Existence of defects in the Swift-Hohenberg equation

Mariana Haragus & Arnd Scheel

Existence of defects in the Swift-Hohenberg equation

Defects



• dislocations

• grain boundaries

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disclinations

[Ercolani, Indik, Newell, Passot, 2000]

Swift-Hohenberg equation

• Swift-Hohenberg equation

$$u_t = -(\Delta + 1)^2 u + \mu u - u^3$$

• grain boundaries



• anisotropic Swift-Hohenberg equation

$$u_t = -(\Delta + 1)^2 u + \mu u - u^3 + \beta u_{\mathsf{x}\mathsf{x}}$$

dislocations

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Spatial dynamics

dynamical system

$$\frac{\mathrm{d}\mathbf{U}}{\mathrm{d}\mathbf{x}} = \mathcal{F}(\mathbf{U}; \mu, k, c, \beta)$$

dislocation/grain boundary \longleftrightarrow heteroclinic orbit

- bifurcation problem : bifurcation points
- center manifold reduction : reduced system
- reduced system :
 - leading order system : existence of heteroclinic orbits
 - full system : persistence of heteroclinic orbits

Spatial dynamics Bifurcation problem Reduced system

Swift-Hohenberg equation

• anisotropic Swift-Hohenberg equation

$$u_t = -(\Delta + 1)^2 u + \mu u - u^3 + \beta u_{xx}$$

• dislocations

• two-dimensional traveling waves

$$cu_{x} = -(\Delta+1)^{2}u + \mu u - u^{3} + \beta u_{xx}$$

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Spatial dynamics Bifurcation problem Reduced system

Spatial dynamics



• limits at $x = \pm \infty$: rolls

(y-periodic solutions, x-independent)

solutions connecting two rolls

Spatial dynamics Bifurcation problem Reduced system

Spatial dynamics



• limits at $x = \pm \infty$: rolls

(y-periodic solutions, x-independent)

- solutions connecting two rolls
- dynamical system

$$\frac{d\mathbf{U}}{d\mathbf{x}} = \mathcal{F}(\mathbf{U}; \mu, k, c, \boldsymbol{\beta})$$

- rolls \longleftrightarrow equilibria
- dislocations \longleftrightarrow heteroclinic orbits

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Dynamical system

• Swift-Hohenberg equation

$$cu_{x} = -(\partial_{xx} + k^{2}\partial_{yy} + 1)^{2}u + \mu u - u^{3} + \beta u_{xx}$$

• Ansatz :
$$\mathbf{U} = (u, u_1, v, v_1)$$

• dynamical system

$$\frac{d\mathbf{U}}{d\mathbf{x}} = \mathcal{A}(\mu, k, c, \beta)\mathbf{U} + \mathcal{F}(\mathbf{U})$$
$$\mathcal{A}(\mu, k, c, \beta) = \begin{pmatrix} 0 & 1 & 0 & 0\\ -(1+k^2\partial_y^2) & 0 & 1 & 0\\ 0 & 0 & 0 & 1\\ -\beta(1+k^2\partial_y^2) + \mu & c & -(1+k^2\partial_y^2) + \beta & 0 \end{pmatrix}, \quad \mathcal{F}(\mathbf{U}) = \begin{pmatrix} 0\\ 0\\ 0\\ -u^3 \end{pmatrix}$$

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Dynamical system

• dynamical system

$$\frac{d\mathbf{U}}{d\mathbf{x}} = \mathcal{A}(\mu, k, c, \beta)\mathbf{U} + \mathcal{F}(\mathbf{U})$$
$$\mathcal{A}(\mu, k, c, \beta) = \begin{pmatrix} 0 & 1 & 0 & 0\\ -(1+k^2\partial_y^2) & 0 & 1 & 0\\ 0 & 0 & 0 & 1\\ -\beta(1+k^2\partial_y^2) + \mu & c & -(1+k^2\partial_y^2) + \beta & 0 \end{pmatrix}, \quad \mathcal{F}(\mathbf{U}) = \begin{pmatrix} 0 \\ 0 \\ 0 \\ -u^3 \end{pmatrix}$$

o phase space

 $\mathcal{X}=H^3_{
m per}(0,2\pi) imes H^2_{
m per}(0,2\pi) imes H^1_{
m per}(0,2\pi) imes L^2(0,2\pi)$

• $\mathcal{A}(\mu, k, c, \beta)$ closed linear operator; domain

$$\mathcal{Y}=\mathcal{H}^4_{ ext{per}}(0,2\pi) imes\mathcal{H}^3_{ ext{per}}(0,2\pi) imes\mathcal{H}^2_{ ext{per}}(0,2\pi) imes\mathcal{H}^1_{ ext{per}}(0,2\pi)$$

