Optimal experimental design that minimizes the width of simultaneous confidence bands

Satoshi Kuriki (Inst. Statist. Math., Tokyo)

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Joint with Henry Wynn (LSE, UK)

- 1. New criterion for optimal experimental design
- 2. Polynomial regression and Möbius group action
- 3. Optimization over the cross-section space
- 4. Summary and open problems

1. New criterion for optimal experimental design

Very brief introduction to Optimal Design

- ▶ The data $(x_i, y_i)_{1 \le i \le N} \in \mathcal{X} \times \mathbb{R}$ $(\mathcal{X} \subset (-\infty, \infty)$ is the domain of explanatory variable x.)
- Assume a regression model

►

$$y_i = b^{\top} f(x_i) + \varepsilon_i, \quad \varepsilon_i \sim N(0, \sigma^2(x_i)) \text{ i.i.d.}$$

$$b \in \mathbb{R}^{n \times 1} \text{ (unknown), } f(x) \in \mathbb{R}^{n \times 1} \text{ (known), } \sigma^2(x) > 0$$

(known)
The LS: $\hat{b} \sim N(b, \Sigma)$, where

$$\Sigma = M^{-1}, \quad M = \sum_{i=1}^{N} f(x_i) f(x_i)^{\top} \frac{1}{\sigma^2(x_i)} \text{ (information matrix)}$$

► "Optimal design" is to find a good {x₁,...,x_N} ∈ X^N and hence good M, e.g., that maximizes

$$\det(\operatorname{Var}(\widehat{b}))^{-1} = \det(M)$$
 (D-optimal criterion)

Simultaneous confidence bands

► 100(1 -
$$\alpha$$
)%-simultaneous confidence band:

$$P\left(b^{\top}f(x) \in \underbrace{\widehat{b}^{\top}f(x) \pm \|M^{-\frac{1}{2}}f(x)\| \cdot c_{\alpha}}_{\text{confidence band}} \text{ for all } x \in \mathcal{X}\right) = 1-\alpha$$

Example of a confidence band:

$$b^{\top}f(x) = x^2 - x + 1, \ \sigma^2(x) \equiv 1, \ x_i = 1, 0, -1, \ \mathcal{X} = [-1, 1]$$



- Blue : Estimated curves (20 times)
- Red : 90% Confidence band (Naiman's volume-of-tube method)
- Black : Conservative 90% confidence band (Scheffè)

Volume-of-tube method (to determine c_{α})

The trajectory of the normalized regression basis vector

$$\Gamma = \left\{ \pm \frac{M^{-\frac{1}{2}} f(x)}{\|M^{-\frac{1}{2}} f(x)\|} \mid x \in \mathcal{X} \right\} \subset \mathbb{S}^{n-1} \text{ (unit sphere in } \mathbb{R}^n)$$
 Let

 ${
m Vol}_1(\Gamma)\,:\, {
m 1-dim}$ volume (length) of Γ $\chi(\Gamma)\,:\, {
m the}$ number of connected components of Γ

Proposition 1 (Naiman's (1986) volume-of-tube method)

$$P\left(b^{\top}f(x)\in\widehat{b}^{\top}f(x)\pm\|M^{-\frac{1}{2}}f(x)\|\cdot c \text{ for all } x\in\mathcal{X}\right)$$

$$\gtrsim 1-\frac{\mathrm{Vol}_{1}(\Gamma)}{2\pi}P\left(\chi_{2}^{2}>c^{2}\right)-\frac{\chi(\Gamma)}{2}P\left(\chi_{1}^{2}>c^{2}\right)$$
(1)

("≥" holds for all c ≥ 0, "≈" holds when c is large)
By equating the RHS (1) to 1 - α, c = c_α is obtained.

Volume criterion — New optimal design criterion

Naiman's formula (redisplay)

$$\begin{split} P\Big(b^{\top}f(x)\in\widehat{b}^{\top}f(x)\pm\underbrace{\|M^{-\frac{1}{2}}f(x)\|\cdot c_{\alpha}}_{\text{band width}} \quad \text{for all } x\in\mathcal{X}\Big)\\ &\underset{\approx}{\gtrsim}1-\frac{\text{Vol}_{1}(\Gamma)}{2\pi}P\big(\chi_{2}^{2}>c_{\alpha}^{2}\big)-\frac{\chi(\Gamma)}{2}P\big(\chi_{1}^{2}>c_{\alpha}^{2}\big) \ (=1-\alpha) \end{split}$$

- Propose a new criterion of optimal experimental design so that the width of confidence band is minimal. That is, the design minimizes ||M^{-1/2} f(x)|| and Vol₁(Γ)
- ► The design that minimizes max_{x∈X} ||M^{-1/2} f(x)|| is known to be the D-optimal design (Kiefer-Wolfowitz's equivalence theorem).
- We propose the optimal design that minimizes $Vol_1(\Gamma)$.

