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Continuous Cluster Categories

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Motivation: Continuous cluster categories of type \mathbf{A} are uncountably infinite categories with cluster structures, where the clusters correspond to ideal geodesic triangulations of the hyperbolic plane in one case, or clusters of the cluster categories of type \mathbf{A}_n in the other case. (The hyperbolic plane is the universal cover of once punctured surfaces.)

We define $\mathcal{A}_{\mathbb{R}}$ to be the category of k -representations of the real line \mathbb{R} , where k is a field. For each $a < b \in \mathbb{R}$ we denote by $V_{(a,b]}$ the special representation: $V_{(a,b]}(x) = k, \forall x \in (a, b]$ and $V_{(a,b]}(y) \rightarrow V_{(a,b]}(x)$ is 1_k for all $a < x < y \leq b$. We also define the full subcategory $\mathcal{B} \subset \mathcal{A}_{\mathbb{R}}$ to be additively generated by the indecomposable objects $\{V_{(a,b]} \mid a < 0 < b\}$.

A particularly nice correspondence between indecomposable objects of \mathcal{B} and points in \mathbb{R}^2 is obtained by:

$$V_{(a,b]} \leftrightarrow M(x, y) \text{ where } (x, y) = (-\ln(-a), \ln(b)),$$

and we will use this correspondence to identify the k -representations of \mathbb{R} with points in the plane \mathbb{R}^2 .

For a positive real number $c \in \mathbb{R}$, we define the full subcategory $\mathcal{B}_{\geq c} \subset \mathcal{B}$ by defining the indecomposable objects of $(\mathcal{B}_{\geq c})$ as $\{M(x, y) \in \mathcal{B} \mid |x - y| \geq c\}$. The continuous derived category \mathcal{D}_c is defined using “two way $\mathcal{B}_{\geq c}$ -approximations” in \mathcal{B} and defining triangulated structure on $\mathcal{D}_c := \mathcal{B}/\mathcal{B}_{\geq c}$.

For each positive real number $d \in \mathbb{R}$ we define functor $F_d : \mathcal{D}_c \rightarrow \mathcal{D}_c$ by $F_d(M(x, y)) = M(y + d, x + d)$ which can be used to define a triangulated automorphism of the doubled derived category $\mathcal{D}_c^{(2)}$. Using the functor F_d the orbit category of $\mathcal{D}_c^{(2)}$ is defined and denoted by $\mathcal{C}_{(c,d)} := \mathcal{D}_c^{(2)}/F_d$. With these definitions we have the following results.

Theorem: The orbit category $\mathcal{C}_{(c,d)}$ is triangulated if $c \leq d$.

Theorem: The orbit category $\mathcal{C}_{(c,d)}$ has a cluster structure if and only if either $c = d$ or $c = \frac{n+1}{n+3}d$ for some positive integer n .

Relation between continuous cluster category and ideal triangulation of hyperbolic plane by geodesics is obtained in the case $c = d = \pi$. To each representation $M(x, y) \in \mathcal{C}_{(\pi,\pi)}$ we associate geodesic starting at angle x and ending at $y + \pi$. With this correspondence, each cluster in the continuous cluster category $\mathcal{C}_{(\pi,\pi)}$ corresponds to an ideal triangulation of the hyperbolic plane.

Objects of $\mathcal{C}_{(c,\pi)}$ can also be viewed as representations of the circle S^1 .