Renormalized Stochastic PDE's

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The Finite Dimensional Case

$$\dot{X}_t = -\nabla V(X_t) + \sigma \xi_t, \qquad X_0 = x$$

- $V: \mathbb{R}^d
 ightarrow \mathbb{R}$ is a potential, $\sigma \in \mathbb{R}$ is a scalar
- ξ_t is a white noise is time $\mathbb{E}[\xi_t \xi_s] = \delta(t-s)$
- Equivalently, $\xi = \dot{W}$, where W is a Brownian motion on \mathbb{R}^d
- ▶ The solution X_t^x is a stochastic process indexed by time *t* and the initial condition $x \in \mathbb{R}^d$
- Let µ be a stationary probability distribution on ℝ^d, that is for all times t > 0 and Borel sets A ∈ ℝ^d

$$\int_{\mathbb{R}^d} \mathbb{P}(X_t^{\times} \in A) \mu(x) dx = \int_A \mu(y) dy.$$

- ► Recall that the paths of t → W_t are not smooth, they belong only to C^{1/2−κ} for any κ > 0 (not C^{1/2}).
- ► This makes calculus more interesting: for a smooth ψ : ℝ^d → ℝ it holds

$$\frac{d}{dt}\mathbb{E}^{\times}[\psi(X_t^{\times})] = \mathbb{E}^{\times}\big[-\nabla V(X_t^{\times})\cdot\nabla\psi(X_t^{\times}) + \frac{1}{2}\sigma^2\Delta\psi(X_t^{\times})\big].$$

Averaging over $x \in \mathbb{R}^d$ with respect to μ gives

$$0 = \sum_{i} \int_{\mathbb{R}^{d}} \left[-\partial_{i} V(y) \partial_{i} \psi(y) + \partial_{i}^{2} \psi(y) \right] \mu(y) dy$$
$$= \sum_{i} \int_{\mathbb{R}^{d}} \psi(y) \partial_{i} \left[\partial_{i} V(y) \mu(y) + \frac{\sigma^{2}}{2} \partial_{i} \mu(y) \right] dy$$

This leads to the familiar $\mu(y) = Cexp(-\frac{1}{2\sigma^2}V(y))$.

Stochastic Quantization of Φ_4

$$\partial_t u = \Delta u - u^3 + \xi$$

ξ is a space/time white noise

$$\mathbb{E}[\xi(t,x)\xi(s,y)] = \delta(t-s)\delta(x-y).$$

• Note that
$$\Delta u - u^3 = -
abla V(u)$$
, where

$$V(u) = \int |\nabla u|^2 + \frac{1}{4}u^4 dx$$

- Formally, the invariant measure for the (infinite dimensional) stochastic dynamics is again Cexp(-V(u))du.
- (Parisi-Wu) Try to understand the measure Cexp(-V(u))du through the (infinite dimensional) stochastic dynamics.

A Fundamental Difficulty

$$\partial_t u = \Delta u - u^3 + \xi, \qquad V(u) = \int |\nabla u|^2 + \frac{1}{4}u^4 dx$$

 If the noise ξ is not too rough, the PDE above is well-posed (and well understood in the deterministic literature). For instance, if ξ = 0 one has

$$\frac{d}{dt}|u|_{L^2}^2+V(u)\leq 0.$$

- ► However, space-time white noise ξ is very singular, it is not a function, it belongs to C^{-d+2/2} −κ for all κ > 0.
- Consider the solution v to the linearized problem

$$(\partial_t - \Delta_x)v = \xi,$$

By Schauder theory for parabolic equations, v belongs to $C^{1-\frac{d}{2}-\kappa}$, so at best u belongs to this space, and there is no canonical meaning of u^3 .

2d Case: Da-Prato/Debussche

$$\partial_t u = \Delta u - : u^3 : +\xi \text{ on } \mathbb{T}^2 \times \mathbb{R}_+$$

- 1. Earlier work by Jona Lasinio/Mitter, Albeverio/Rockner, and Mikulevicius/Rozovsky with different methods
- 2. Da-Prato/Debussche gave the first pathwise approach, dividing the problem into a probabilistic step and an analytic step.
- ► Key Idea: Split the solution into a rough peice v and a more regular peice u - v = w and re-write the equation as

$$\partial_t w = \Delta w - (w + v)^3$$
:

A Detour into Rough Paths

Return to the finite dimensional case and consider instead the (driftless) ODE with multiplicative noise

$$\dot{X} = \sigma(X)\dot{W},$$

where σ is some smooth function.

