

Introduction The nonlinear term Main result Strategy Proof Tightness Possible developments Equation for the limit

Hence, for  $\xi$  general measure, we define  $u \cdot \nabla \xi$  as

$$\langle u \cdot \nabla \xi, \varphi \rangle := \int \int \xi(x) \xi(y) F_{\varphi}(x, y) dx dy$$

Note that

$$|\langle u \cdot \nabla \xi, \varphi \rangle| \le C \|\xi\|_{\mathcal{M}}^2 \|\varphi\|_{C^2} \le C \|\xi\|_{\mathcal{M}}^2 \|\varphi\|_{H^4}$$

that is

$$\|u\cdot\nabla\xi\|_{H^{-4}}\leq C\|\xi\|_{\mathcal{M}}^2$$

The nonlinear term Strategy Tightness Equation for the limit

Strategy: 1) tightness 2) equation for any limiting object 1) Tightness: approximation by regular solutions, uniform  $L^{\infty}_{t,\omega}(\mathcal{M}), L^{2}_{t,\omega}(H^{-1})$  and  $L^{2}_{\omega}(C^{\alpha}_{t}(H^{-4}))$  bounds, via transport structure, Poupaud trick, stochastic  $C^{\alpha}$  bounds. 2) Equation for the limiting objects: a.s. convergence (Skorohod-Jakubowski theorem), convergence of nonlinear term by Poupaud trick. Introduction The nonlinear term Main result Strategy Proof Tightness Possible developments Equation for the limit

Take  $\xi^{\epsilon}$  bounded solutions to stochastic Euler equations but with regular initial data  $\xi^{\epsilon}$  approximating  $\xi$ . 1) Uniform  $L^{\infty}_{t,\omega}(\mathcal{M})$  bound: transport structure implies mass conservation:

$$\partial_t \int \xi^{\epsilon} dx = -\int u^{\epsilon} \cdot \nabla \xi^{\epsilon} dx - \int \sigma_k \cdot \nabla \xi^{\epsilon} dx \circ \dot{W}^k = 0$$



2) Uniform  $L_t^{\infty}(L_{\omega}^2(H^{-1}))$  bound: equivalent to uniform  $L_t^{\infty}(L_{\omega}^2(L^2))$  bound on  $u^{\epsilon}$  (energy bound): Equation for  $u^{\epsilon}$ :

$$\partial_t u^{\epsilon} + (u^{\epsilon} \cdot \nabla) u^{\epsilon} + (\sigma_k \cdot \nabla u^{\epsilon}) \circ \dot{W}^k + (\nabla \sigma_k)^T u^{\epsilon} \circ \dot{W}^k = -\nabla p^{\epsilon}$$

Assumptions on  $\sigma_k$  imply that  $(\nabla \sigma_k)^T u^{\epsilon} \circ \dot{W}^k = (\nabla \sigma_k)^T u^{\epsilon} \dot{W}^k$ . Get equation for  $|u^{\epsilon}|^2$  and integrate in x and  $\omega$ :

$$\partial_t \mathbb{E} \int |u^{\epsilon}|^2 dx = \mathbb{E} \int |(\nabla \sigma_k)^T u^{\epsilon}|^2 dx \leq C \mathbb{E} \int |u^{\epsilon}|^2 dx$$

Conclusion by Gronwall lemma.

Introduction The nonlinear term Main result Strategy Proof Tightness Possible developments Equation for the limit

3) Uniform  $L^2_{\omega}(C^{\alpha}_t(H^{-4}))$  bound,  $\alpha < 1/2$ : use Poupaud trick and stochastic calculus:

$$u_t - u_s = -\int_s^t u \cdot \nabla \xi dr - \int_s^t \sigma_k \cdot \nabla \xi dW^k + \frac{1}{2} \int_s^t \operatorname{tr}[C(0)D^2\xi]dr$$

Nonlinear term:  $\|u \cdot \nabla \xi\|_{H^{-4}} \leq C \|\xi\|_{\mathcal{M}}^2$ , hence Lipschitz in time. Stochastic term:  $\|\sigma_k \cdot \nabla \xi\|_{H^{-4}} \leq C \|\sigma_k\|_C \|\xi\|_{\mathcal{M}}$ , hence 1/2-Hölder in time (stochastic integration in the Hilbert space  $H^{-4}$ ).

Introduction	The nonlinear term
Main result	Strategy
Proof	Tightness
Possible developments	Equation for the limit

Tightness in the space  $\chi = C_t(\mathcal{M}_M, w*) \cap (L^2_t(H^{-1}_x), w)$ :

- The set  $A = \{ \mu \in \chi \mid \|\mu\|_{L^2_t(H^{-1}_x,w)} + \|\mu\|_{C^{\alpha}_t(H^{-4}_x)} \le a \}$  is compact.
- Uniform bounds before: Law $(\xi^{\epsilon})(A^{c}) < \delta$  for small  $\epsilon$ .

Introduction Main result	The nonlinear term Strategy
Proof	Tightness
Possible developments	Equation for the limit

Let  $\xi^{\epsilon_n}$  be a subsequence such that  $(W, \xi^n)$  converges in law. Skorokhod-Jakubowski theorem (Jakubowski 97 for r.v. with values in topological spaces): on an enlarged probability space, there exist r.v.  $(\tilde{W}^{(n)}, \tilde{\xi}^n)$ , copies of  $(W, \xi^{\epsilon_n})$ , converging a.s. to a r.v.  $(\tilde{W}, \tilde{\xi})$ . Adaptedness: take  $\tilde{\mathcal{F}}_t$  as the completion of the filtration generated by  $(\tilde{W}, \tilde{\xi})$ , then  $\tilde{W}$  is a (cylindrical) Brownian motion w.r.t.  $\tilde{\mathcal{F}}_t$ and  $\tilde{\xi}$  is adapted w.r.t.  $\tilde{\mathcal{F}}_t$ .



Limiting equation: show that each term in the equation for  $\tilde{\xi}^n$  passes to the limit.

Nonlinear term

$$\int \int \tilde{\xi}(x)\tilde{\xi}(y)F_{\varphi}(x,y)dxdy$$

Poupaud trick:

- If ξ(x)ξ(y) gives no mass to the diagonal {x = y} and ξ is positive, then the nonlinear term converges: indeed recall F<sub>φ</sub> is continuous outside the diagonal.
- If  $\tilde{\xi}$  is in  $H^{-1}$ , then  $\tilde{\xi}$  has no atom and so  $\tilde{\xi}(x)\tilde{\xi}(y)$  gives no mass to the diagonal.

Introduction The nonlinear term Main result Strategy Proof Tightness Possible developments Equation for the limit

Stochastic term: linear but not continuous functional of  $\tilde{\xi}$ . Brzezniak-Goldys-Jegarai 13:

If the integrands were step functions (in time), the stochastic integral would be continuous w.r.t.  $\tilde{\xi}$  and so convergence would hold. In the general case, approximate the integrand by step functions.

Further developments:

- Particle approximation for L<sup>p</sup> vorticity (à la Schochet 96)
- More general noises (fractional Brownian motion, or also non-transport noises)
- $\sigma_k$  irregular? (Kraichnan model for passive scalars)

## Thank you!