Problem is not convex!

 From now on, consider a polynomial regression (cf. Dette, et al., 1999)

$$f(x) = (1, x, \dots, x^{n-1})^{\top}$$

• For example, $length(M) := Vol_1(M)$ for

$$M = (1 - \alpha) \frac{1}{8} \begin{pmatrix} 3 & 0 & 1\\ 0 & 1 & 0\\ 1 & 0 & 3 \end{pmatrix} + \alpha \frac{1}{72} \begin{pmatrix} 15 + 4\sqrt{3} & 0 & 1\\ 0 & 1 & 0\\ 1 & 0 & 7 - 4\sqrt{3} \end{pmatrix}$$



The problem is not convex.

2. Polynomial regression and Möbius group action

Volume criterion — New optimal design criterion (contd)

• The length of the curve Γ is

$$\begin{aligned} \operatorname{length}(M) &:= \operatorname{Vol}_{1}(\Gamma) = \int_{\mathcal{X}} \left\| \frac{d}{dx} \left(\frac{M^{-\frac{1}{2}} f(x)}{\|M^{-\frac{1}{2}} f(x)\|} \right) \right\| dx \\ &= \int_{\mathcal{X}} \frac{\sqrt{f^{\top} M^{-1} f \cdot g^{\top} M^{-1} g - (fM^{-1}g)^{2}}}{f^{\top} M^{-1} f} dx \end{aligned}$$

where $f(x) = (1, \dots, x^{n-1})^{\top}$, $g(x) = \frac{d}{dx}f(x)$ Droblem: Minimize

Problem: Minimize

 $\operatorname{length}(M)$

subject to $M \in \mathcal{M}$, where

$$\mathcal{M} = \left\{ M = \int_{\mathcal{X}} f(x) f(x)^{\top} dP(x) \mid P : \text{ positive measure} \right\}$$

(moment cone)

- ▶ Note: Instead of $\{x_i\}_{1 \le i \le N}$, we use the design measure P.
- ▶ length(M) is homogeneous in M, \mathcal{M} can be a cone.

Volume optimal design (polynomial regression)

► The moment cone *M* is equivalent to the set of positive definite Hankel matrices (Karlin and Studden, 1966)

$$M \in \mathcal{M} = \left\{ \begin{pmatrix} m_0 & m_1 & m_{n-1} \\ m_1 & \ddots & \\ & \ddots & & \\ & & \ddots & & \\ m_{n-1} & & m_{2n-3} & m_{2n-2} \end{pmatrix}_{n \times n} \succ 0 \right\}$$

• Objective function length(M) is an elliptic integral

Möbius group action

• Let
$$\overline{\mathbb{R}} = \mathbb{R} \cup \{\pm \infty\}$$
. The map $\varphi : \overline{\mathbb{R}} \to \overline{\mathbb{R}}$:
 $x \mapsto \varphi(x) = \varphi(x; a, b, c, d) = \frac{ax + b}{cx + d} \quad (ad - bc \neq 0)$

the (real) Möbius transform

►
$$f(x) = (1, x, \dots, x^{n-1})^{\top}$$

Define a matrix $A = A(a, b, c, d)$ by

$$f(\varphi(x)) = Af(x)\frac{1}{(cx+d)^{n-1}}$$

e.g., when n=3,

$$\underbrace{\begin{pmatrix}1\\\frac{ax+b}{cx+d}\\(\frac{ax+b}{cx+d})^2\end{pmatrix}}_{f(\varphi(x))} = \underbrace{\begin{pmatrix}d^2 & 2cd & c^2\\bd & bc+ad & ac\\b^2 & 2ab & a^2\end{pmatrix}}_{A} \underbrace{\begin{pmatrix}1\\x\\x^2\end{pmatrix}}_{f(x)} \frac{1}{(cx+d)^2}$$

▶ $\mathcal{A} = \{A \mid ad - bc \neq 0\}$ forms a group (a representation of GL(2))

Möbius group action (contd)

Lemma 1

If M is Hankel, then AMA^{\top} $(A \in \mathcal{A})$ is Hankel. That is, the group \mathcal{A} acts onto \mathcal{M} .