- Similar power counting issue, σ(X) ∈ C^{1/2−κ} for all κ, while W ∈ C^{-1/2−κ}, so no canonical meaning for σ(X)W.
- Classical approach of Ito is probabilistic, searches for a solution in a class of (adapted), random processes.
- Approach by Terry Lyons and further developed by Massimilliano Gubinelli is pathwise. Efficient splitting into a probabilistic step and an analytic step.

$$\dot{X} = \sigma(X) \dot{V},$$

 (Analytic Step) Define a class of "controlled rough paths" X for which there exists a σ such that

$$X_t = X_s + \sigma_s(W_t - W_s) + O(|s - t|^{1 - 2\kappa})$$

- 1. (Reconstruction) Given X controlled and a meaning for $W \diamond \dot{W}$, give a meaning to $\sigma(X) \diamond \dot{W}$.
- 2. (Integration) Given a meaning for $\sigma(X) \diamond W$ and a solution X to the ODE, show that X is controlled.
- (Probabilistic Step) Use stochastic analysis to define $W \diamond \dot{W}$.
- Better to think of the solution as a linear form acting on vectors (1, W) ∈ ℝ² via

$$t\mapsto X_t\mathbf{1}+\sigma_t\mathbf{W}.$$

d = 3 and beyond

Theorem (Hairer)

There exists a choice of constants C_{ϵ} such that the sequence of solutions to

$$\partial_t u_{\epsilon} = \Delta u_{\epsilon} + C_{\epsilon} u_{\epsilon} + \xi_{\epsilon} \quad on \quad \mathbb{T}^3 \times \mathbb{R}_+$$

converges to a limit (for small times).

- Alternative proof using Paracontrolled Calculus by Catellier/Chouk.
- Global a priori bounds derived by Mourrat and Weber (should yield an invariant measure). Alternative, direct construction of an invariant measure by Albeverio/Kusuoka.
- (Highly non-trivial) Extension to Φ₄^{4-δ} as a culmination of work by Bruned, Chandra, Chevrev, Hairer, Zambotti.

Singular SPDE Philosophy

Heightened interest in Singular SPDE:

- Regularity Structures: Hairer
- Paracontrolled Distributions: Gubinelli/Imkeller/Perkowski, Bailleul/Bernicot
- Renormalization group: Kupainen

General themes

- Models: building blocks
- Modelled Distributions: "regularity" in quotation marks
- Integration: gaining "regularity" through the PDE
- Reconstruction: using "regularity" + off-line inputs to give a meaning to the non-linearity

Quasi-linear SPDE

$$\partial_t u - A(u) \partial_x^2 u = \mathbf{f}.$$



Quasi-linear SPDE

$$\partial_t u - A(u)\partial_x^2 u = \mathbf{f}.$$

Motivation: Toy model for PDE's of a more geometric nature, intrinsic interest in PDE and probability, Feynmac-Kac representation (for regular enough f).

For notational convenience, one space dimension. For simplicity, periodic in space/time, re-label coordinates

$$\partial_2 u - A(u)\partial_1^2 u = \mathbf{f},$$

for $x = (x_1, x_2) \in [0, 1]^2$ where x_1 is for space, x_2 is for time.

A Fundamental Difficulty

$$\partial_2 u - A(u)\partial_1^2 u = \mathbf{f},$$

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A Fundamental Difficulty

$$\partial_2 u - A(u)\partial_1^2 u = \mathbf{f},$$

- 1. (Integration) For $f \in C^{\alpha-2}$, expect $u \in C^{\alpha}$.
- 2. (Reconstruction) For $A(u) \in C^{\alpha}$ and $\partial_1^2 u \in C^{\alpha-2}$, meaning of $A(u)\partial_1^2 u$?

Classical view: regularity α of A(u) must over-compensate for the irregularity $\alpha - 2$ of $\partial_1^2 u$.