•
$$\mathcal{F}:\mathcal{Y} \rightarrow \mathcal{Y}$$
 smooth

Defects Spatial dynamics Dislocations Bifurcation problem Grain boundaries Reduced system

Parameters

• dynamical system

$$rac{\mathrm{d} \mathbf{U}}{\mathrm{d} \mathbf{x}} = \mathcal{A}(\mu, k, c, eta) \mathbf{U} + \mathcal{F}(\mathbf{U})$$

- parameters : equation : μ , β
 - *y-periodic solutions :* wavenumber *k*
 - traveling waves : speed c
- choice of parameters : *co-existence of rolls with different wavenumbers*
- dispersion relation

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Dispersion relation

• dispersion relation : solutions of the form $\mathbf{U} = e^{\nu x} e^{i\ell y} \mathbf{u}$

$$(
u^2+1-k^2\ell^2)^2=\mu+eta
u^2-c
u\,,\quad\ell\in\mathbb{Z}$$

• co-existence of rolls with wavenumbers $\ell_- \neq \ell_+$ if

$$u = 0, \quad \mu = (1 - k^2 \ell_{\pm}^2)^2$$

• choice of parameters :

•
$$|\ell_{-} - \ell_{+}| = 1$$
: $\ell_{-} = \ell_{*}, \ \ell_{+} = \ell_{*} + 1$, $\ell_{*} \in \mathbb{N}$
• $\mu = (1 - k^{2}\ell_{*}^{2})^{2}, \ \mu = (1 - k^{2}(\ell_{*} + 1)^{2})^{2}$
 $k_{*}^{2} = \frac{2}{2\ell_{*}^{2} + 2\ell_{*} + 1}, \ \sqrt{\mu_{*}} = \frac{2\ell_{*} + 1}{2\ell_{*}^{2} + 2\ell_{*} + 1}$
• $\beta > 0, \ c = 0$

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Spatial dynamics Bifurcation problem Reduced system

Bifurcation problem

• dynamical system

$$rac{\mathrm{d} \mathsf{U}}{\mathrm{d} \mathsf{x}} = \mathcal{A}(\mu, k, c, eta) \mathsf{U} + \mathcal{F}(\mathsf{U})$$

parameters

- $\beta > 0$, $k = k_* > 0$ fixed parameters
- $c \sim 0$, $\mu \sim \mu_*$ bifurcation parameters

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Spatial dynamics Bifurcation problem Reduced system

Bifurcation problem

• dynamical system

$$rac{\mathrm{d} \mathsf{U}}{\mathrm{d} \mathsf{x}} = \mathcal{A}(\mu, k, c, eta) \mathsf{U} + \mathcal{F}(\mathsf{U})$$

parameters

• $\beta > 0$, $k = k_* > 0$ fixed parameters

• $c \sim$ 0, $\mu \sim \mu_{*}$ bifurcation parameters

• dynamical system : $\mu = \mu_* + \bar{\mu}$

$$rac{d\mathsf{U}}{d\mathsf{x}} = \mathcal{A}_*\mathsf{U} + \mathcal{B}(ar{\mu}, c)\mathsf{U} + \mathcal{F}(\mathsf{U})$$

 $\mathcal{A}_* = \mathcal{A}(\mu_*, k_*, \mathbf{0}, \beta), \quad \mathcal{B}(\bar{\mu}, c) = \mathcal{A}(\mu_* + \bar{\mu}, k_*, c, \beta) - \mathcal{A}(\mu_*, k_*, \mathbf{0}, \beta).$

• μ_* small parameter

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Linear operator

• dynamical system

$$rac{\mathrm{d} \mathsf{U}}{\mathrm{d} \mathsf{x}} = \mathcal{A}_* \mathsf{U} + \mathcal{B}(ar{\mu}, c) \mathsf{U} + \mathcal{F}(\mathsf{U})$$

• spectrum of \mathcal{A}_*



 $(\beta = 0 : 4\ell_* \text{ additional eigenvalues!})$

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Center manifold

small bounded solutions

$$\mathbf{U}(x) = U_c(x) + \mathbf{\Psi}_c(U_c(x); \bar{\mu}, c), \quad U_c(x) \in \mathcal{X}_c$$