We can define a equivalence relation:

 $M_1 \sim M_2 \quad \Leftrightarrow \quad M_2 = A M_1 A^\top, \; \exists A \in \mathcal{A}$

 $(M_1 \text{ and } M_2 \text{ are on the same orbit})$

Theorem 1

The group \mathcal{A} remains the length length(M) invariant, i.e.,

 $\operatorname{length}(M_1) = \operatorname{length}(M_2)$ if $M_1 \sim M_2$

We can reduce the dimension of the optimization problem.

3. Optimization over the cross-section space

Orbital decomposition

From now on, we restricted our attention to the case n = 3.

Theorem 2

The moment cone \mathcal{M} (= set of positive definite Hankel matrices) has an orbital decomposition

$$\mathcal{M} = \bigsqcup_{v \in (0, \frac{1}{3}]} \{ M \mid M \sim M_v \}$$

where

$$M_v = \begin{pmatrix} 1 & 0 & v \\ 0 & v & 0 \\ v & 0 & 1 \end{pmatrix} \in \mathcal{M}$$

Orbital decomposition (contd)

Proof of Theorem 2.

We can show that for any $M \in \mathcal{M}$,

$$M \stackrel{(i)}{\sim} \begin{pmatrix} u_1 & 1 & 1\\ 1 & 1 & 1\\ 1 & 1 & w_1 \end{pmatrix} \stackrel{(ii)}{\sim} \begin{pmatrix} u_2 & 0 & v_2\\ 0 & v_2 & 0\\ v_2 & 0 & w_2 \end{pmatrix} \stackrel{(iii)}{\sim} \begin{pmatrix} 1 & 0 & v_3\\ 0 & v_3 & 0\\ v_3 & 0 & 1 \end{pmatrix} = M_{v_3}$$

(i) and (iii) are easy. For (ii), we need to find ${\cal A}={\cal A}(a,b,c,d)$ such that

$$A\begin{pmatrix} u_1 & 1 & 1\\ 1 & 1 & 1\\ 1 & 1 & w_1 \end{pmatrix} A^{\top} = \begin{pmatrix} u_2 & 0 & v_2\\ 0 & v_2 & 0\\ v_2 & 0 & w_2 \end{pmatrix}$$

by solving algebraic equations with checking resultants so that $ad - bc \neq 0$. (algebraic statistics here?)

Optimization on the cross-section space

• The volume (length) of Γ at M_v is

$$length(M_v) = \int_{-\infty}^{\infty} s(x; v) dx$$

where

$$s(x;v) = \frac{\sqrt{\frac{1-v^2}{v}}\sqrt{1+6vx^2+x^4}}{1+(\frac{1}{v}-3v)x^2+x^4}$$

(still elliptic integral...)

Theorem 3

Over $v \in (0, 1/3]$, the minimum of $length(M_v)$ is attained if and only if v = 1/3, i.e.,

$$M=M_{1/3}=\begin{pmatrix} 1 & 0 & \frac{1}{3}\\ 0 & \frac{1}{3} & 0\\ \frac{1}{3} & 0 & 1 \end{pmatrix}$$
 The minimum is $2\pi\sqrt{\frac{2}{3}}.$

Optimization on the cross-section space (contd)

Proof of Theorem 3. Using $1/\sqrt{1+z} \ge 1-z/2$, construct a lower bound:

$$s(x;v) \ge \underline{s}(x;v) = \frac{\sqrt{\frac{1-v^2}{v}}(1+6vx^2+x^4)}{(1+(\frac{1}{v}-3v)x^2+x^4)(1+x^2)} \left(1+\frac{(1-3v)x^2}{(1+x^2)^2}\right)$$

(equality iff v = 1/3) $\underline{s}(x; v)$ is a rational function and the integral can be evaluated by residues.