- $\alpha \in (2,\infty)$: Pointwise solutions
- $\alpha \in (1,2)$: Distributional solutions $(\alpha 2 < 0, \quad \alpha + \alpha 2 > 0)$

Modern view: need an enhanced definition of regularity of u and additional off-line structure of f

► $\alpha \in (0,1)$: Active area, focus of the remainder of the talk $(\alpha + \alpha - 2 < 0)$

Related Singular SPDE Literature

Quasi-linear

1. Otto-Weber ($\alpha \in (\frac{2}{3}, 1)$, parametric model)

$$\begin{aligned} (\partial_2 - a_0 \partial_1^2) \mathbf{v}_{\alpha}(\cdot, a_0) &= \mathbf{f}. \\ u(y) - u(x) \stackrel{2\alpha}{\approx} \delta_{A(u(x))} \cdot \left(\mathbf{v}_{\alpha}(y) - \mathbf{v}_{\alpha}(x) \right) \\ [(\cdot)_{\mathcal{T}}, A(u)] \diamond \partial_1^2 u \stackrel{3\alpha-2}{\approx} A'(u) \delta_{A(u)} \cdot [(\cdot)_{\mathcal{T}}, \mathbf{v}_{\alpha}] \diamond \partial_1^2 \mathbf{v}_{\alpha} \end{aligned}$$

- 2. Furlan-Gubinelli , Bailleul-Debussche-Hofmanova ($\alpha \in (\frac{2}{3},1)$ paracontrolled approach with and without a parametric ansatz, respectively)
- 3. Gerenscer-Hairer (parametric model, regularity structures: big progress for $\alpha > 0$, one (crucial) step working only for $\alpha > \frac{1}{2}$) Transformation method
- 4. Otto-Sauer-Smith-Weber (parametric, regularity structures (with some twists); abstract tools work for $\alpha > 0$, concrete results for $\alpha > \frac{1}{2}$ posted, $\alpha > \frac{2}{5}$ also checked) Direct approach

Flexible Approach

Study (linear) parabolic PDE's with $a \in C^{\alpha}$ and $f \in C^{\alpha-2}$

$$\partial_2 u - \mathbf{a} \diamond \partial_1^2 u = \mathbf{f}$$

- ► Off-line step: Given a (small) model f, v_{α} , $v_{\alpha} \diamond \partial_1^2 v_{\alpha}$, $w_{2\alpha}$, $w_{2\alpha} \diamond \partial_1^2 v_{\alpha}$, $v_{2\alpha} \diamond \partial_1^2 w_{2\alpha}$, $w_{3\alpha}$, ...
- ► Functional framework: Modelled distributions V, linear forms acting on (abstract) functions of several parameters (a₀, a'₀,...).
- ► The solution map: Build the (non-linear) map V_a → V_u which takes a modelled distribution describing a into a modelled distribution describing u.
- ▶ Reconstruction: Given V_a and V_u , build and characterize $a \diamond \partial_1^2 u$.
- ▶ Integration: Given $a \diamond \partial_1^2 u$ and the solution u to the PDE, show that that V_u is a modelled distribution.

Non-linear problem follows via a straightforward iteration

$$V_{\widetilde{u}} \mapsto V_a \mapsto V_u, \qquad a = A(\widetilde{u}).$$

Abstract Integration Theorem (Local Splitting Method)

Let $\eta \in (1,2)$ and $(x,y) \mapsto U(x,y)$ be a bounded, continuous function (periodic in y) with the following properties:

1. For all base points x and length scales $T^{\frac{1}{4}}, R \leq 1$ it holds

$$\begin{split} \inf_{a_0 \in I} \| (\partial_2 - a_0 \partial_1^2) (\cdot)_T U(x, \cdot) \|_{B_R(x)} \\ &\leq \sum_{\beta \in \mathsf{A}} (T^{\frac{1}{4}})^{\eta - 2 - \beta} R^{\beta}. \end{split}$$

2. For all x, y, z it holds

$$ig| oldsymbol{U}(x,y) - oldsymbol{U}(x,z) - oldsymbol{U}(y,y) + oldsymbol{U}(y,z) - \gamma(x,y)(z-y)_1 ig| \ \leq \sum_{eta \in \mathsf{A}} d^{\eta-eta}(y,x) d^eta(z,y)$$

for some function $(x, y) \mapsto \gamma(x, y)$. Then there exists a continuous function ν such that for all x, y

$$\left| U(x,y) - U(x,x) - \nu(x)(y-x)_1 \right| \lesssim d^{\eta}(y,x).$$

Main (Concrete) Theorem

Given:

- α ∈ (²/₅, 1) and a (small) model consisting of C^{α−2}
 distributions v₊ ◊ v_− and C^α functions v₊.
- modelled distribution V_a of order η (large enough) describing
 a with [a]_α small

There exists a unique modelled distribution V_u of order η (describing to lowest order a function u) with the following properties.