- X_c spectral subspace associated with the purely imaginary eigenvalues (dimension 8)
- reduced system

$$\frac{\mathrm{d}U_c}{\mathrm{d}\,\mathbf{x}} = \mathcal{A}_* U_c + \mathbf{P}_c \Big(\mathcal{B}(\bar{\mu}, c) (U_c + \Psi_c(U_c; \bar{\mu}, c)) + \mathcal{F}(U_c + \Psi_c(U_c; \bar{\mu}, c)) \Big)$$

- \mathbf{P}_c spectral projector on \mathcal{X}_c
- ODE; dimension 8

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Reduced system

reduced system

$$\frac{\mathrm{d}U_c}{\mathrm{d}\mathbf{x}} = \mathcal{A}_*U_c + \mathbf{P}_c\Big(\mathcal{B}(\bar{\mu}, c)(U_c + \Psi_c(U_c; \bar{\mu}, c)) + \mathcal{F}(U_c + \Psi_c(U_c; \bar{\mu}, c))\Big)$$

first difficulties

- dimension 8 (too large)
 - even solutions in y -
- μ_* small parameter
 - appropriate scaling -

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Defects	Spatial dynamics
Dislocations	
Grain boundaries	Reduced system

Ansatz

• small bounded solutions

$$\mathbf{U}(x) = U_c(x) + \mathbf{\Psi}_c(U_c(x); \bar{\mu}, c), \quad U_c(x) \in \mathcal{X}_c$$

• base of
$$\mathcal{X}_c$$

$$E_{\pm \ell_*} = \begin{pmatrix} e^{\pm i\ell_* y} \\ 0 \\ \sqrt{\mu_*} e^{\pm i\ell_* y} \\ 0 \end{pmatrix}, \ E_{\pm (\ell_* + 1)} = \begin{pmatrix} e^{\pm i(\ell_* + 1)y} \\ 0 \\ -\sqrt{\mu_*} e^{\pm i(\ell_* + 1)y} \\ 0 \end{pmatrix}, \ F_{\pm \ell_*} = \begin{pmatrix} 0 \\ e^{\pm i\ell_* y} \\ 0 \\ \sqrt{\mu_*} e^{\pm i\ell_* y} \end{pmatrix}, \ F_{\pm (\ell_* + 1)} = \begin{pmatrix} 0 \\ e^{\pm i(\ell_* + 1)y} \\ 0 \\ -\sqrt{\mu_*} e^{\pm i(\ell_* + 1)y} \end{pmatrix}$$

• even solutions $U_{c}(x,y) = a_{0}(x)(E_{+\ell_{*}}(y) + E_{-\ell_{*}}(y)) + b_{0}(x)(E_{+(\ell_{*}+1)}(y) + E_{-(\ell_{*}+1)}(y)) + a_{1}(x)(F_{+\ell_{*}}(y) + F_{-\ell_{*}}(y)) + b_{1}(x)(F_{+(\ell_{*}+1)}(y) + F_{-(\ell_{*}+1)}(y))$

• scaling

$$ar{\mu}=\mu_*^3\widetilde{ar{\mu}},\quad m{c}=\mu_*^{3/2}\widetilde{m{c}},\quad m{a}_j=\mu_*^{3/2}\widetilde{m{a}}_j,\quad m{b}_j=\mu_*^{3/2}\widetilde{m{b}}_j,\quad m{j}=0,1$$

Existence of defects in the Swift-Hohenberg equation

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Dislocations Reduced system

Reduced system

• reduced system

$$\begin{aligned} a'_{0} &= a_{1} \\ a'_{1} &= -\frac{1}{\beta} \left(\mu_{*}^{3} \bar{\mu} a_{0} + \mu_{*}^{3/2} c a_{1} - 3 \mu_{*}^{3} a_{0} (a_{0}^{2} + 2 b_{0}^{2}) \right) + \cdots \\ b'_{0} &= b_{1} \\ b'_{1} &= -\frac{1}{\beta} \left(\mu_{*}^{3} \bar{\mu} b_{0} + \mu_{*}^{3/2} c b_{1} - 3 \mu_{*}^{3} b_{0} (2 a_{0}^{2} + b_{0}^{2}) \right) + \cdots \end{aligned}$$

• second scaling

$$X = \frac{1}{\sqrt{\beta}} \, \mu_*^{3/2} \sqrt{\bar{\mu}} \, x, \quad c = \sqrt{\bar{\mu}} \, \bar{c}, \quad a_0 = \frac{1}{\sqrt{3}} \, \sqrt{\bar{\mu}} \, A_0, \quad b_0 = \frac{1}{\sqrt{3}} \, \sqrt{\bar{\mu}} \, B_0$$

