A generalization of the MAC scheme on non conforming meshes

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approximation of

$$-\Delta \mathbf{u} + \nabla p = f \text{ in } \Omega, \quad \mathbf{u} = 0 \text{ on } \partial \Omega$$
$$\operatorname{div}(\mathbf{u}) = 0 \text{ in } \Omega$$

- $\bullet~\mathcal{T}$: Cartesian rectangular mesh of $\Omega,~\mathcal{E}$: edges of \mathcal{T}
- Discretization of **u**, and *p* by piecewise constant functions



$$p_{\mathcal{T}} \in X_{\mathcal{T}}, p_{\mathcal{T}} = p_{\mathcal{K}} \text{ in } \mathcal{K}, \\ \mathcal{K} \in \mathcal{T} \text{ (black cell)}$$

$$\begin{split} \mathbf{n}_{\sigma} &= \mathbf{e}^{(1)} \text{ for } \sigma \in \mathcal{E}_{\text{ver}} \text{ and } \mathbf{n}_{\sigma} = \mathbf{e}^{(2)} \text{ for } \sigma \in \mathcal{E}_{\text{hor}} \\ \mathbf{u}_{\mathcal{T}} &= (u_{\mathcal{T}}^{(1)}, u_{\mathcal{T}}^{(2)}) \in \mathbf{H}_{\mathcal{T}} \\ u_{\mathcal{T}}^{(1)} &= u_{\sigma}, \text{ first component of } \mathbf{u}_{\mathcal{T}} \text{ in the red cell} \\ u_{\mathcal{T}}^{(2)} &= u_{\sigma}, \text{ second component of } \mathbf{u}_{\mathcal{T}} \text{ in the blue cell} \\ u_{\sigma} \in \mathbb{R} \text{ is an approximate value for } \mathbf{u} \cdot \mathbf{n}_{\sigma} \\ u_{\sigma} &= 0 \text{ if } \sigma \subset \partial \Omega \end{split}$$

Variational formulation of the MAC scheme

$$\mathbf{u}_{\mathcal{T}} \in \mathbf{H}_{\mathcal{T}}, \quad \mathbf{p}_{\mathcal{T}} \in X_{\mathcal{T}}$$
$$\langle \mathbf{u}_{\mathcal{T}}, \mathbf{v} \rangle_{\mathcal{T}} - \int_{\Omega} \mathbf{p}_{\mathcal{T}} \operatorname{div}_{\mathcal{T}} \mathbf{v} dx = \int_{\Omega} \mathbf{f} \cdot \mathbf{v} dx, \quad \forall \mathbf{v} \in \mathbf{H}_{\mathcal{T}}$$
$$\int_{\Omega} q \operatorname{div}_{\mathcal{T}} \mathbf{u}_{\mathcal{T}} dx = \mathbf{0}, \quad \forall q \in X_{\mathcal{T}}$$





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$$\int_{\Omega} q \operatorname{div}_{\mathcal{T}} \mathbf{u}_{\mathcal{T}} dx = 0, \quad \forall q \in X_{\mathcal{T}}$$







Pressure grid : again approximate

$${\rm div} \bm{u} = \bm{0}$$

by

$$div_{\mathcal{K}}\mathbf{u} = \frac{1}{|\mathcal{K}|} \sum_{\sigma \in \mathcal{E}_{\mathcal{K}}} |\sigma| u_{\sigma} \mathbf{n}_{\sigma} \cdot \mathbf{n}_{\mathcal{K},\sigma} = 0$$



approximation of diffusion term

$$\langle \mathbf{u}, \mathbf{v} \rangle_{\mathcal{T}} = \langle u_1, v_1 \rangle_{\mathcal{T}_1} + \langle u_2, v_2 \rangle_{\mathcal{T}_2}$$

$$\langle u_1, v_1 \rangle_{\mathcal{T}_1} = \sum_{\sigma_1 = (\kappa_1, \ell_1)} |\sigma_1| d_{\sigma_1} \frac{u_{\kappa_1} - u_{\ell_1}}{d_{\sigma_1}} \frac{v_{\kappa_1} - v_{\ell_1}}{d_{\sigma_1}} -$$





approximation of diffusion term

$$\langle \mathbf{u}, \mathbf{v} \rangle_{\mathcal{T}} = \langle u_1, v_1 \rangle_{\mathcal{T}_1} + \langle u_2, v_2 \rangle_{\mathcal{T}_2}$$

$$\langle u_2, v_2 \rangle_{\mathcal{T}_2} = \sum_{\sigma_2 = (\kappa_2, L_2)} |\sigma_2| d_{\sigma_2} \frac{u_{\kappa_2} - u_{L_2}}{d_{\sigma_2}} \frac{v_{\kappa_2} - v_{L_2}}{d_{\sigma_2}}$$