- $V_{\partial_1^2 u}$ is algebraically determined by V_a .
- There exists a unique distribution $a \diamond \partial_1^2 u$ such that

 $\lim_{T\to 0} \|(a\diamond \partial_1^2 u)_T - a(\partial_1^2 u)_T - (\overline{V}_a \otimes V_{\partial_1^2 u})' \cdot (v_+ \diamond v_-)_T\| = 0,$

where $\overline{V}_a = V_a - a$.

► $\partial_2 u - a \diamond \partial_1^2 u = f$ in the sense of distributions.

Moreover, the map $V_a \mapsto V_u$ is bounded. For $\alpha \in (\frac{1}{2}, 1)$, also locally Lipschitz.

The Positive Model: $\alpha \in (\frac{1}{2}, \frac{2}{3})$ $v_+ := (1, v_\alpha, x_1, w_{2\alpha})$

$$\begin{aligned} (\partial_2 - a_0 \partial_1^2) \mathbf{v}_{\alpha}(\cdot, a_0) &= f \\ (\partial_2 - a_0 \partial_1^2) \mathbf{w}_{2\alpha}(\cdot, a'_0, a_0) &= (\mathbf{v}_{\alpha} \diamond \partial_1^2 \mathbf{v}_{\alpha})(\cdot, a'_0, a_0), \end{aligned}$$

where f and $v_{\alpha} \diamond \partial_1^2 v_{\alpha}(a'_0, a_0)$ in $C^{\alpha-2}$ satisfy

$$(T^{\frac{1}{4}})^{2-\alpha}\|f_{\mathcal{T}}\|\leq \mathsf{N},\quad (T^{\frac{1}{4}})^{2-2\alpha}\|(\mathsf{v}_{\alpha}\diamond\partial_{1}^{2}\mathsf{v}_{\alpha})_{\mathcal{T}}-\mathsf{v}_{\alpha}(\partial_{1}^{2}\mathsf{v}_{\alpha})_{\mathcal{T}}\|\leq \mathsf{N}^{2}.$$

Lemma

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For all x, y it holds (for some function ω)

$$\begin{aligned} |w_{2\alpha}(y, a'_{0}, a_{0}) - w_{2\alpha}(x, a'_{0}, a_{0}) \\ &- v_{\alpha}(x, a'_{0}) (\partial_{a_{0}} v_{\alpha}(y, a_{0}) - \partial_{a_{0}} v_{\alpha}(x, a_{0})) \\ &- \omega(x, a_{0}, a'_{0})(y - x)_{1} | \lesssim N^{2} d^{2\alpha}(x, y). \end{aligned}$$

$$(y) \mapsto U(x, y, a'_{0}, a_{0}) := w_{2\alpha}(y, a'_{0}, a_{0}) - v_{\alpha}(x, a'_{0}) \partial_{a_{0}} v_{\alpha}(y, a_{0}).$$

Function-like Modelled Distributions

Define a graded Banach space for placeholders $v_+ = (1, v_{\alpha}, x_1, w_{2\alpha}).$

 $\begin{aligned} \mathsf{T}_+ &= \mathsf{T}_0 \oplus \mathsf{T}_\alpha \oplus \mathsf{T}_1 \oplus \mathsf{T}_{2\alpha} \\ &:= \mathbb{R} \oplus C^2(I) \oplus \mathbb{R} \oplus C^{2,1}(I \times I), \end{aligned}$

where $C^{2,1}(I \times I) = C^{2}(I) \otimes C^{1}(I)$.

A modelled distribution V_u describing u to order η is a family of linear forms on T_+ indexed by points $x \in \mathbb{R}^2$ such that Continuity condition: For each $x, y \in \mathbb{R}^2$ and placeholder $v_+ \in T_+$

