

# The Sine Transform of Isotropic Measures

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joint work with F.E. Schuster

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# The Cosine Transform

The cosine transform assigns to each finite (signed) Borel measure  $\mu$  on  $S^{n-1}$  the continuous function

$$\mathcal{C}(\mu)(u) = \int_{S^{n-1}} |u \cdot v| d\mu(v), \quad u \in S^{n-1}.$$

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# Zonoids

If  $\mu$  is an even (positive) Borel measure on  $S^{n-1}$ , then  $\mathcal{C}_\mu(u)$  is the support function of a unique convex body  $\mathcal{C}_\mu \subset \mathbb{R}^n$ :

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- ▶  $C_\mu$  is centered and origin-symmetric.
- ▶  $C_\mu$  is a zonoid, i.e. can be approximated by finite Minkowski sums of segments.

## Finite dimensional subspaces

Theorem (Bolker 1969; Lewis 1978)

Each  $n$ -dimensional subspace  $F$  of  $L_1(S^{n-1})$  is isometric to the Banach space  $(\mathbb{R}^n, \|\cdot\|_F)$  whose dual space norm is given by

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- ▶  $\mu$  is not concentrated on any great-sphere,
- ▶  $\mu$  is isotropic.

# Finite dimensional subspaces

## Example

- ▶  $F := \text{span}\{u \mapsto u \cdot x : x \in \mathbb{R}^n\} = \mathcal{H}_1^n$ . Then the representing measure is suitably normalized spherical Lebesgue measure

$$\lambda = \frac{1}{\kappa_n} d\sigma$$

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- ▶ The set of all *discrete* isotropic measures is a weakly dense subset of all isotropic measures (due to F. Barthe).

## Isotropic Position

The minimal surface area of a convex body  $K \subseteq \mathbb{R}^n$  is defined as

$$\partial(K) := \inf\{S(\Phi K) : \Phi \in \text{SL}(n)\},$$

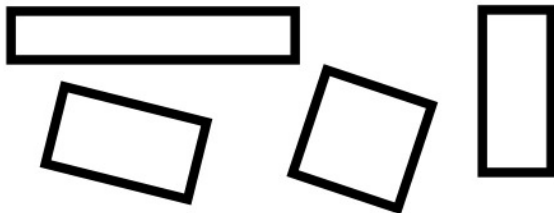
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$K$  is in surface isotropic position if  $S(K) = \partial(K)$ .

# Isotropic Position

## Theorem (Petty 1961)

*Let  $K \subseteq \mathbb{R}^n$  be a convex body. Then there exists a linear transformation  $\Phi \in SL(n)$  such that  $\Phi K$  is in surface isotropic position. This  $\Phi$  is unique up to orthogonal transformations.*

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## Theorem (Petty 1961)

*Let  $K \subseteq \mathbb{R}^n$  be a convex body.  $K$  is in surface isotropic position if and only if the surface area measure  $\mu_K$  is (up to normalization) isotropic.*

# Volume Inequalities for the Cosine Transform

## Theorem (Lutwak, 1990)

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### Remark:

- ▶ Extremizers exist due to compactness.

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Proof.

Makes use of the Urysohn inequality:

$$\left(\frac{\text{Vol}(K)}{\kappa_n}\right)^{1/n} \leq \frac{1}{n \kappa_n} \int_{S^{n-1}} h(K, u) du$$

Where equality only holds if  $h(K, u)$  is constant.



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- ▶  $\mathcal{S}$  annihilates odd measures.
- ▶  $\mathcal{S}\mu = c_n \cdot \mathcal{R}(\mathcal{C}\mu)$ , where  $\mathcal{R}$  is the Radon transform and  $c_n$  a constant only depending on the dimension.

# Disc Bodies

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- ▶  $\mathcal{S}_\mu$  is centered and origin-symmetric.
- ▶  $\mathcal{S}_\mu$  is a disc body, i.e. can be approximated by finite Minkowski sums of  $(n - 1)$  dimensional discs. Disc bodies constitute a subclass of zonoids.

## Examples

- ▶ For a convex body  $K$  in  $\mathbb{R}^n$ , denote its  $i$ -th intrinsic volume by  $V_i(K)$ . Then,  $h(\Pi_i K, u) := V_i(K|u^\perp)$  defines the projection body of order  $i$  and

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- ▶ If  $K$  is a convex body in  $\mathbb{R}^n$  then

$$\frac{1}{2(n+1)} \mathcal{S}\mu_K(u) = \int_{-\infty}^{\infty} \text{Vol}_{n-2} \left( K \cap (u^\perp + t u) \right) dt,$$

where  $\text{Vol}_{n-2}(L)$  denotes the  $n-2$  dimensional surface area of the  $n-1$  dimensional body  $L$ . This characterization of  $\mathcal{S}$  is due to Schneider.

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# Volume Inequalities for the Sine Transform

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### Remark:

- ▶ Extremizers exist due to compactness.

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**Remark:** These inequalities are *asymptotically* optimal.

# Brascamp-Lieb Inequality

Main tool is the Brascamp-Lieb inequality: Let  $\mu$  be a discrete measure such that  $\frac{1}{n-1} \mu$  is isotropic, say

$$\mu := c_1 \delta_{u_1} + \dots + c_m \delta_{u_m}.$$

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**Choose**  $f_1(x) = \dots = f_m(x) = \exp(-\|x\|)$ .

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Re-interpretation of the previous results:

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The End

**Thank you for your attention!**