Proof of convergence, main steps

 $(\mathcal{T}_n)_{n\in\mathbb{N}}$ sequence of grids, such that $h_n \to 0$ as $n \to +\infty$ (\mathbf{u}_n, p_n) satisfying the discrete equations on mesh \mathcal{T}_n **(4)** Estimate on the discrete H_0^1 norm of the components of \mathbf{u}_n : $\mathbf{v} = \mathbf{u}_n$ and $\|\mathbf{v}\|_{L^2(\Omega)^d}^2 \leq C \langle \mathbf{v}, \mathbf{v} \rangle_{\mathcal{T}_n}$ imply $\langle \mathbf{u}_n, \mathbf{u}_n \rangle_{\mathcal{T}_n} \leq C$ **(a)** $L^2(\Omega)$ estimate on p_n : $p_n = \operatorname{div} \mathbf{v}, \ \mathbf{v}_\sigma = \frac{1}{|\sigma|} \int \mathbf{v} \cdot \mathbf{n}_\sigma$ Compactness : classical, consequence of Kolmogorov : $\mathbf{u}_n \to \mathbf{u} \in H^1_0(\Omega)^2$ in $L^2(\Omega)^2$ and $p_n \to p$ in $L^2(\Omega)$ • Passing to the limit in velocity terms : $\langle \mathbf{u}_n, \varphi_n \rangle_{\mathcal{T}_n} \rightarrow \int_{\Omega} \nabla \mathbf{u} : \nabla \varphi dx$ Passing to the limit in divergence terms $\int_{\Omega} p_n \operatorname{div}_{\mathcal{T}} \varphi_n dx \to \int_{\Omega} p \operatorname{div} \varphi dx, \quad \int_{\Omega} \varphi_n \operatorname{div}_{\mathcal{T}} \mathbf{u}_n dx \to \int_{\Omega} \varphi \operatorname{div} \mathbf{u} dx = 0$ • Strong convergence of p_n in $L^2(\Omega)$: convergence of $\int p_n^2 dx$

Passing to the limit $\int_{\Omega} \varphi_n \operatorname{div}_{\mathcal{T}} \mathbf{u}_n d\mathbf{x} \to \int_{\Omega} \varphi \operatorname{div} \mathbf{u} d\mathbf{x} = \mathbf{0}$

$$\varphi \in C_{c}^{\infty}(\Omega), \ \varphi_{K} = \text{ mean value of } \varphi \text{ on } K$$

$$0 = \sum_{K \in \mathcal{T}} \sum_{\sigma \in \mathcal{E}_{K}} |\sigma| u_{K,\sigma} \varphi_{K} = \sum_{\sigma = K \mid L} |\sigma| u_{\sigma} (\varphi_{K} - \varphi_{L})$$

$$= \sum_{\sigma = K \mid L} |K_{\sigma}| u_{\sigma} |\sigma| \frac{(\varphi_{K} - \varphi_{L})}{|K_{\sigma}|}$$

$$= -\sum_{i=1}^{d} \int_{\Omega} u_{T}^{(i)} \partial_{T}^{(i)} \varphi \ dx$$

where

$$\partial_{\mathcal{T}}^{(i)} \varphi(\mathbf{x}) = |\sigma| \frac{(\varphi_L - \varphi_K)}{|K_{\sigma}|} \quad \text{for} \quad \mathbf{x} \in K_{\sigma} \quad \text{and} \quad \mathbf{n}_{\sigma} = \mathbf{e}^{(i)}, \ \sigma = K | L$$

conclusion thanks to weak convergence of $\partial^{(i)}_T arphi$ and strong convergence of $u^{(i)}_T$