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Reduced system

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• new system

$$A_0'' = -A_0 - \bar{c}A_0' + A_0(A_0^2 + 2B_0^2) + \mathcal{O}(\mu_*^{1/2})$$

$$B_0'' = -B_0 - \bar{c}B_0' + B_0(2A_0^2 + B_0^2) + \mathcal{O}(\mu_*^{1/2})$$

leading order system : $\bar{c} = \mu_* = 0$

$$A_0'' = -A_0 + A_0(A_0^2 + 2B_0^2)$$

$$B_0'' = -B_0 + B_0(2A_0^2 + B_0^2)$$

rich dynamics (9 equilibria, several heteroclinic orbits, ...)
first integral

$$H(A_0, B_0, A_0', B_0') = (A_0')^2 + (B_0')^2 - \frac{1}{2} \left(A_0^2 + B_0^2 - 1\right)^2 - A_0^2 B_0^2$$

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Spatial dynamics Bifurcation problem Reduced system

Rolls and dislocations

• rolls

• equilibria (1,0), (0,1), (-1,0), (0,-1)

dislocations

- heteroclinic orbit $(A_0^{\star}, B_0^{\star})$ connecting (1, 0) and (0, 1)
- existence of this heteroclinic orbit :

[van den Berg & van der Vorst, 1997]

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Persistence of the heteroclinic orbit

• solve $\mathcal{T}(A_0, B_0, \bar{c}, \bar{\mu}, \mu_*) = 0$

$$\mathcal{T}(A_0, B_0, \bar{c}, \bar{\mu}, \mu_*) = \begin{pmatrix} A_0'' + A_0 - A_0(A_0^2 + 2B_0^2) + \bar{c}A_0' - \mathcal{R}_A^*(A_0, A_0', B_0, B_0', \bar{\mu}, \bar{c}; \mu_*) \\ B_0'' + B_0 - B_0(2A_0^2 + B_0^2) + \bar{c}B_0' - \mathcal{R}_B^*(A_0, A_0', B_0, B_0', \bar{\mu}, \bar{c}; \mu_*) \end{pmatrix}.$$

- *particular solution* : ($A_0^{\star}, B_0^{\star}, 0, 0, 0$)
- $D_{(A_0,B_0)}\mathcal{T}(A_0^{\star},B_0^{\star},0,0,0) = \mathcal{L}_{\star}, \quad \partial_{\bar{c}}\mathcal{T}(A_0^{\star},B_0^{\star},0,0,0) = (A_0^{\star}{}',B_0^{\star}{}')$

Iinear operator

$$\mathcal{L}_{\star} = egin{pmatrix} \partial_{xx} + 1 - 3A_0^{\star 2} - 2B_0^{\star 2} & -4A_0^{\star}B_0^{\star} \ -4A_0^{\star}B_0^{\star} & \partial_{xx} + 1 - 2A_0^{\star 2} - 3B_0^{\star 2} \end{pmatrix}$$

- Fredholm operator with index 0
- 0 simple eigenvalue; eigenvector $(A_0^{\star \prime}, B_0^{\star \prime})$

implicit function theorem

• solution
$$(A_0, B_0) = (A_0, B_0)(\bar{\mu}, \mu_*), \ \bar{c} = \bar{c}(\bar{\mu}, \mu_*)$$

Defects Grain boundaries

Swift-Hohenberg equation

• Swift-Hohenberg equation

$$u_t = -(\Delta + 1)^2 u + \mu u - u^3$$

• grain boundaries



• two-dimensional steady waves

$$0=-(\Delta+1)^2u+\mu u-u^3$$

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Spatial dynamics Reduced system

Spatial dynamics

• grain boundaries



• solutions connecting two rolls with different orientations

• dynamical system

$$\frac{\mathsf{dU}}{\mathsf{dx}} = \mathcal{F}(\mathsf{U}; \mu, k_*)$$

• rolls \longleftrightarrow equilibria

• grain boundaries \longleftrightarrow heteroclinic orbit

Existence of defects in the Swift-Hohenberg equation

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Spatial dynamics Reduced system

Bifurcation problem

• dynamical system

$$\frac{\mathrm{d}\mathbf{U}}{\mathrm{d}\mathbf{x}} = \mathcal{F}(\mathbf{U}; \mu, k_*)$$

• parameters (co-existence of rolls with different orientations)

- $\frac{1}{2} < k_* < 1$ fixed parameter
- $\mu \sim 0$ bifurcation parameter
- center manifold reduction
 - spectrum of $\mathcal{A}_* = D_{\mathbf{U}}\mathcal{F}(0; \mathbf{0}, k_*)$
 - reduced system