Fortunately,

$$\min_{v\in(0,1/3]}\int_{-\infty}^\infty \underline{s}(x;v)dx \quad \text{attains at } v=1/3$$

and

$$\int_{-\infty}^{\infty} s(x;v) dx = \int_{-\infty}^{\infty} \underline{s}(x;v) dx \quad \text{at } v = 1/3$$

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Optimization on the cross-section space (contd)



Objective function and its (integrable) lower bound

$$\operatorname{length}(M_v) = \int_{-\infty}^{\infty} s(x; v) dx \ge \int_{-\infty}^{\infty} \underline{s}(x; v) dx$$

4. Summary and open problems

Optimal design in the polynomial regression (n = 3)

Theorem 4 (polynomial regression) *M* is volume-mimimum optimal design iff

$$M = AM_{1/3}A^{\top}, \quad \exists A \in \mathcal{A}, \quad M_{1/3} = \begin{pmatrix} 1 & 0 & \frac{1}{3} \\ 0 & \frac{1}{3} & 0 \\ \frac{1}{3} & 0 & 1 \end{pmatrix}$$

Concretely

$$M = k \begin{pmatrix} 1 & r & \frac{q^2}{3} + r^2 \\ r & \frac{q^2}{3} + r^2 & r(q^2 + r^2) \\ \frac{q^2}{3} + r^2 & r(q^2 + r^2) & (q^2 + r^2)^2 \end{pmatrix}, \quad q \neq 0, \quad k > 0$$

Proof.

 $A \in \mathcal{A}$ has a decomposition

$$A(a, b, c, d) = k \underbrace{A(q, r, 0, 1)}_{\text{affine}} \underbrace{A(\pm s, \mp t, t, s)}_{O(2) \text{ (isotropy group)}}, \quad \begin{cases} s = \cos\theta\\ t = \sin\theta \end{cases}$$

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Optimal design in the polynomial regression (n = 3) (contd)

Remark 1 It is known that

$$M_{1/3} = \begin{pmatrix} 1 & 0 & \frac{1}{3} \\ 0 & \frac{1}{3} & 0 \\ \frac{1}{3} & 0 & 1 \end{pmatrix}$$

is the D-optimal information matrix.

$$\begin{cases} Whole \ designs \end{cases} (4-dim) \\ \supseteq \left\{ Minimum-volume \ optimal \ designs \right\} (2-dim) \\ \supseteq \left\{ D\text{-optimal } design \right\} (0-dim) \end{cases}$$

The D-optimal design is a universal optimal design that optimizes both D-criterion and volume criterion (hence, minimizes the width of simultaneous confidence bands).

Optimization in the polynomial regression (n = 3) (contd)

Remark 2

The minimum-volume design $M \in \mathcal{M}$ is attained iff the curve

$$\Gamma_{+} = \left\{ M^{-\frac{1}{2}} f(x) / \| M^{-\frac{1}{2}} f(x) \| \mid x \in \mathcal{X} \right\}$$

forms a circle.



Future topic: Multivariate extension

$$x = (x_i)_{1 \le i \le p}^{\top}$$

$$f(x) = (1, (x_i)_{1 \le i \le p}, (x_i x_j)_{1 \le i \le j \le p}, \dots, (x_{i_1} \cdots x_{i_d})_{1 \le i_1 \le \dots \le i_d})^{\top}$$

$$\in \mathbb{R}[x]^{\binom{p+d}{d}}$$

• Möbius transform $\overline{\mathbb{R}}^p \to \overline{\mathbb{R}}^p$

$$\varphi(x; A, b, c, d) = \frac{Ax + b}{c^{\top}x + d}, \quad A \in \mathbb{R}^{p \times p}, \quad b, \, c \in \mathbb{R}^{p \times 1}, \quad d \in \mathbb{R}$$

"Volume preserving property" holds:

$$\operatorname{Vol}(M) = \operatorname{Vol}(AMA^{\top}), \ A \in \mathcal{A}, \ M \in \mathcal{M}$$

Moment cone:

$$\mathcal{M} = \left\{ \int_{\mathcal{X} \subset \mathbb{R}^{\binom{p+d}{d}}} f(x) f(x)^\top dP(x) \mid P : \text{ positive measure} \right\} = ?$$

Summary

- We proposed a new optimal design criterion volume criterion.
- ► For the polynomial regression problems, the Möbius group acts on the moment cone *M*, and keeps our problem invariant.
- When n = 3, by the optimization over cross-section space, we found the Möbius group orbit passing through the D-optimal design are minimum-volume optimal.

(We conjecture that this is true for arbitrary n.)

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