Stationary NS

$$\mathbf{u}_{\mathcal{T}} \in \mathbf{H}_{\mathcal{T}}$$

$$\langle \mathbf{u}, \mathbf{v} \rangle_{\mathcal{T}} + b_{\mathcal{T}}(\mathbf{u}, \mathbf{u}, \mathbf{v}) - \int_{\Omega} p_{\mathcal{T}} \operatorname{div}_{\mathcal{T}} \mathbf{v}, \forall \mathbf{v} \in \mathbf{H}_{\mathcal{T}}$$

$$\int_{\Omega} q \operatorname{div}_{\mathcal{T}} \mathbf{u} dx = 0, \ \forall q \in X_{\mathcal{T}}$$

$$\forall \mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbf{H}_{\mathcal{T}}, \ b_{\mathcal{T}}(\mathbf{u}, \mathbf{v}, \mathbf{w}) = \sum_{\substack{\sigma \in \mathcal{E} \\ \sigma = \{K, L\}}} |\sigma| u_{\sigma} (\mathbf{\Pi}_{L} \mathbf{v} - \mathbf{\Pi}_{K} \mathbf{v}) \cdot \frac{\mathbf{\Pi}_{K} \mathbf{w} + \mathbf{\Pi}_{L} \mathbf{w}}{2}$$

with

$$\boldsymbol{\Pi}_{\boldsymbol{K}}\boldsymbol{\mathsf{v}} = \left(\begin{array}{c} \frac{1}{|\boldsymbol{K}|} \sum_{\sigma \in \mathcal{E}_{\boldsymbol{K}, \mathrm{ver}}} |\boldsymbol{K} \cap \boldsymbol{K}_{\sigma}| | \boldsymbol{v}_{\sigma} \\ \frac{1}{|\boldsymbol{K}|} \sum_{\sigma \in \mathcal{E}_{\boldsymbol{K}, \mathrm{hor}}} |\boldsymbol{K} \cap \boldsymbol{K}_{\sigma}| | \boldsymbol{v}_{\sigma} \end{array}\right)$$

properties

$$\begin{split} &\text{if } \operatorname{div}_{\mathcal{T}} \mathbf{u} = \mathbf{0} \\ &b_{\mathcal{T}}(\mathbf{u},\mathbf{v},\mathbf{w}) = -b_{\mathcal{T}}(\mathbf{u},\mathbf{w},\mathbf{v}) \\ &\text{and } b_{\mathcal{T}}(\mathbf{u},\mathbf{u},\mathbf{u}) = \mathbf{0} \end{split}$$

 $\mathbf{v} = \mathbf{u}$ in (NS)_T yields discrete H_0^1 estimate in \mathbf{u}

Passing to the limit in

$$\sum_{i,j=1}^{d} \int_{\Omega} u_{T}^{(j)} \ \partial_{T}^{(j)} \mathbf{\Pi}_{T}^{(i)} u_{T}^{(i)} \ \mathcal{P}_{T}^{(i)} \varphi \ dx$$

The 30° inclined driven cavity : the locally refined mesh





	Generalized MAC scheme				Demirdzic 92
	$\operatorname{card}(\mathcal{D}_0^{\mathrm{m}})$	$\operatorname{card}({\mathcal D}_1^{\mathrm{m}})$	$\operatorname{card}(\mathcal{D}_2^{\mathrm{m}})$	$\operatorname{card}(\mathcal{D}_3^{\mathrm{m}})$	102400
	924	3698	14796	59190	$(= 320^2)$
$\min(u^{(1)}(\xi_2))$	$-1.86 \cdot 10^{-1}$	$-1.99 \cdot 10^{-1}$	$-1.99 \cdot 10^{-1}$	$-1.98 \cdot 10^{-1}$	$-1.98 \cdot 10^{-1}$
ξ2	$7.50\cdot10^{-1}$	$7.83\cdot 10^{-1}$	$7.87\cdot 10^{-1}$	$7.81\cdot 10^{-1}$	$7.82\cdot10^{-1}$
$\min(u^{(2)}(\xi_1))$	$-2.14 \cdot 10^{-2}$	$-2.25 \cdot 10^{-2}$	$-2.06 \cdot 10^{-2}$	$-2.01 \cdot 10^{-2}$	$-1.99 \cdot 10^{-2}$
ξ1	$3.42 \cdot 10^{-1}$	$3.24 \cdot 10^{-1}$	$3.146 \cdot 10^{-1}$	$3.19\cdot10^{-1}$	$3.17\cdot10^{-1}$
$\max(u^{(2)}(\xi_1))$	$1.36 \cdot 10^{-2}$	$1.36 \cdot 10^{-2}$	$1.25 \cdot 10^{-2}$	$1.21 \cdot 10^{-2}$	$1.21 \cdot 10^{-2}$
ξ1	$7.85\cdot10^{-1}$	$8.04\cdot 10^{-1}$	$8.26\cdot 10^{-1}$	$8.24 \cdot 10^{-1}$	$8.26 \cdot 10^{-1}$