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Spatial dynamics Reduced system

Reduced system

- spectrum of $\sigma_c(A_*) = \{\pm i, \pm ik_x\};$ 4 eigenvalues
 - $\pm i$ geometric mult. 1, algebraic mult. 2
 - $\pm ik_x$ geometric mult. 2, algebraic mult. 4
- reduced system : ODE in \mathbb{R}^{12}

$$\begin{array}{rcl} A_0' &=& \mathrm{i}A_0 + B_0 - \frac{\mathrm{i}}{4} \left(\mu a_0 - a_0(a_0^2 + 6a_+\overline{a_+})\right) \\ B_0' &=& \mathrm{i}B_0 - \frac{1}{4} \left(\mu a_0 - a_0(a_0^2 + 6a_+\overline{a_+})\right) \\ A_+' &=& \mathrm{i}k_x A_+ + B_+ - \frac{\mathrm{i}}{4k_x^3} \left(\mu a_+ - 3a_+(a_0^2 + a_+\overline{a_+})\right) \\ B_+' &=& \mathrm{i}k_x B_+ - \frac{1}{4k_x^2} \left(\mu a_+ - 3a_+(a_0^2 + a_+\overline{a_+})\right) \\ A_-' &=& \mathrm{i}k_x A_- + B_- - \frac{\mathrm{i}}{4k_x^3} \left(\mu \overline{a_+} - 3\overline{a_+}(a_0^2 + a_+\overline{a_+})\right) \\ B_-' &=& \mathrm{i}k_x B_- - \frac{1}{4k_x^2} \left(\mu \overline{a_+} - 3\overline{a_+}(a_0^2 + a_+\overline{a_+})\right) \\ a_0 &= A_0 + \overline{A_0}, \ b_0 &= B_0 + \overline{B_0}, \ a_+ &= A_+ + \overline{A_-}, \ a_- &= A_+ - \overline{A_-}, \ b_+ &= B_+ + \overline{B_-} \end{array}$$

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Spatial dynamics Reduced system

Normal form

- normal form $(A_{\kappa}, B_{\kappa}) \longrightarrow (C_{\kappa}, D_{\kappa})$
- solutions of the form

$$C_0(x) = \mathrm{e}^{\mathrm{i} x} \widetilde{C_0}, \quad D_0(x) = \mathrm{e}^{\mathrm{i} x} \widetilde{D_0}, \quad C_\pm(x) = \mathrm{e}^{\mathrm{i} k_x x} \widetilde{C_\pm}, \quad D_\pm(x) = \mathrm{e}^{\mathrm{i} k_x x} \widetilde{D_\pm}.$$

scaling

$$\widehat{x} = |\mu|^{1/2} x, \quad c = |\mu| \widehat{c}, \quad C_{\kappa} = |\mu|^{1/2} \widehat{C_{\kappa}}, \quad D_{\kappa} = |\mu| \widehat{D_{\kappa}}, \quad \kappa \in \{0, \pm\},$$

$$C_0'' = -\frac{1}{4}C_0 + \frac{3}{4}C_0(|C_0|^2 + 2|C_+|^2 + 2|C_-|^2)$$

$$C_+'' = -\frac{1}{4k_x^2}C_+ + \frac{3}{4k_x^2}C_+(2|C_0|^2 + |C_+|^2 + 2|C_-|^2)$$

$$C_-'' = -\frac{1}{4k_x^2}C_- + \frac{3}{4k_x^2}C_-(2|C_0|^2 + 2|C_+|^2 + |C_-|^2)$$

$$+O(|\mu|^{1/2})$$

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Spatial dynamics Reduced system

Heteroclinic orbit

• leading order system : $\mu = 0$

$$C_0'' = -\frac{1}{4}C_0 + \frac{3}{4}C_0(|C_0|^2 + 2|C_+|^2 + 2|C_-|^2)$$

$$C_+'' = -\frac{1}{4k_x^2}C_+ + \frac{3}{4k_x^2}C_+(2|C_0|^2 + |C_+|^2 + 2|C_-|^2)$$

$$C_-'' = -\frac{1}{4k_x^2}C_- + \frac{3}{4k_x^2}C_-(2|C_0|^2 + 2|C_+|^2 + |C_-|^2)$$

- heteroclinic orbit $(0, C^*_+, C^*_-)$ $(C^*_0, C^*_+, 0)$? [van den Berg & van der Vorst, 1997]
- reduced system : persistence of these heteroclinic orbits

existence of grain boundaries

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Spatial dynamics Reduced system

Defects

dislocations



• grain boundaries



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