$$\begin{split} \big| (V_{\boldsymbol{u}}(\boldsymbol{y}) - V_{\boldsymbol{u}}(\boldsymbol{x})) \cdot \boldsymbol{v}_{+} \big| \\ &\leq d^{\eta}(\boldsymbol{y}, \boldsymbol{x}) |1| + d^{\eta-\alpha}(\boldsymbol{y}, \boldsymbol{x}) \| \boldsymbol{v}_{\alpha} - \boldsymbol{v}_{\alpha}(\boldsymbol{x}) 1 \|_{\mathsf{T}_{\alpha}} \\ &\quad + d^{\eta-2\alpha}(\boldsymbol{y}, \boldsymbol{x}) \| \boldsymbol{w}_{2\alpha} - \boldsymbol{w}_{2\alpha}(\boldsymbol{x}) 1 \\ &\quad - \boldsymbol{v}_{\alpha}(\boldsymbol{x}) \otimes (\partial_{\boldsymbol{a}_{0}} \boldsymbol{v}_{\alpha} - \partial_{\boldsymbol{a}_{0}} \boldsymbol{v}_{\alpha}(\boldsymbol{x}) 1) \|_{\mathsf{T}_{2\alpha}}. \end{split}$$

 $u(y) - V_u(x) \cdot v_+(y) = O(d^{\eta}(x, y))$ (by prev. Lemma).

Algebraic Lemma

Given V_a on T_+ , define $V_{\partial_1^2 u}$ on placeholders $v_- = (\partial_1^2 v_\alpha, \partial_1^2 w_{2\alpha})$ in $T_- = \partial_1^2 T_+$ by

$$V_{\partial_1^2 u} \cdot v_- = \delta_{a} \cdot \partial_1^2 v_{\alpha} + (\overline{V}'_{a} \otimes \delta_{a}) \cdot \begin{pmatrix} \partial_{a_0} \partial_1^2 v_{\alpha} \\ \partial_1^2 w_{2\alpha}, \end{pmatrix}$$

where. V'_a is the reduction of the form V_a to act only on the placeholders $(1, v_{\alpha}) \in T_0 \oplus T_{\alpha}$.

Lemma

Given a modelled distribution V_a of order η on T_+ , the above definition of $V_{\partial_1^2 u}$ yields a modelled distribution of order $\eta - 2$ on T_- .

The Negative Model: $\alpha \in (\frac{1}{2}, \frac{2}{3})$

Recall that the rough diffusion operator is characterized by

$$\lim_{T\to 0} \|(a\diamond \partial_1^2 u)_T - a(\partial_1^2 u)_T - (\overline{V}_a\otimes V_{\partial_1^2 u})' \cdot (v_+\diamond v_-)_T\| = 0.$$

Need additional distributions $w_{2\alpha} \diamond \partial_1^2 v_{\alpha}$, $v_{\alpha} \diamond \partial_1^2 w_{2\alpha}$

$$\mathbf{v}_{+} \diamond \mathbf{v}_{-} = \begin{pmatrix} \partial_{1}^{2} \mathbf{v}_{\alpha} & \mathbf{v}_{\alpha} \diamond \partial_{1}^{2} \mathbf{v}_{\alpha} & \mathbf{x}_{1} \partial_{1}^{2} \mathbf{v}_{\alpha} & \mathbf{w}_{2\alpha} \diamond \partial_{1}^{2} \mathbf{v}_{\alpha} \\ \partial_{1}^{2} \mathbf{w}_{2\alpha} & \mathbf{v}_{\alpha} \diamond \partial_{1}^{2} \mathbf{w}_{2\alpha} \end{pmatrix}$$

Level $3\alpha - 2$:

$$egin{aligned} &(\mathcal{T}^{rac{1}{4}})^{3lpha-2}\|[(\cdot)_{\mathcal{T}},w_{2lpha}]\diamond\partial_{1}^{2}v_{lpha}(a_{0}^{\prime\prime},a_{0}^{\prime},a_{0})\ &-v_{lpha}(a_{0}^{\prime\prime})\partial_{a_{0}^{\prime}}[(\cdot)_{\mathcal{T}},v_{lpha}]\diamond\partial_{1}^{2}v_{lpha}(a_{0}^{\prime},a_{0})\|\leq N^{3} \end{aligned}$$

$$\begin{aligned} (T^{\frac{1}{4}})^{3\alpha-2} \| [(\cdot)_{\mathcal{T}}, v_{\alpha}] \diamond \partial_1^2 w_{2\alpha}(a_0^{\prime\prime}, a_0^{\prime}, a_0) \\ &- v_{\alpha}(a_0^{\prime}) \partial_{a_0} [(\cdot)_{\mathcal{T}}, v_{\alpha}] \diamond \partial_1^2 v_{\alpha}(a_0^{\prime\prime}, a_0) \| \leq N^3 \end{aligned}$$

Thanks for your attention

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