Max and min of velocity components along the centerlines ξ_1 and ξ_2 .

A second extension to more general grids

$$u \in H_{T}, \quad p \in X_{T}$$

$$\langle u, v \rangle_{T} - \int_{\Omega} p \operatorname{div}_{T} v dx + b_{T}(u, u, v) = \int_{\Omega} \mathbf{f} \cdot \mathbf{\Pi} v dx, \quad \forall v \in H_{T}$$

$$\int_{\Omega} q \operatorname{div}_{T} u dx = 0, \quad \forall q \in X_{T}$$



$$u^{n+1} \in H_{\mathcal{T}}, \ u = \theta u^{n+1} + (1-\theta)u^n, \ \theta \in [\frac{1}{2}, 1], \ p \in X_{\mathcal{T}}$$
$$\int_{\Omega} \frac{\Pi u - \Pi u^n}{\theta \delta t} \cdot \Pi v dx$$
$$+ \langle u, v \rangle_{\mathcal{T}} - \int_{\Omega} p \operatorname{div}_{\mathcal{T}} v dx + b_{\mathcal{T}}(u, u, v) = \int_{\Omega} \mathbf{f}^{n+1} \cdot \Pi v dx, \ \forall v \in H_{\mathcal{T}}$$
$$\int_{\Omega} q \operatorname{div}_{\mathcal{T}} u dx = 0, \ \forall q \in X_{\mathcal{T}}$$

MAC scheme in space, estimate with v = u and sum on n (it works since $\theta \ge \frac{1}{2}$) θ -scheme in time Compactness in time ? B a Banach, $(B_n)_{n \in \mathbb{N}}$ family of finite dimensional subspaces of B $\|\cdot\|_{X_n}$ and $\|\cdot\|_{Y_n}$ two norms on B_n such that • If $(\|w_n\|_{X_n})_{n \in \mathbb{N}}$ is bounded, there exists $w \in B$ such that $w_n \to w$ in B. • If $w_n \to w$ in B and $\|w_n\|_{Y_n} \to 0$, then w = 0. $X_n = B_n$ with norm $\|\cdot\|_{X_n}$, $Y_n = B_n$ with norm $\|\cdot\|_{Y_n}$. Let T > 0, $k_n > 0$ and $(u_n)_{n \in \mathbb{N}}$ be a sequence such that • for all n, $u_n(\cdot, t) = u_n^{(p)} \in B_n$ for $t \in ((p-1)k_n, pk_n)$ • $(u_n)_{n \in \mathbb{N}}$ is bounded in $L^1((0, T), X_n)$, • $(\partial_{t,k_n}u_n)_{n \in \mathbb{N}}$ is bounded in $L^1((0, T), Y_n)$. Then $\exists u \in L^1((0, T), B)$ s.t., up to a subsequence, $u_n \to u$ in $L^1((0, T), B)$.

Application to incompressible NS extended MAC scheme $B = L^2(\Omega), B_n = H_{\mathcal{T}_n}$ $\|w\|_{X_n} = \|w\|_{1,\mathcal{T}_n} \text{ and } \|w\|_{Y_n} = \sup_{v \in H_{\mathcal{T}_n} \setminus \{0\}} \frac{1}{\|v\|_{1,\mathcal{T}_n}} \int_{\Omega} w \ v \ dx$